



# NEW PERSPECTIVES INTO THE CHAOTIC DYNAMICS IN MOLECULES

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**Universidad Politécnica de Madrid (Spain)**

# NOLINEAL 20

## 12th International Conference on Nonlinear Mathematics and Physics

Madrid (Spain)

<https://www.gsc.upm.es/nolineal2020>



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## 12th International Conference on Nonlinear Mathematics and Physics

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# OUTLINE

Introduction

System

Methodology

Results

Conclusions

Introduction



## **Unveiling the chaotic structure in phase space of molecular systems using Lagrangian descriptors**

F. Revuelta,<sup>1,2,\*</sup> R. M. Benito,<sup>1,†</sup> and F. Borondo<sup>2,3,‡</sup>

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<sup>2</sup>*Instituto de Ciencias Matemáticas (ICMAT), Cantoblanco, 28049 Madrid, Spain*

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# CHAOS INDICATORS

**PSOS** - Poincaré Surface of section

**Lyapunov exponent**

**Frequency Analysis** - Laskar

**SALI** and **GALI** (Small and Generalized Alignment Index - Skokos.

**FLI** (Fast Lyapunov Indicator) - Lega, Guzzo, Froeschlé.

**OFLI** (Orthogonal Fast Lyapunov Indicator) - Barrio.

**MEGNO** (Mean Exponential Growth Factor of Nearby Orbits) - Cincotta, Simó

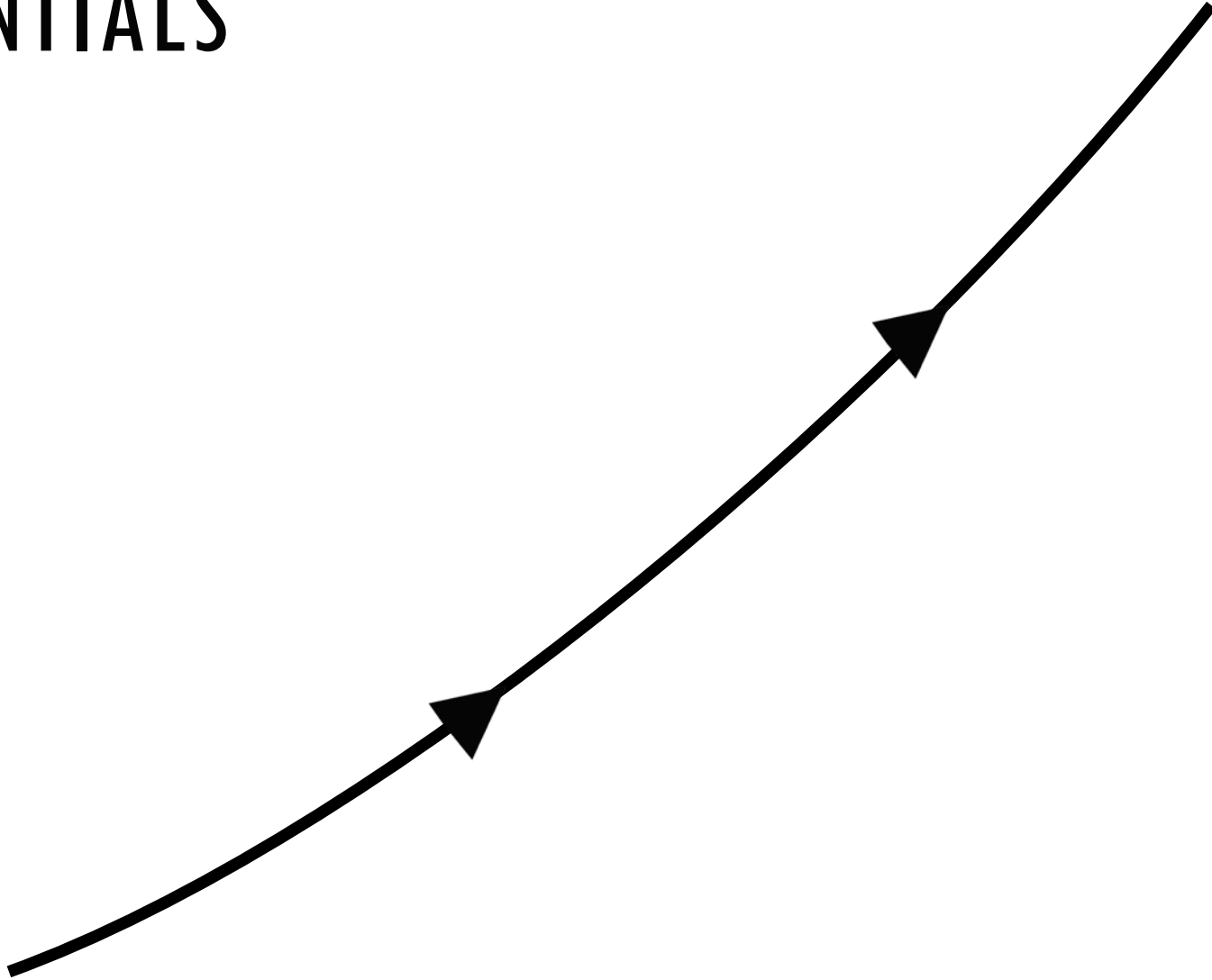
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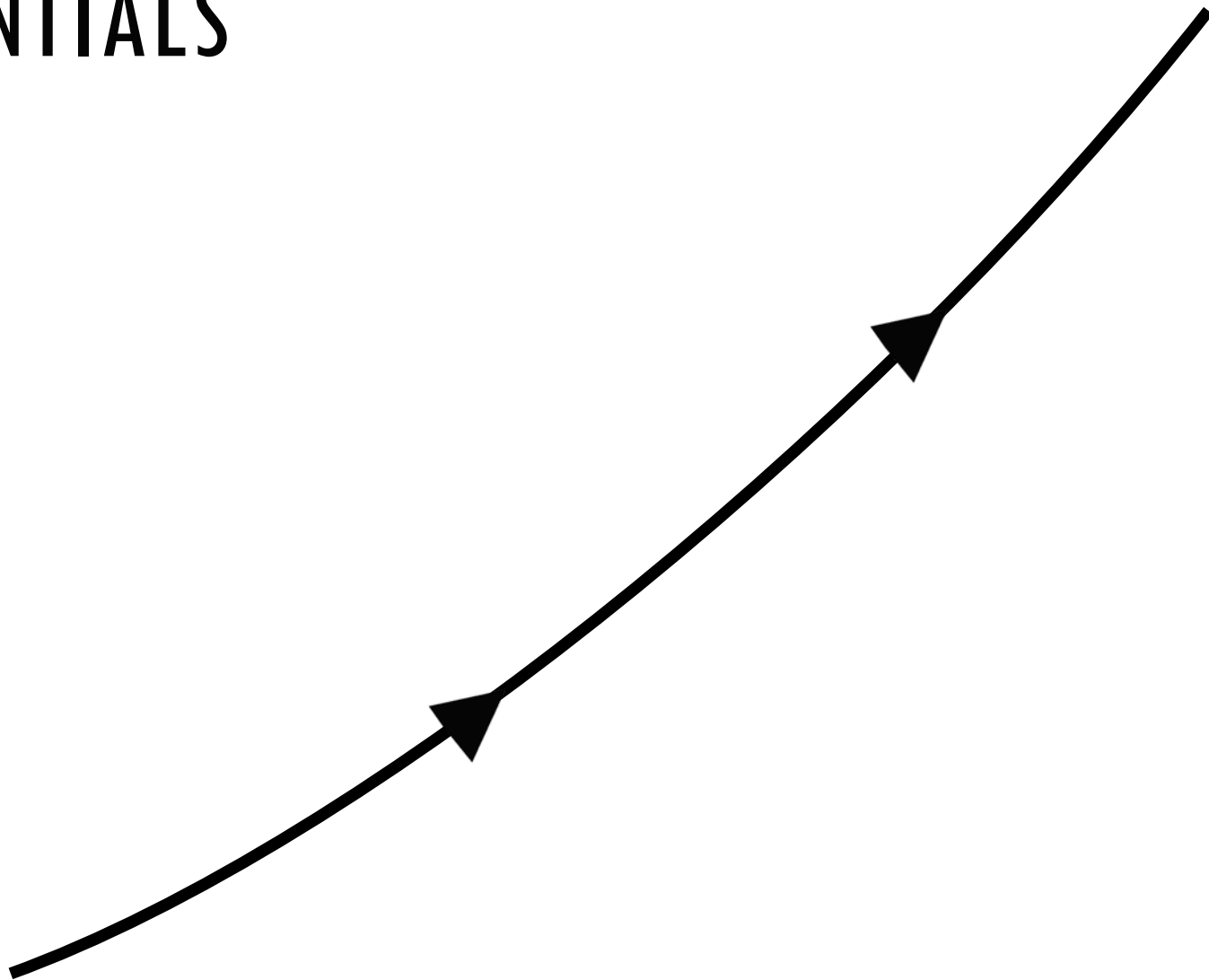


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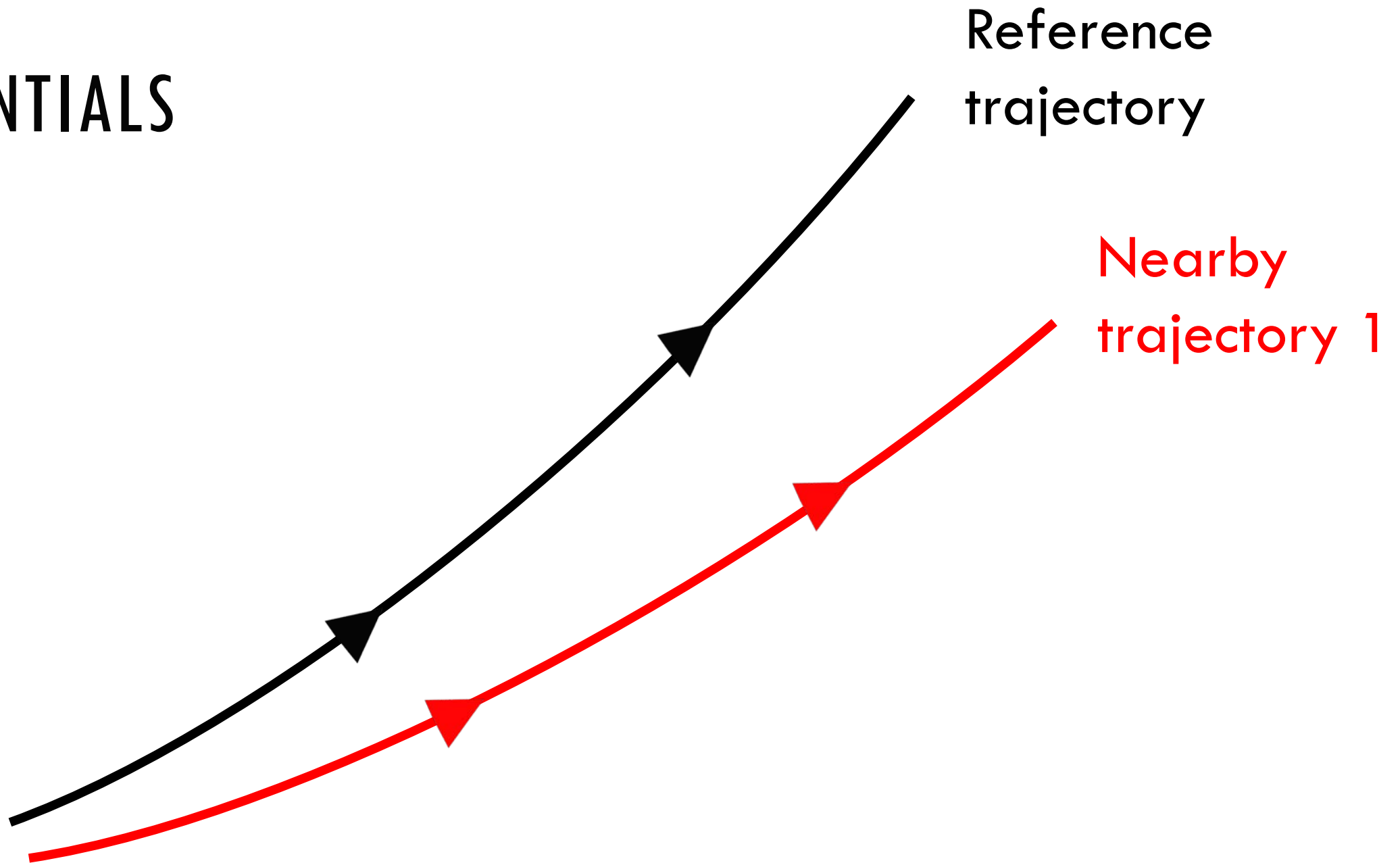


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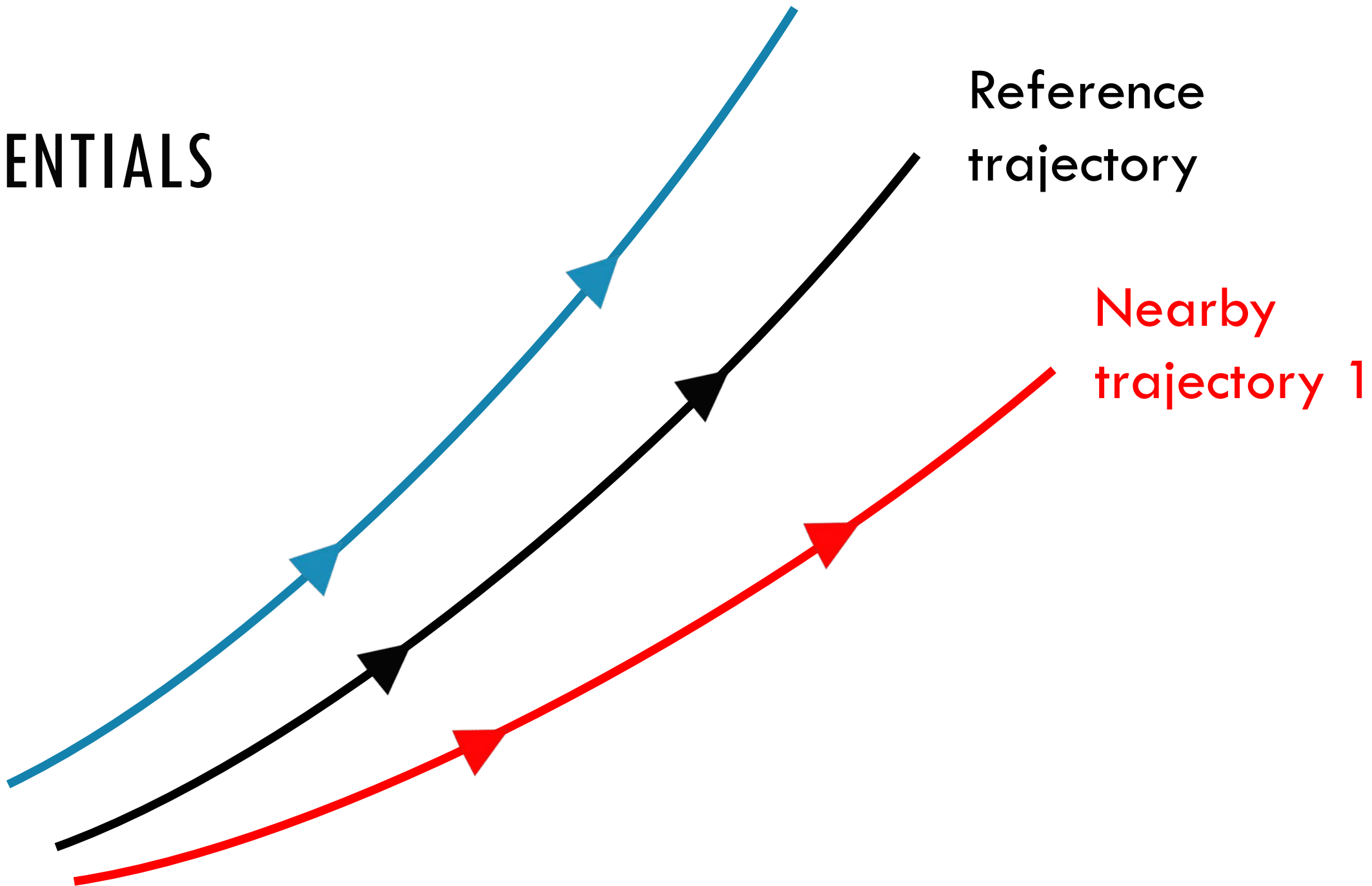
Reference  
trajectory



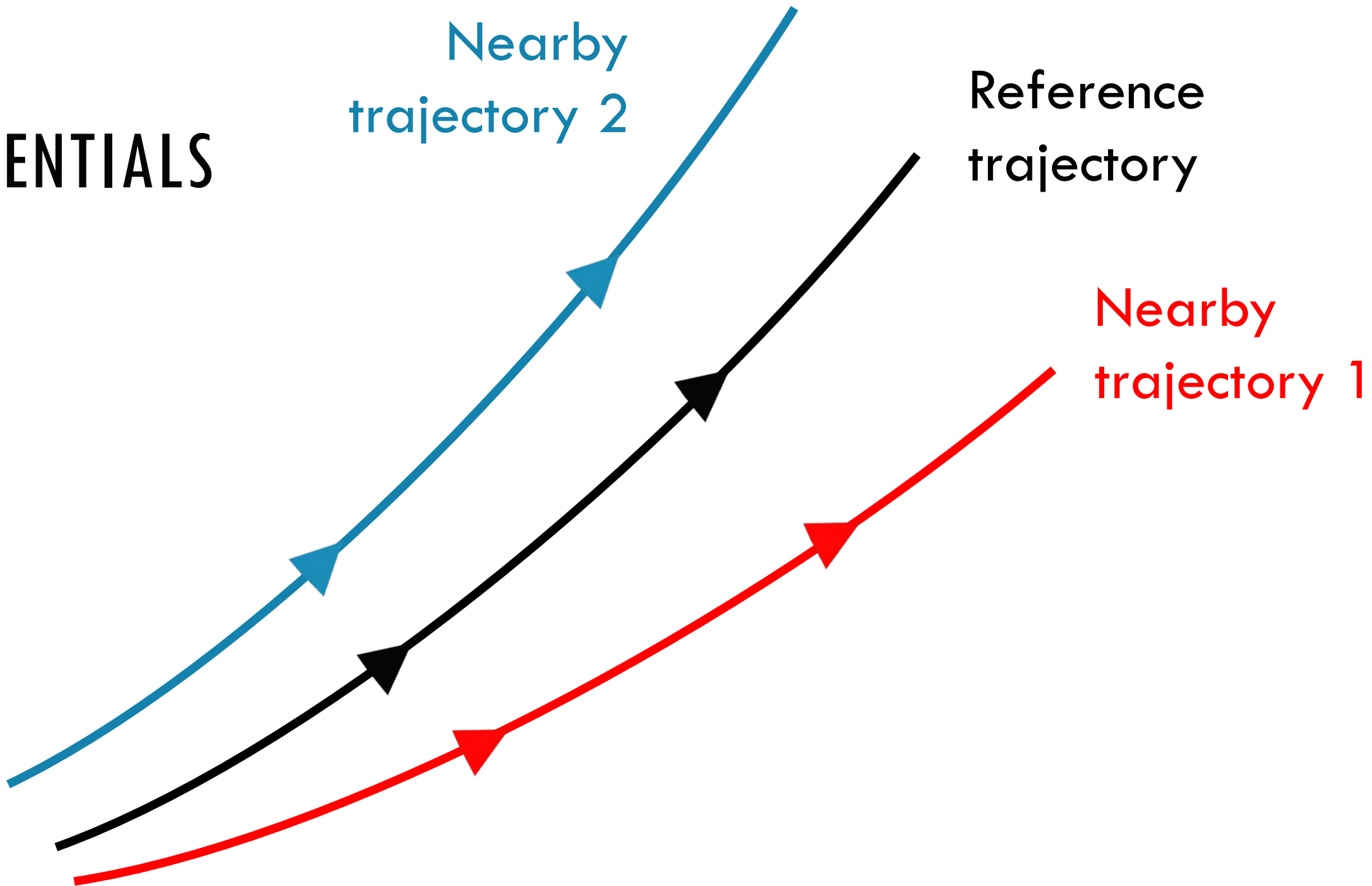
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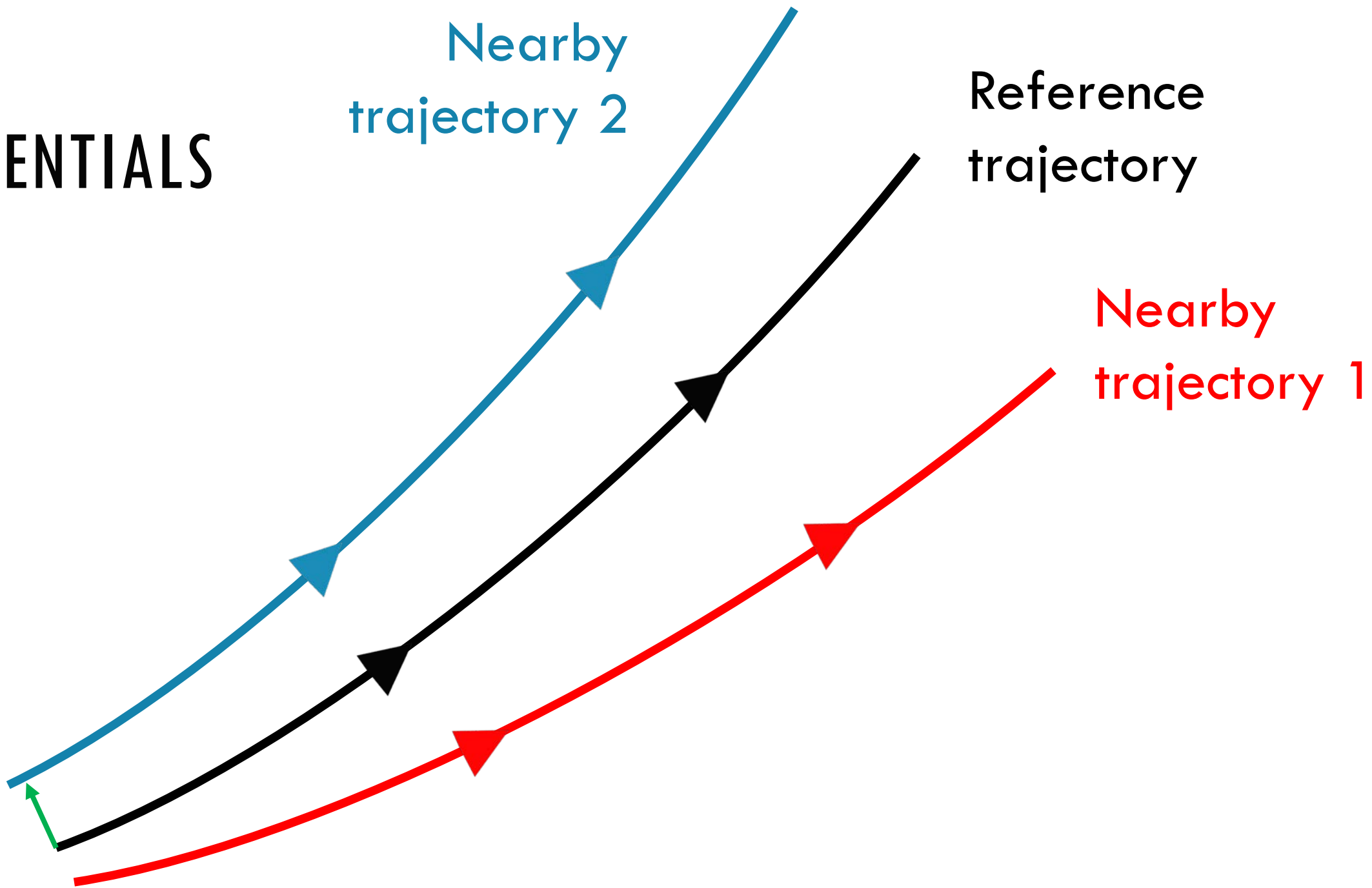
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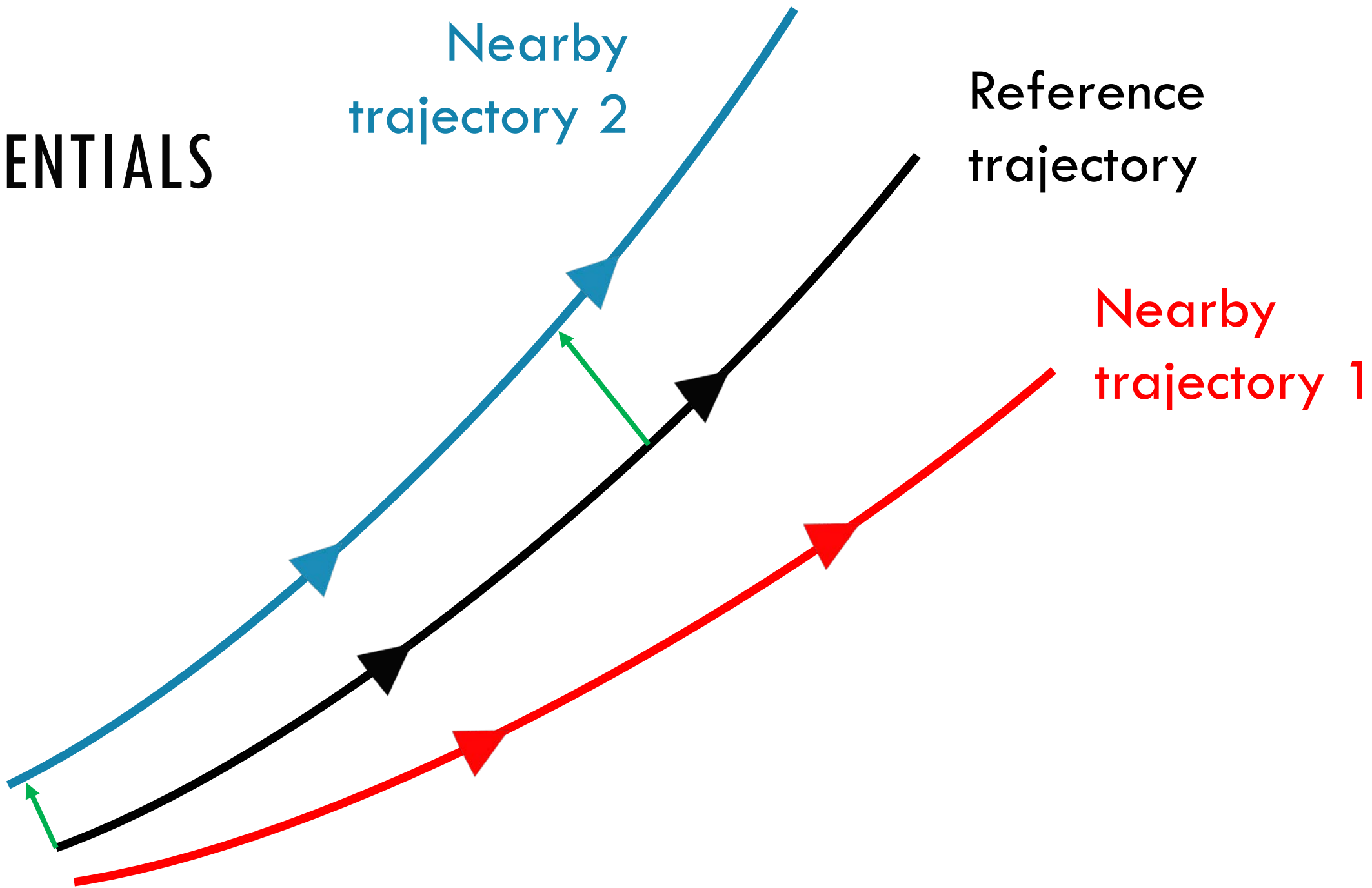
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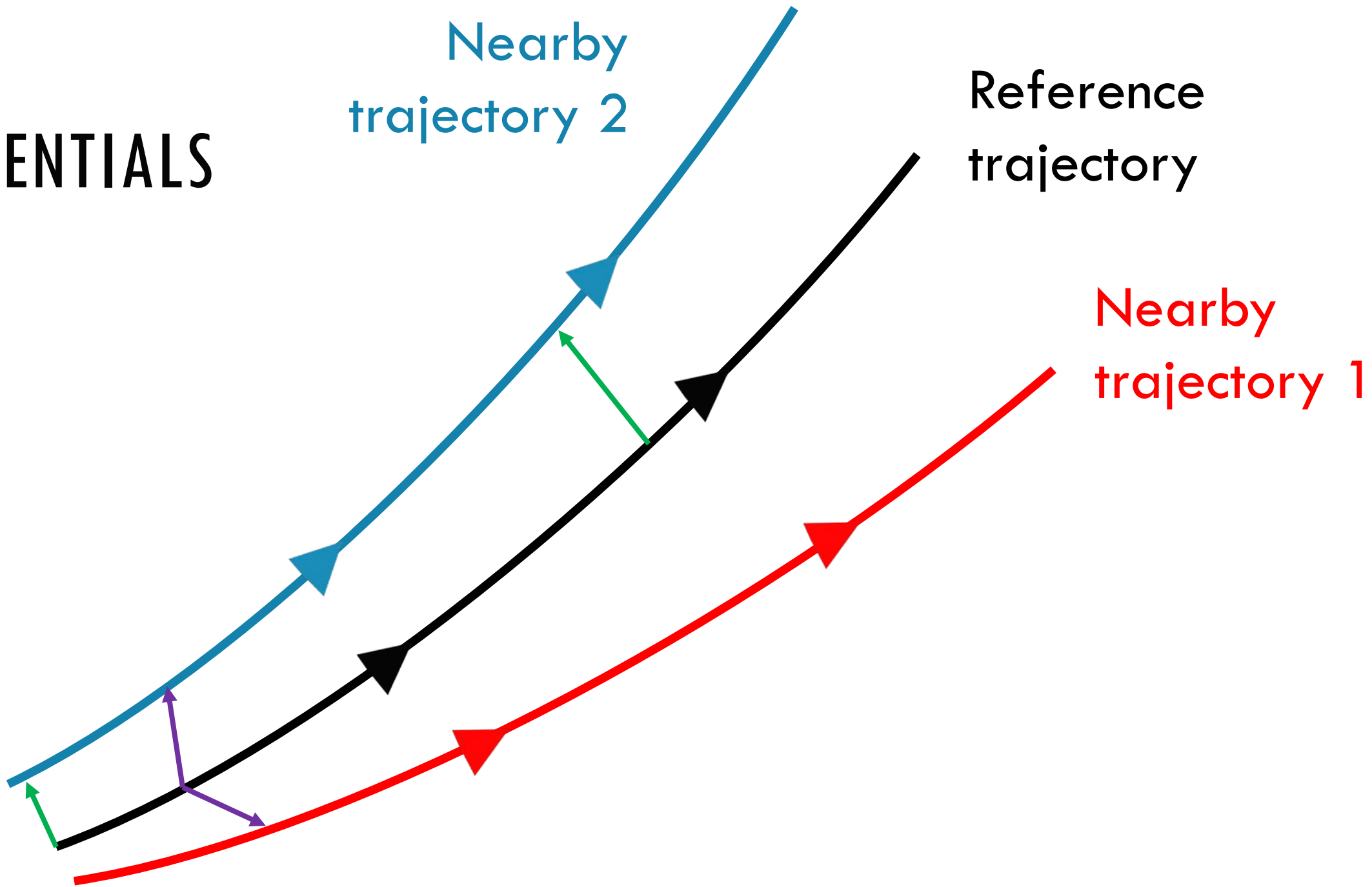


Nearby trajectory 2

Reference trajectory

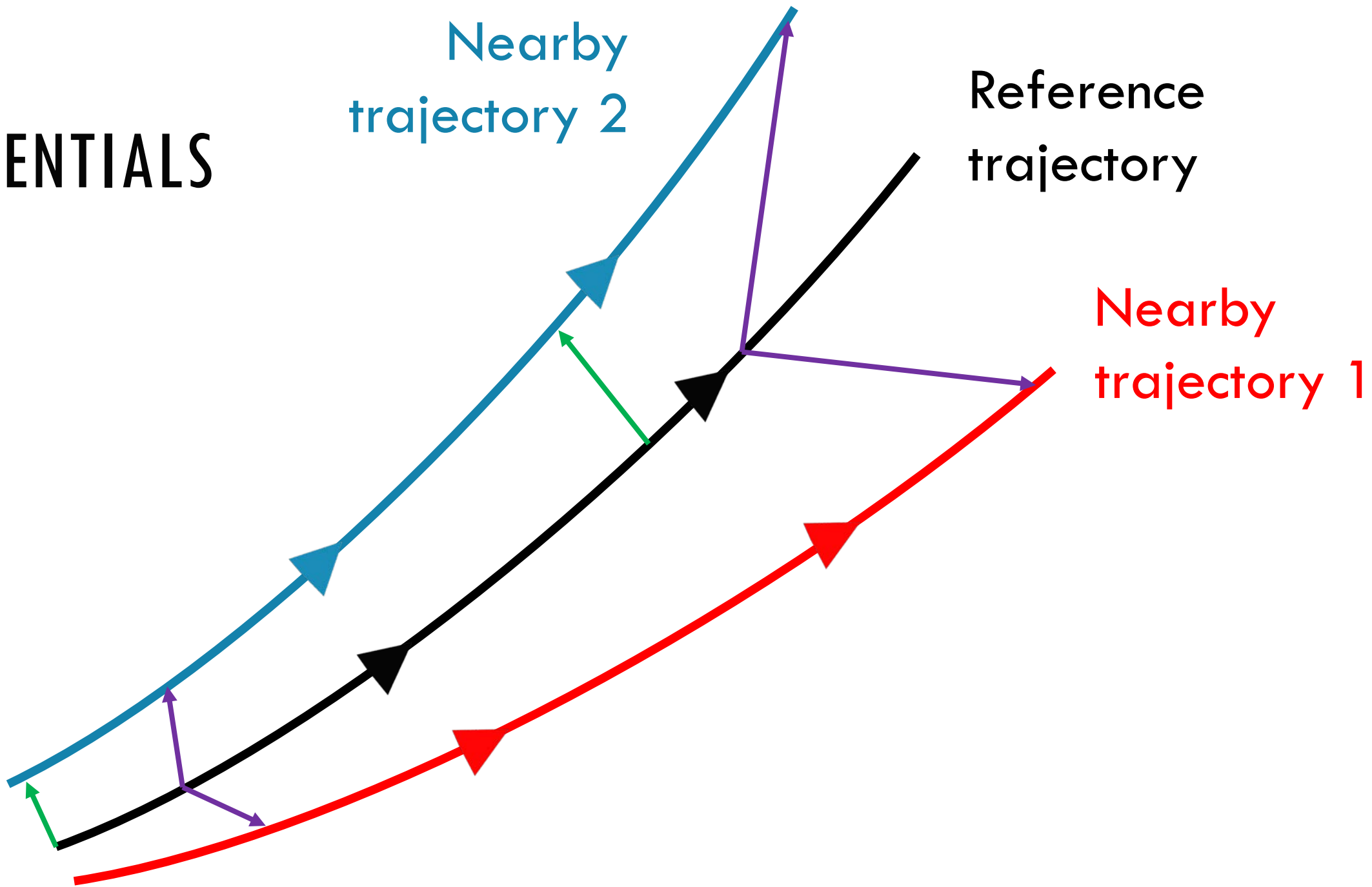
Nearby trajectory 1

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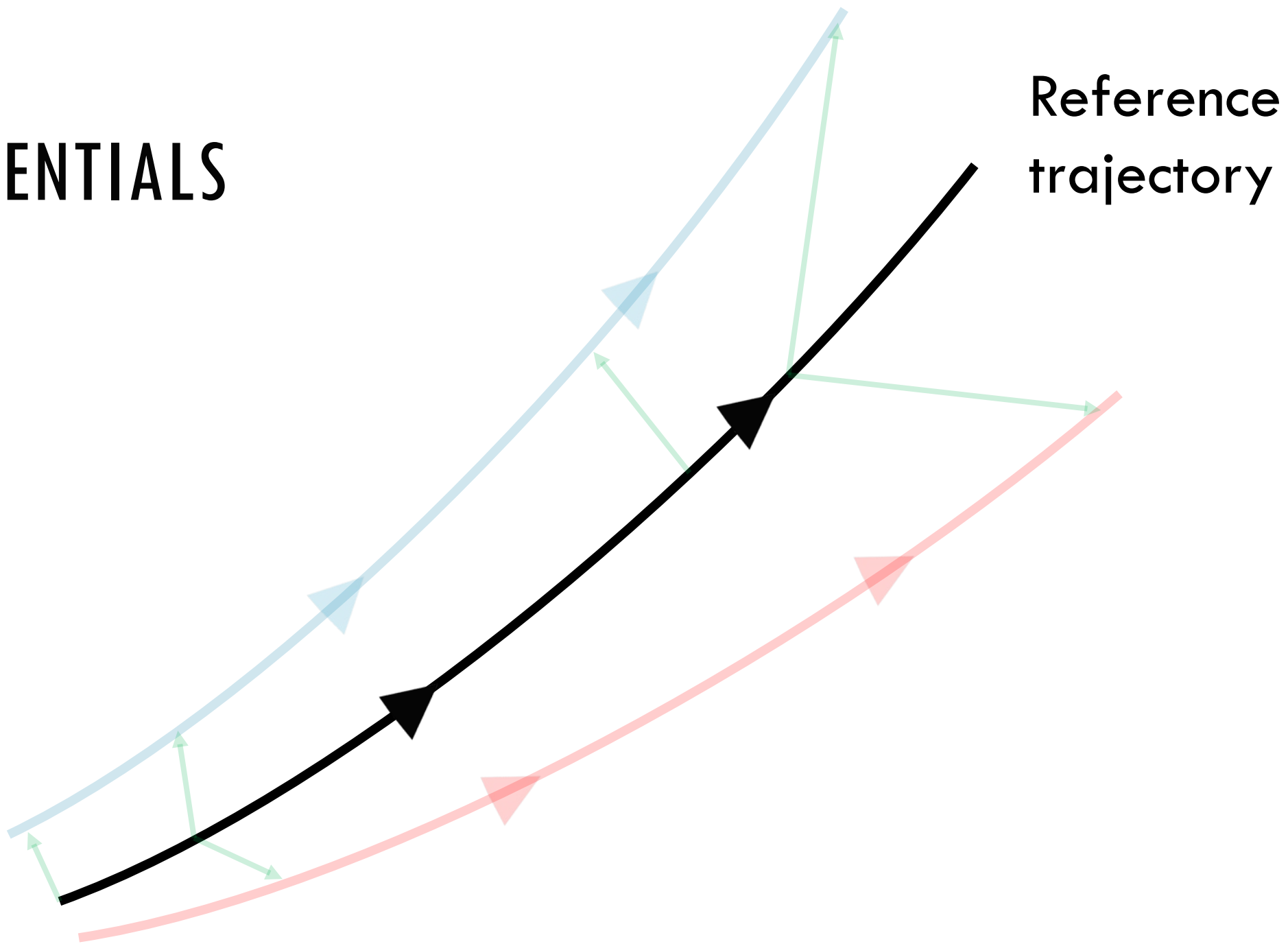




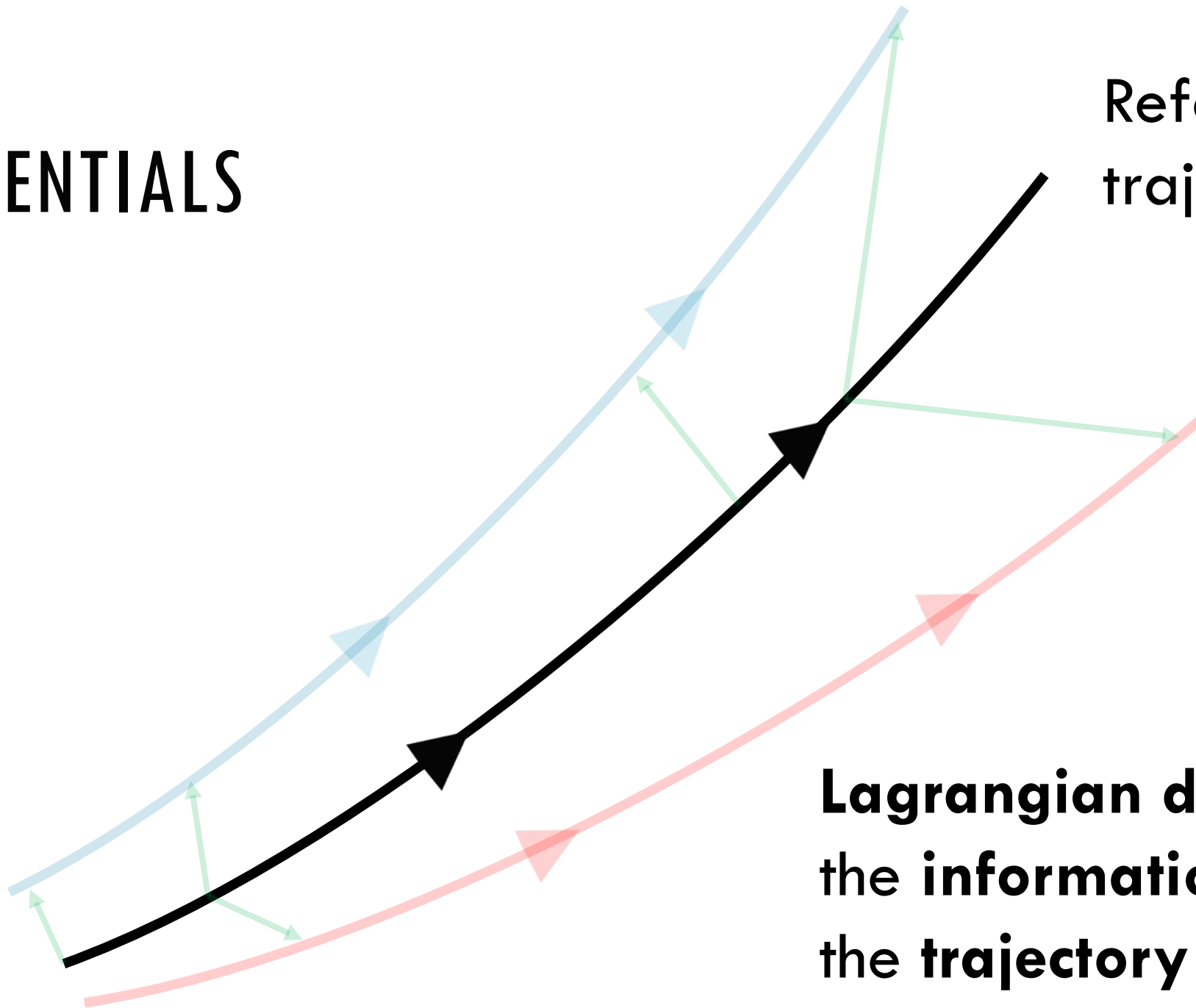
# ESSENTIALS



# ESSENTIALS



# ESSENTIALS



Reference  
trajectory

**Lagrangian descriptors: all  
the information encoded in  
the trajectory itself!**

*"Provides useful insights into the often mysterious world of politics."* The Honorable Evan Bayh, United States Senator from Indiana

# Dynamics

FOR

# DUMMIES®

2nd Edition



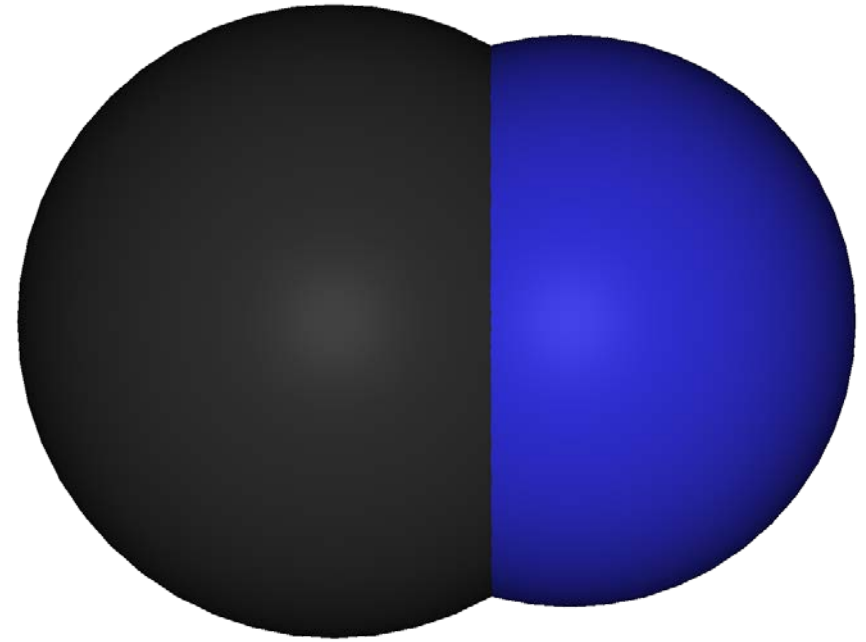
Ann DeLaney

**A Reference for the Rest of Us!**



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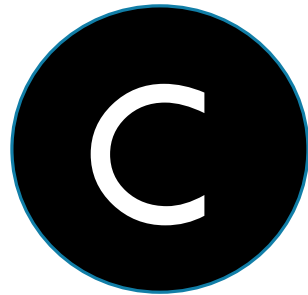
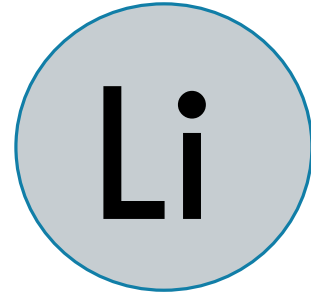
**SYSTEM**



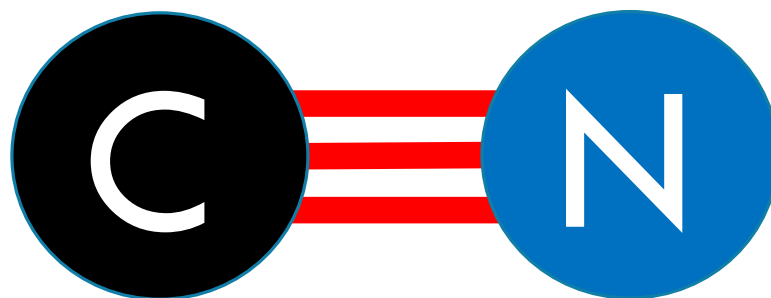
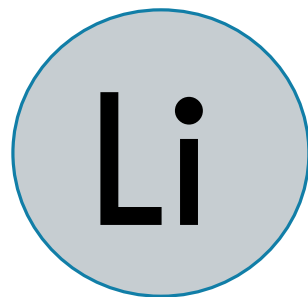
# WHY MOLECULES???

1. Atomic and molecular systems: excellent platforms for application of **dynamical systems theory**
2. ↑↑↑↑ **anharmonic**
3. “Simple” (**2 dof**)

SYSTEM

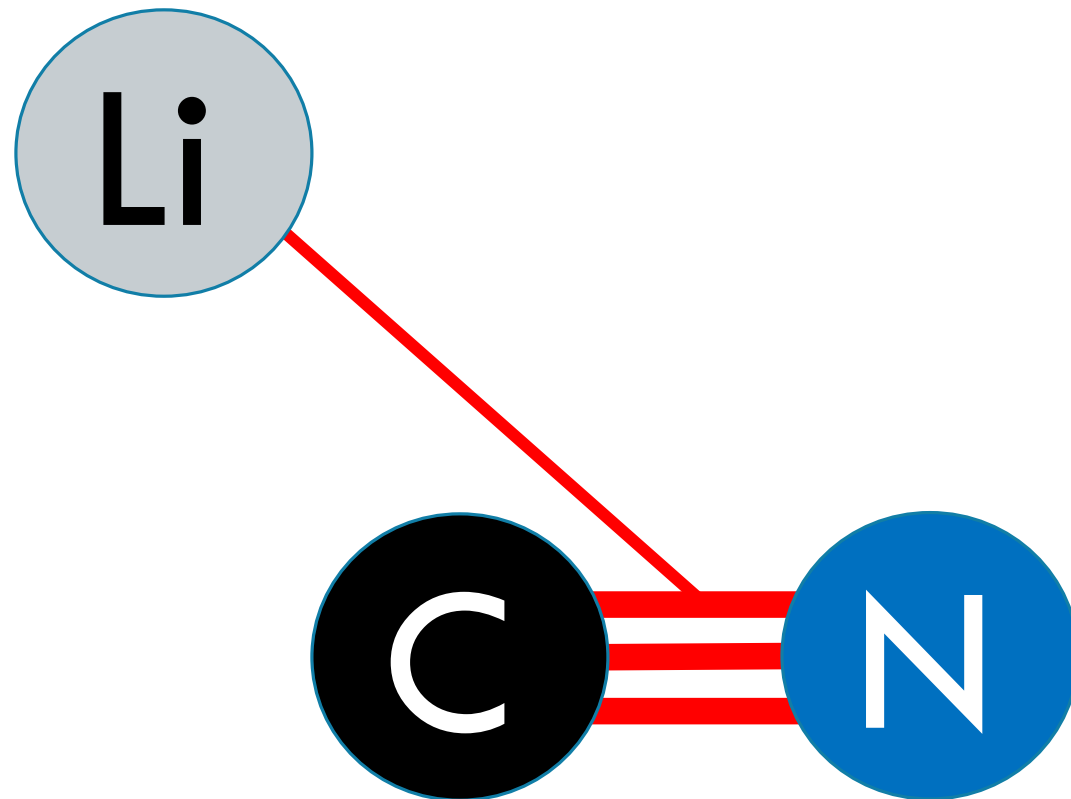


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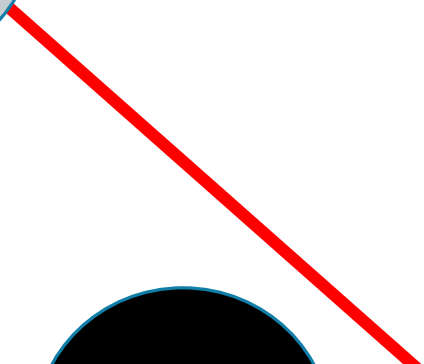
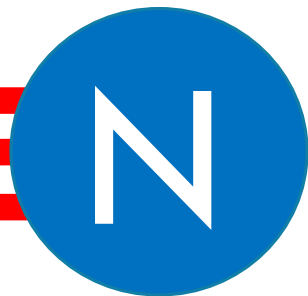
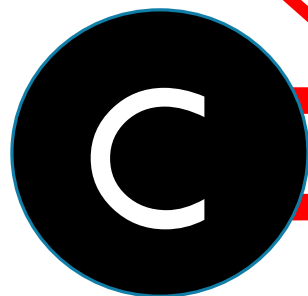
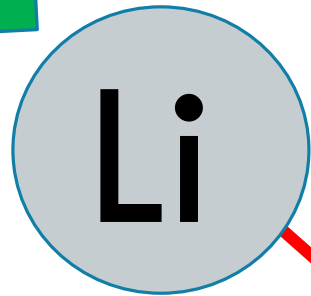


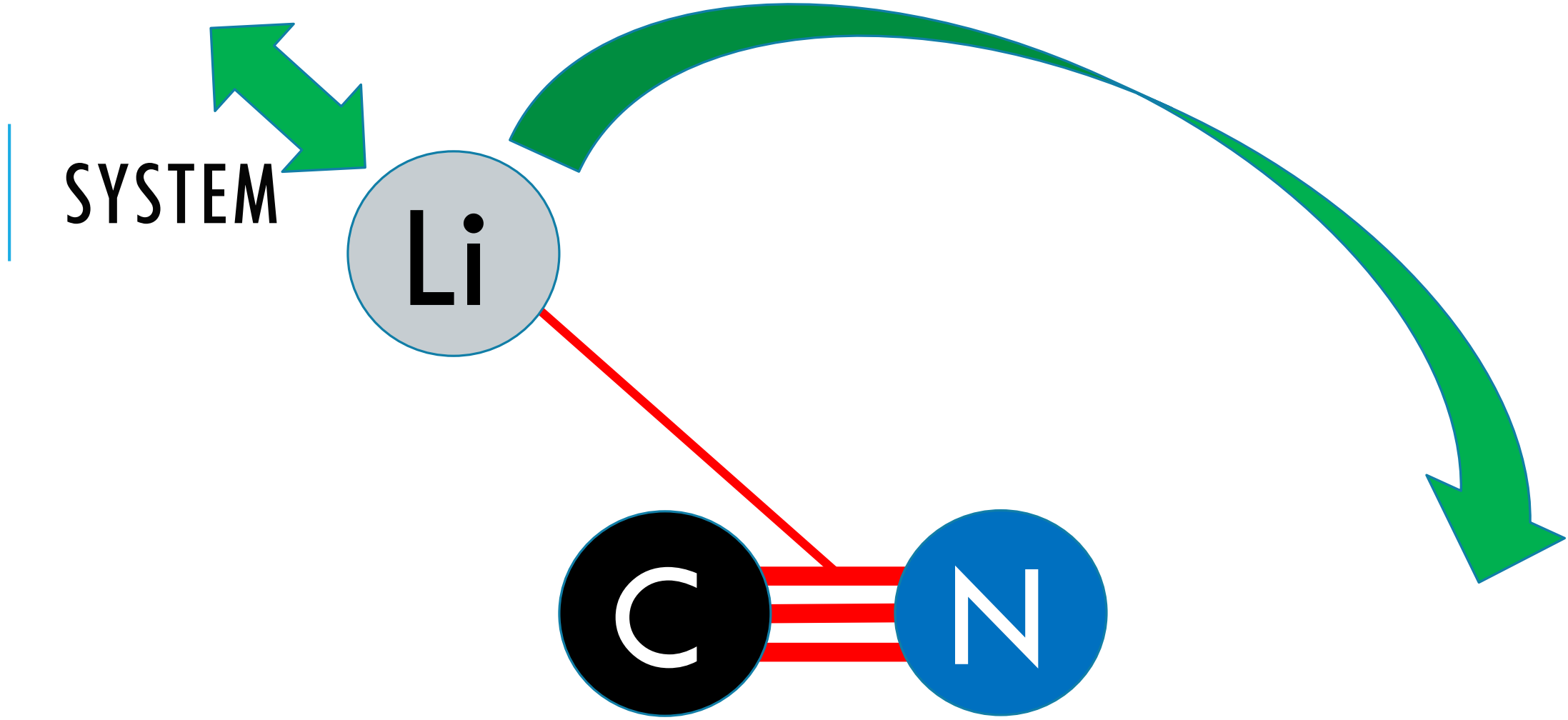


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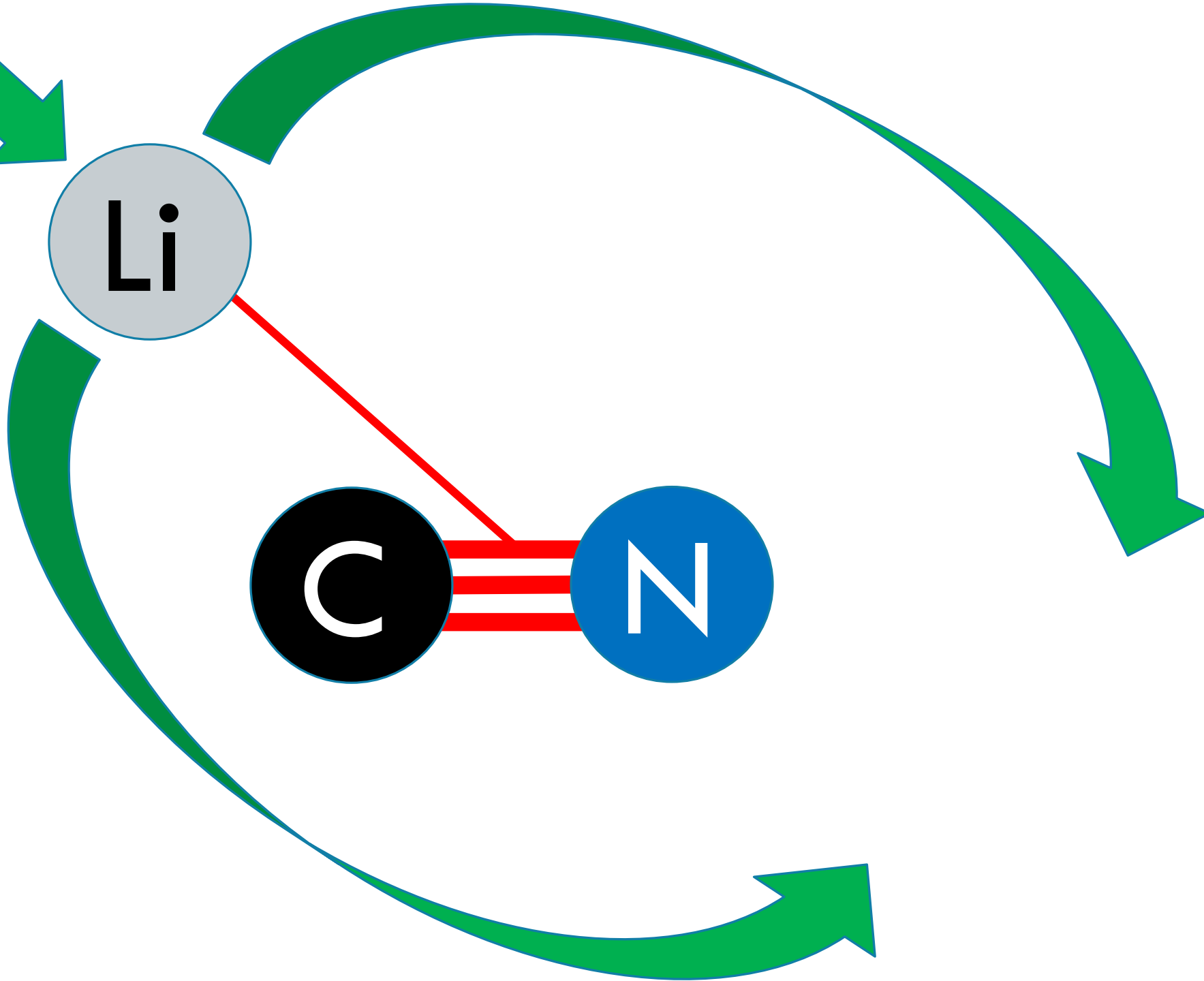
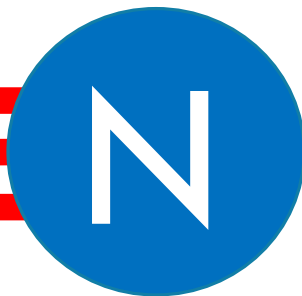
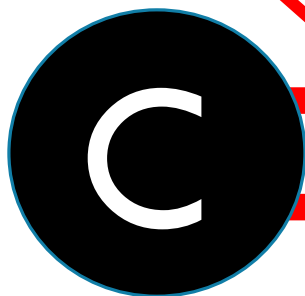
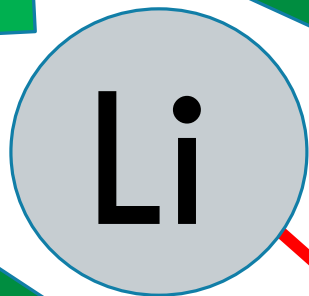


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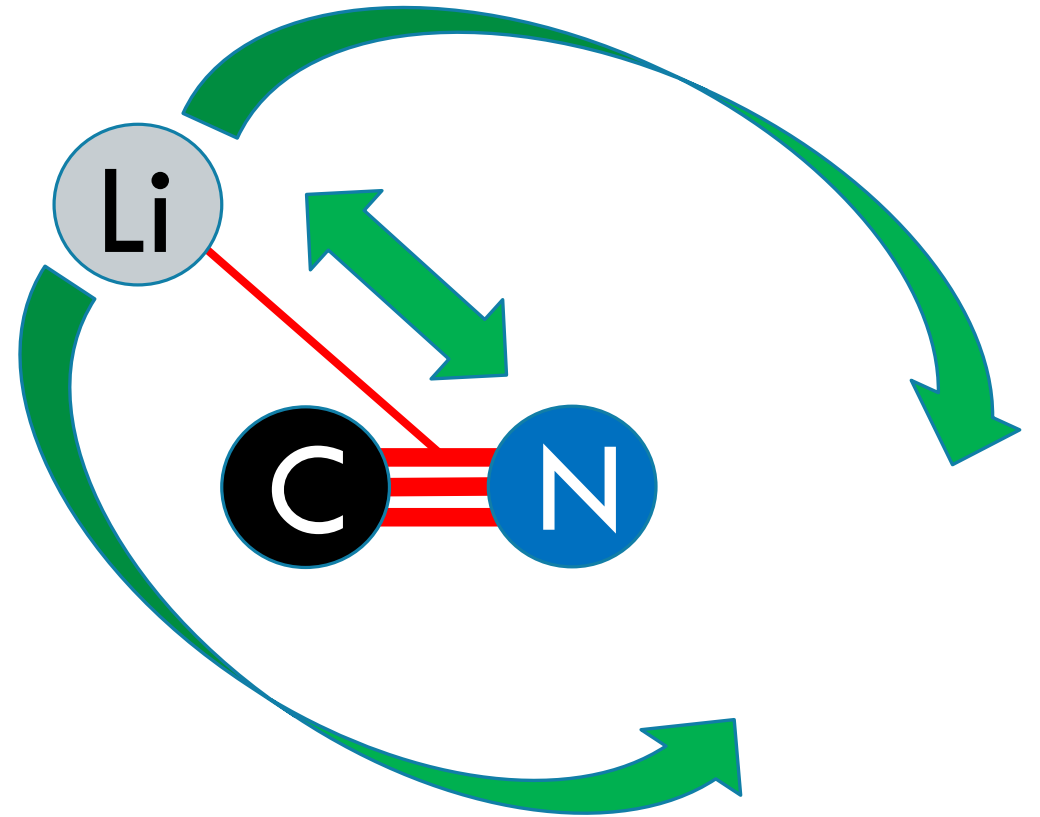


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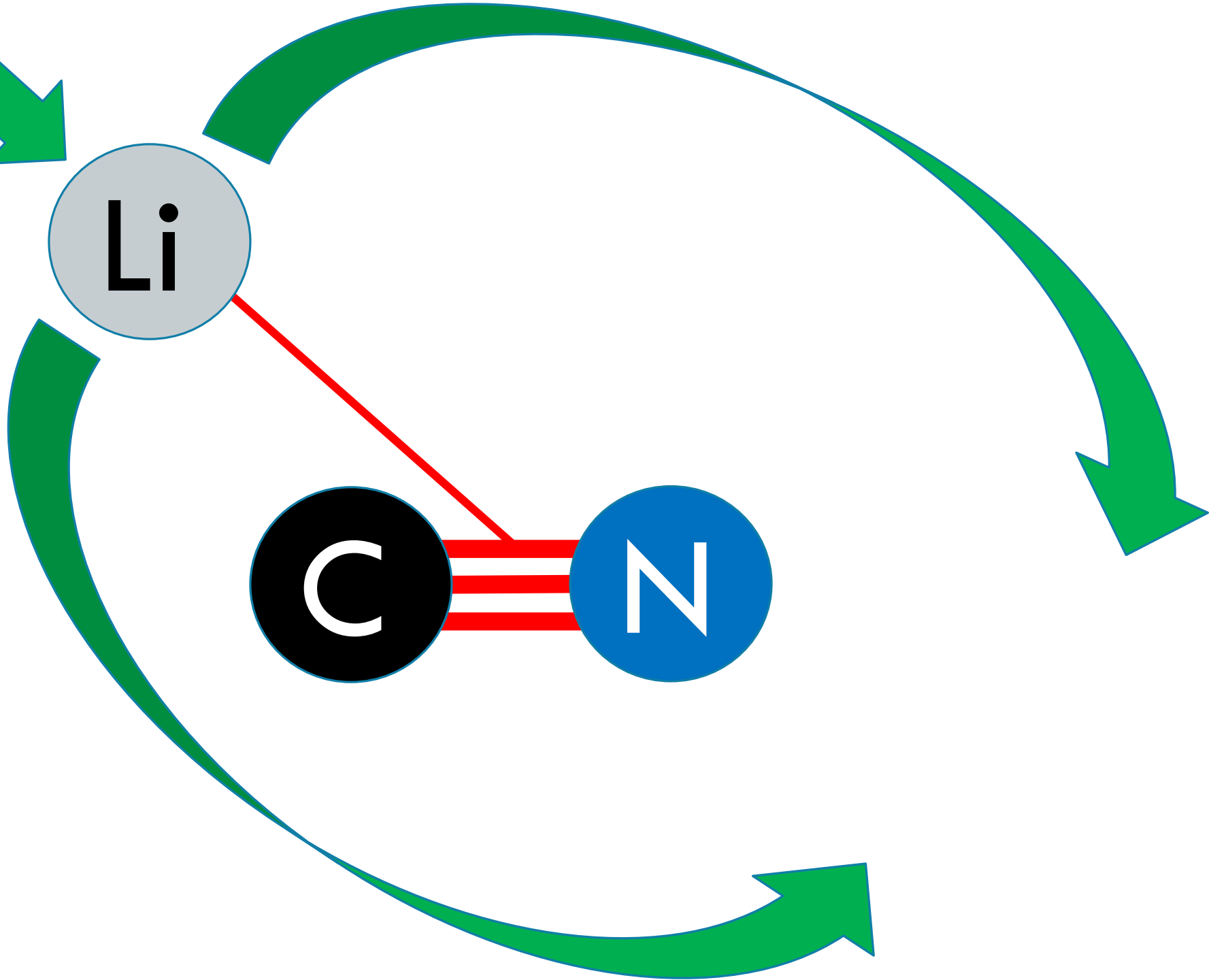
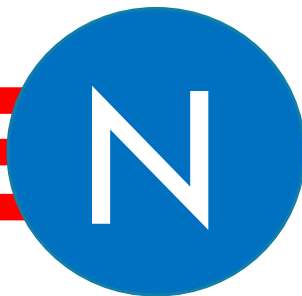
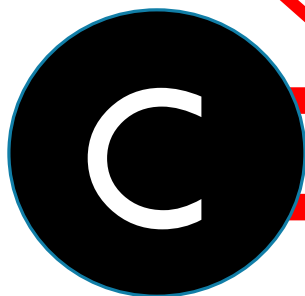
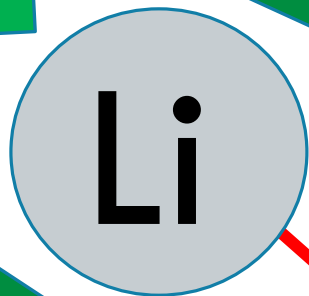


# SYSTEM

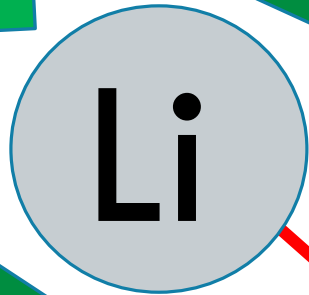
1. 3 atoms: 9 dof
2. No rotation: - 6 dof
3. Coordinates:  $R, \theta, r$



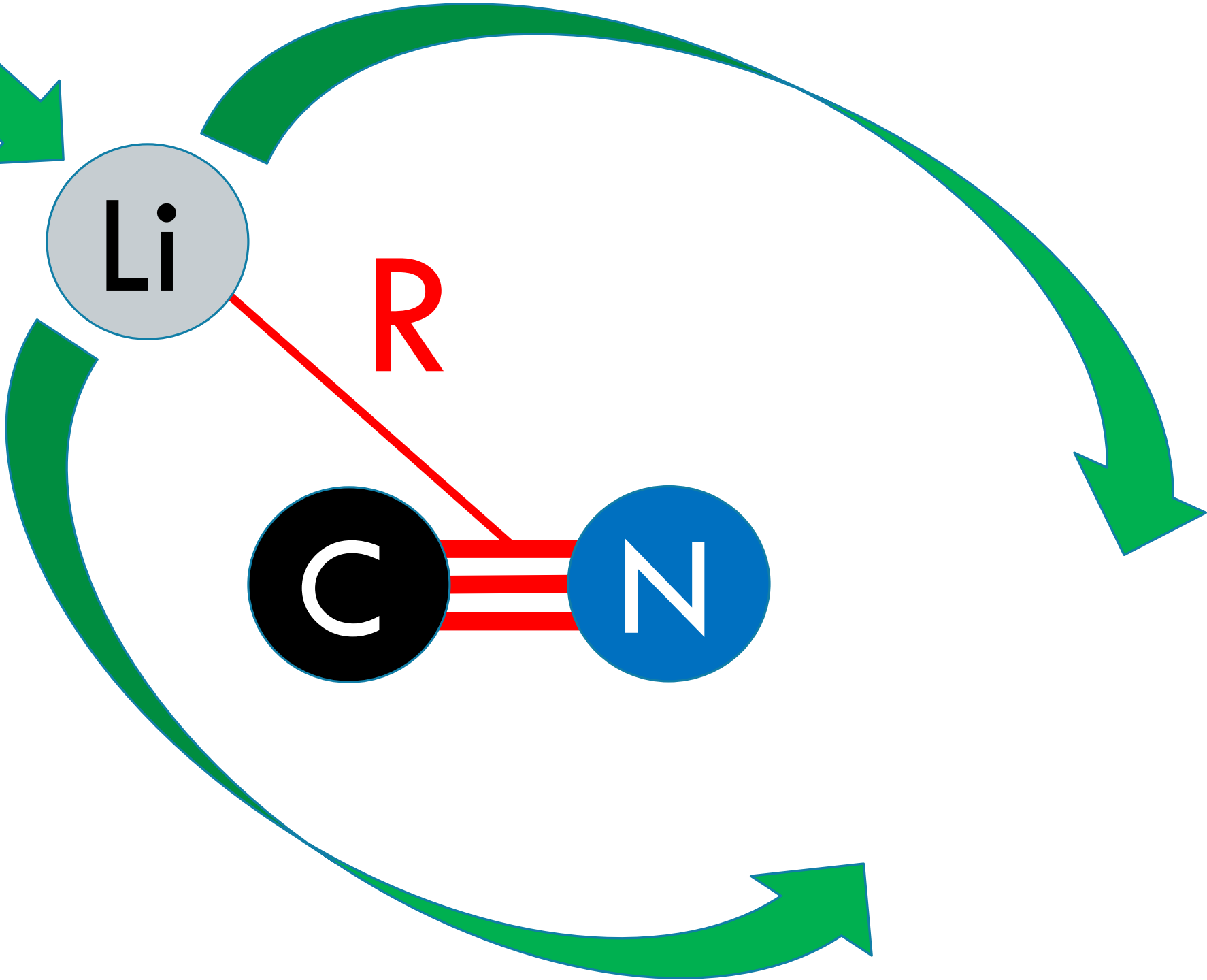
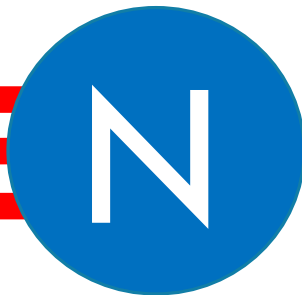
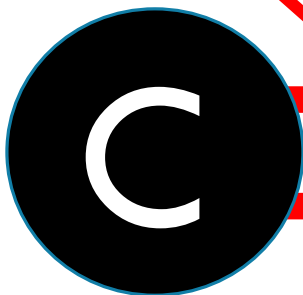
SYSTEM



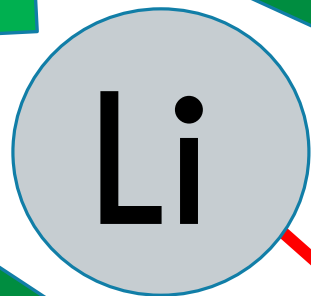
SYSTEM



R

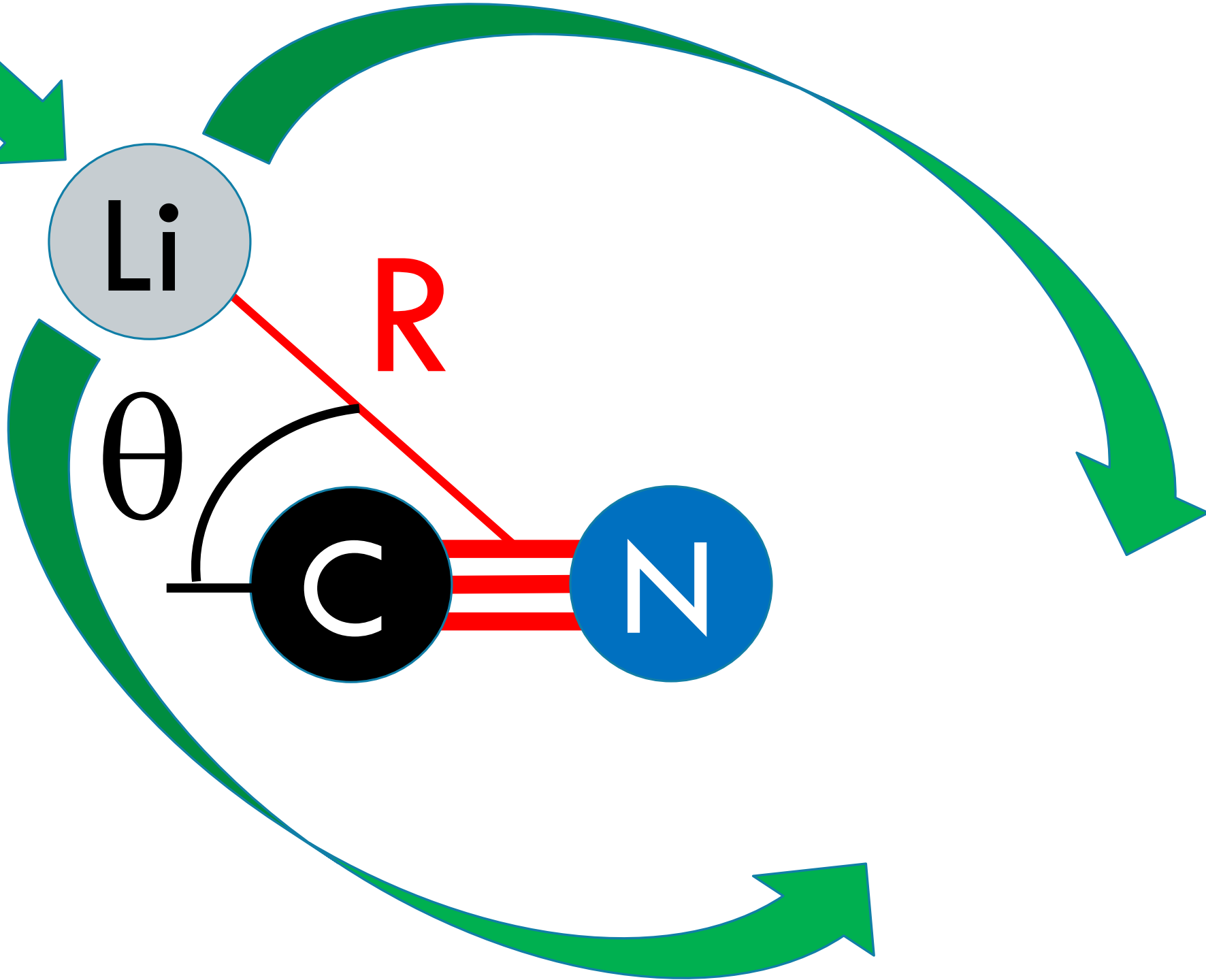
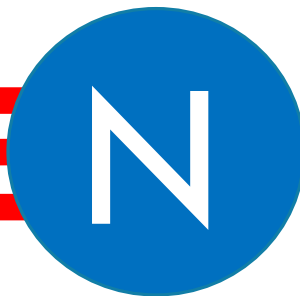
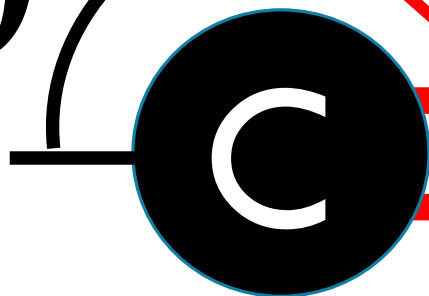


SYSTEM



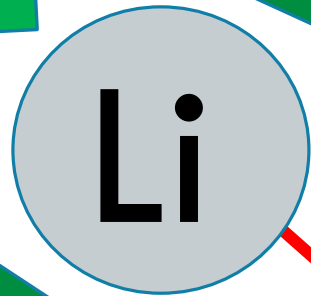
R

$\theta$



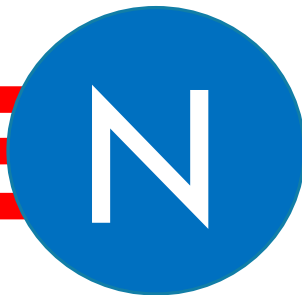
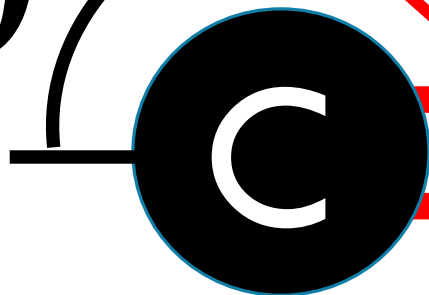


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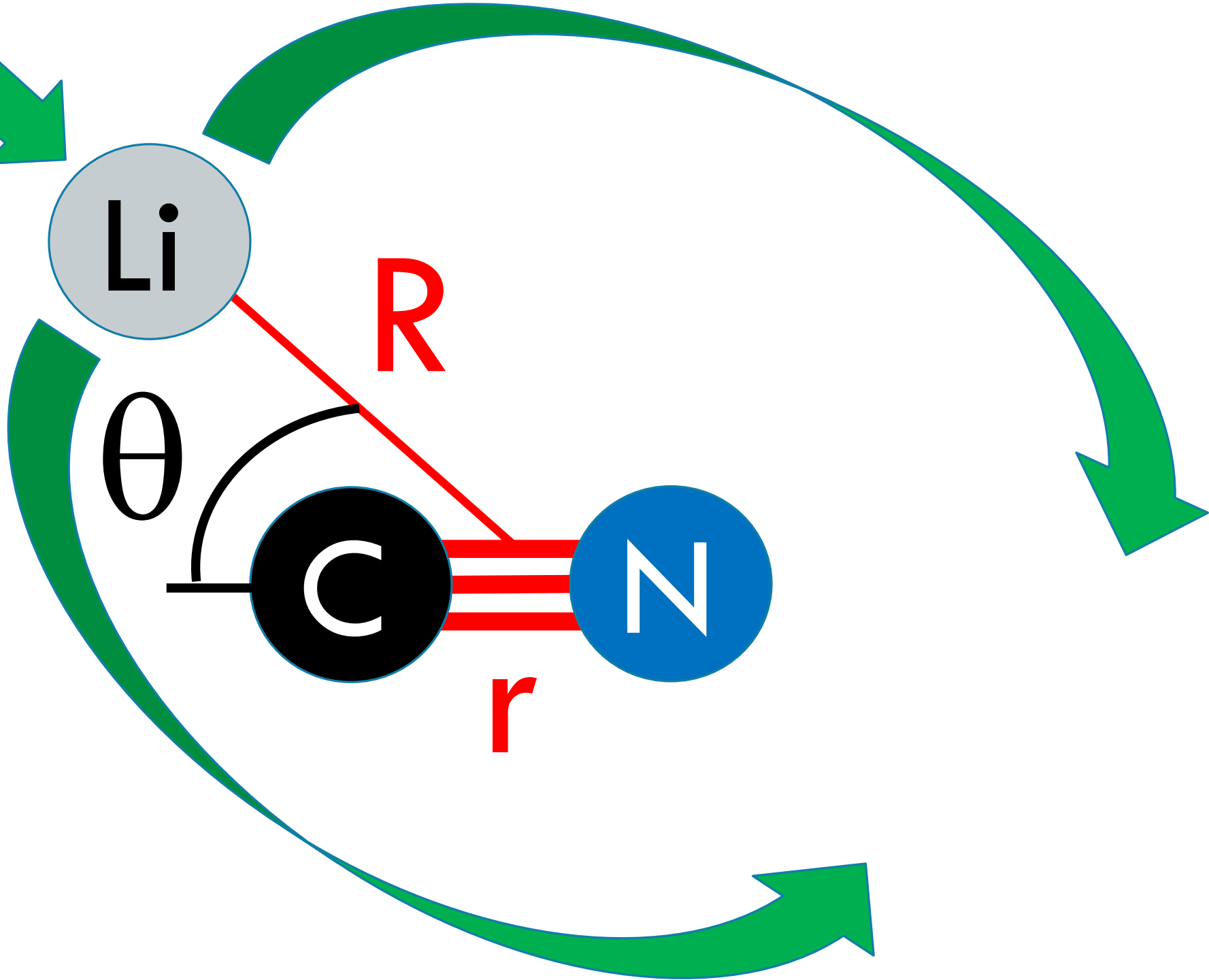


R

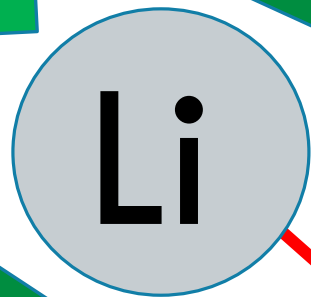
$\theta$



r

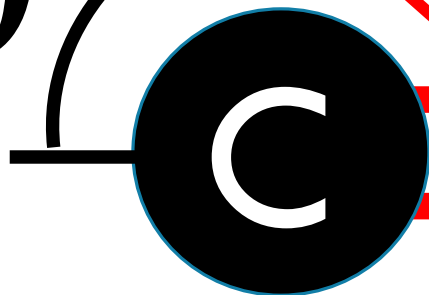


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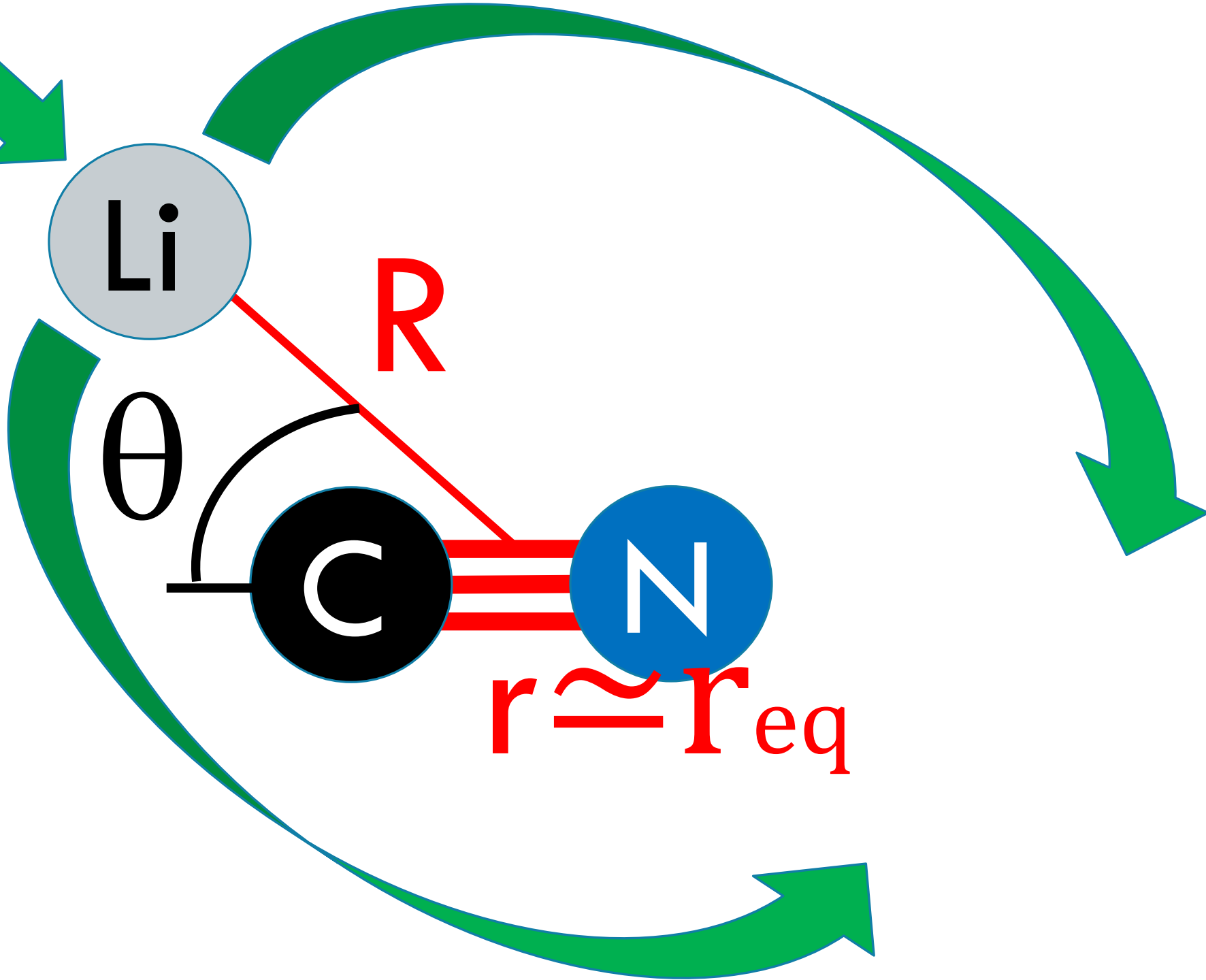


R

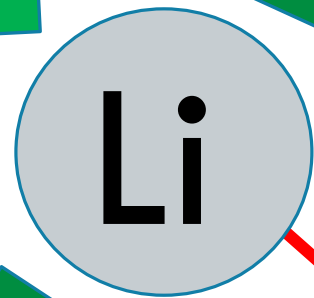
$\theta$



$r \approx r_{eq}$

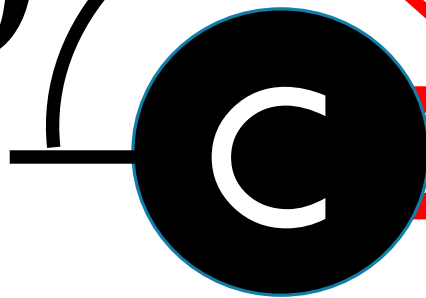


SYSTEM  
(2 DOF)

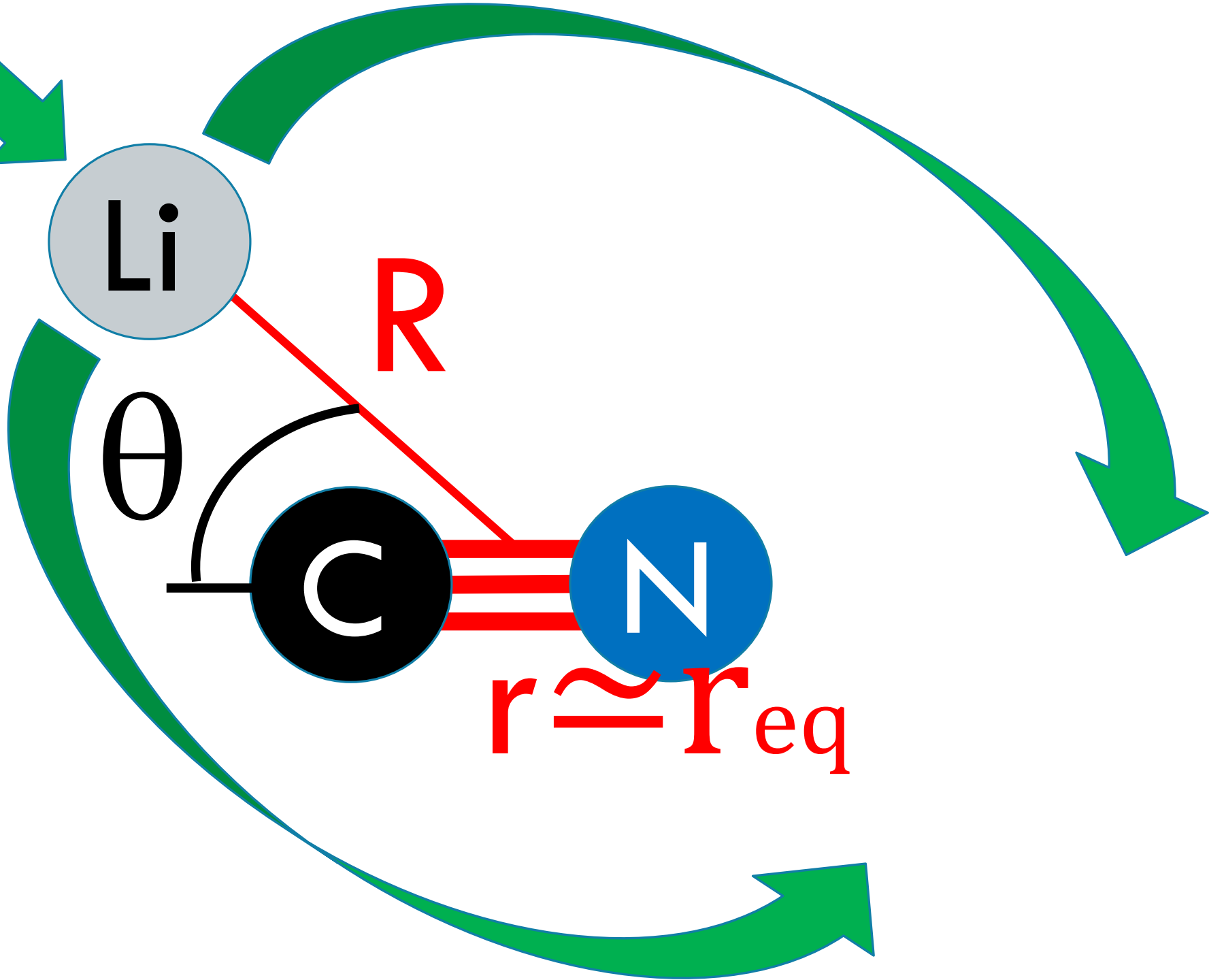


R

$\theta$



$r \approx r_{eq}$





# HAMILTONIAN

# HAMILTONIAN

$$H = \frac{P_R^2}{2\mu_1} + \frac{P_r^2}{2\mu_2} + \left( \frac{1}{\mu_1 R^2} + \frac{1}{\mu_2 r^2} \right) \frac{P_\theta^2}{2} + V(R, r, \theta)$$

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$$\mu_1 = m_K(m_C + m_N) / (m_K + m_C + m_N)$$

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# HAMILTONIAN

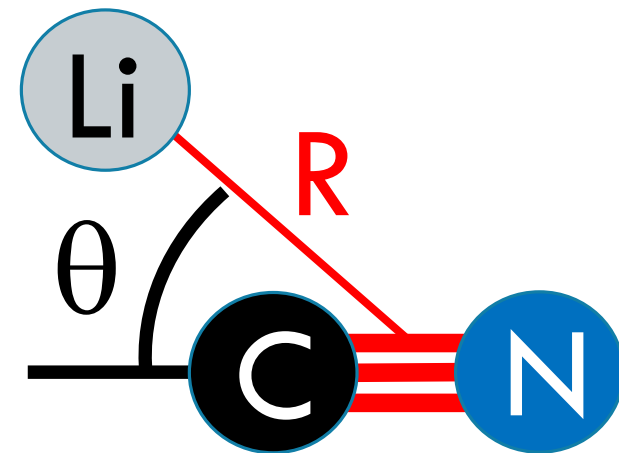
$$H = \frac{P_R^2}{2\mu_1} + \cancel{\frac{P_r^2}{2\mu_2}} + \left( \frac{1}{\mu_1 R^2} + \frac{1}{\mu_2 r^2} \right) \frac{P_\theta^2}{2} + V(R, r, \theta)$$

# HAMILTONIAN

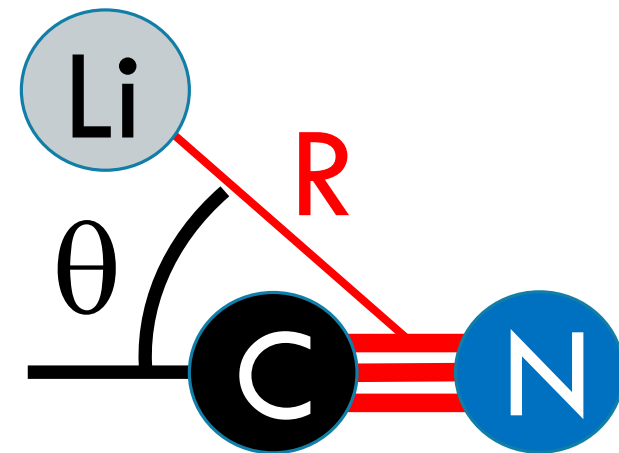
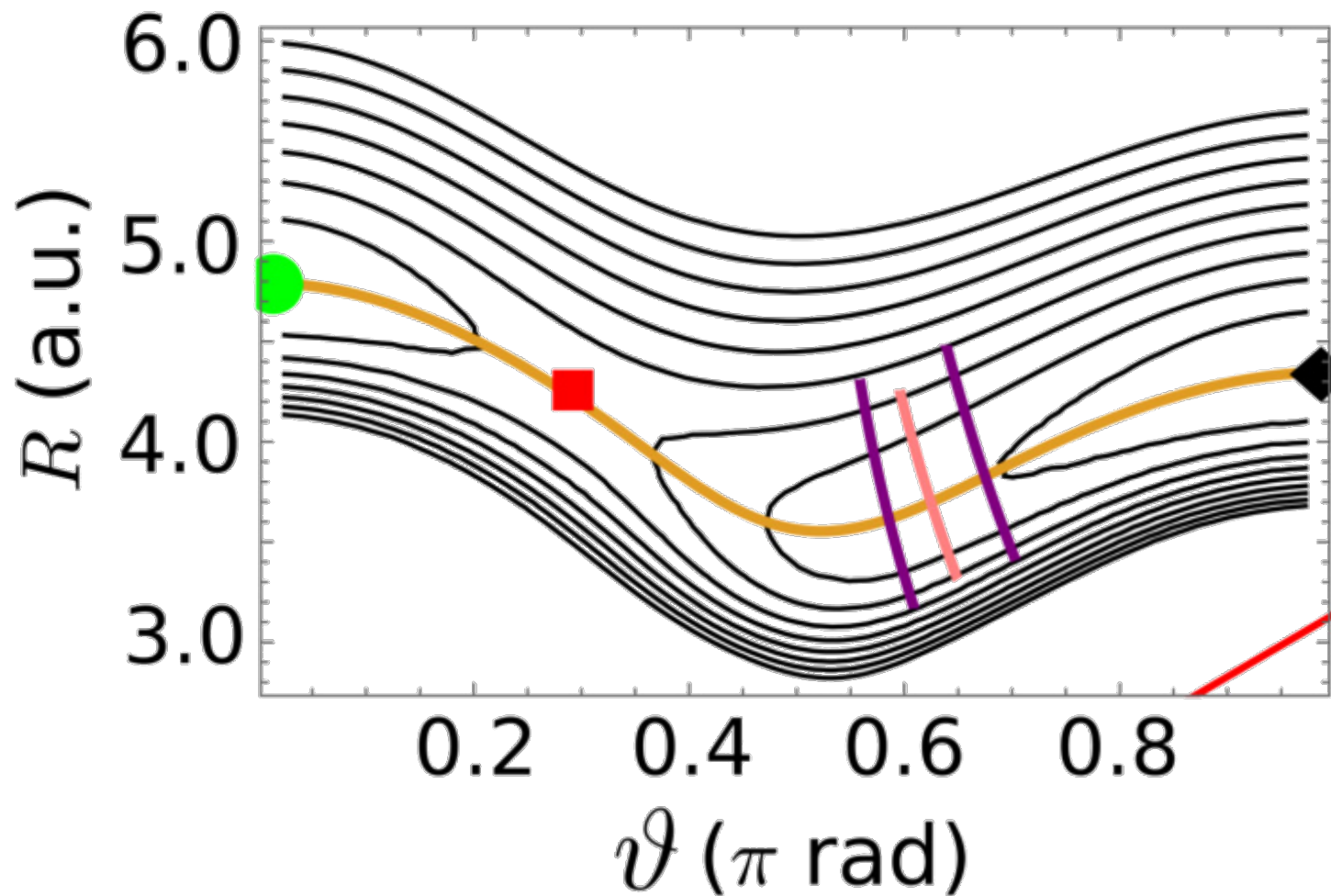
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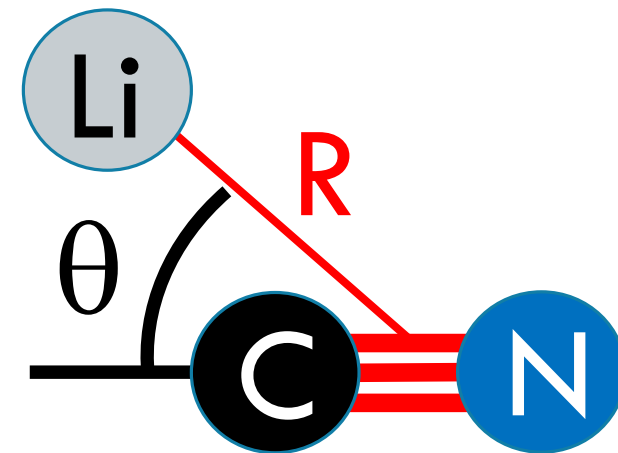
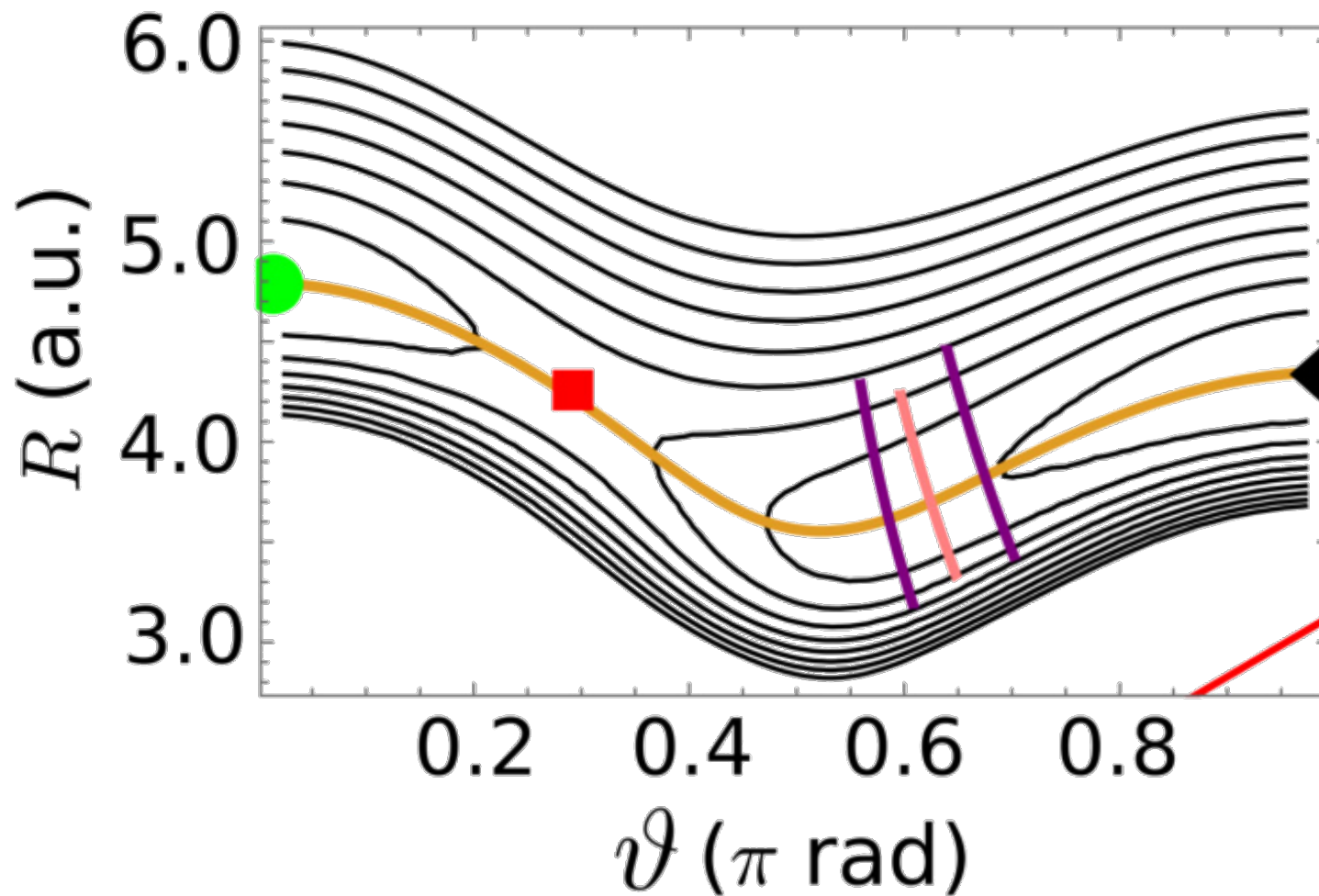
# POTENTIAL ENERGY SURFACE



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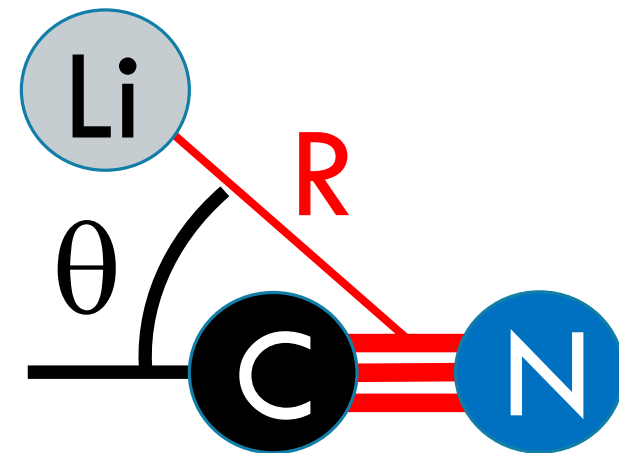
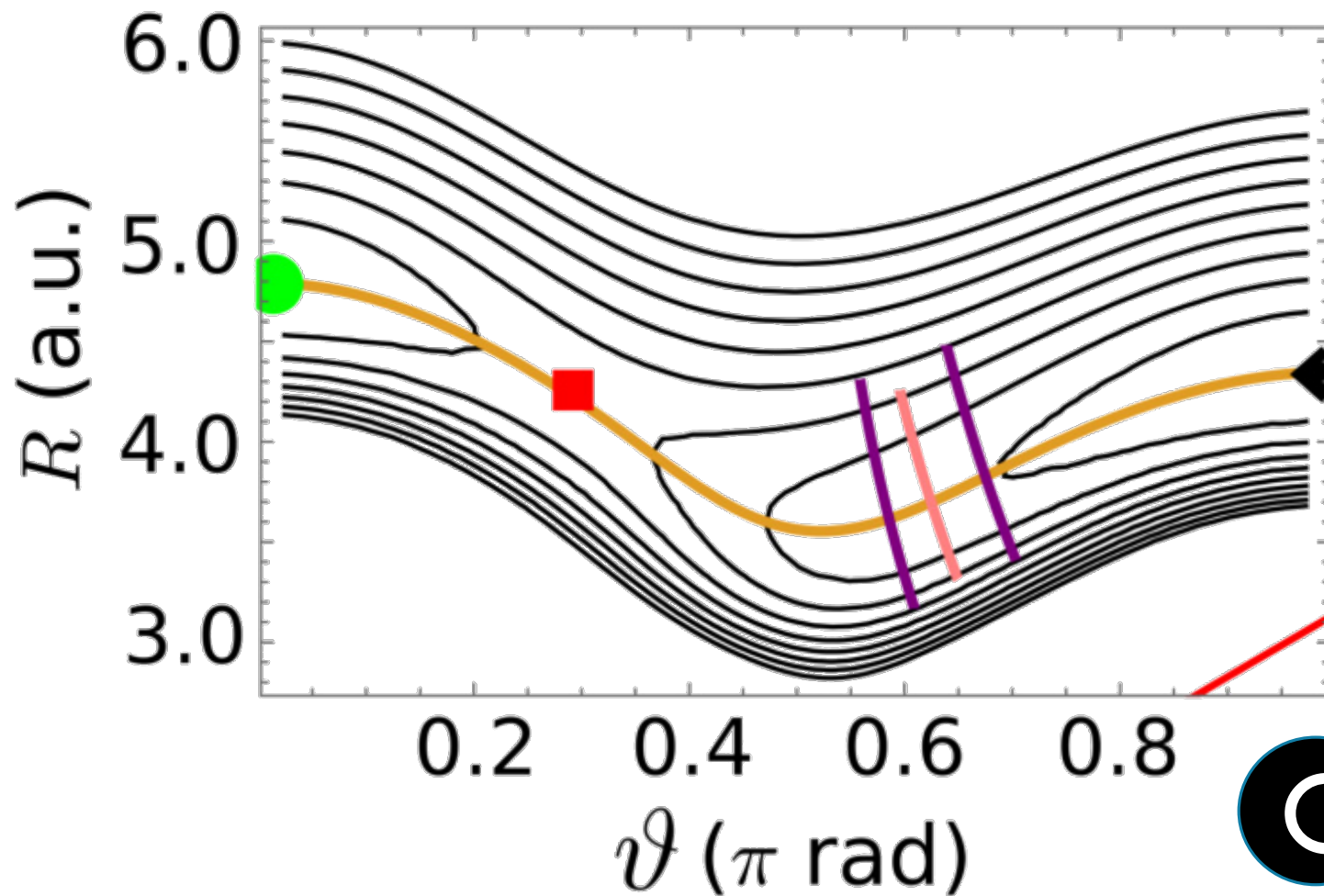


# POTENTIAL ENERGY SURFACE



Absolute  
minimum

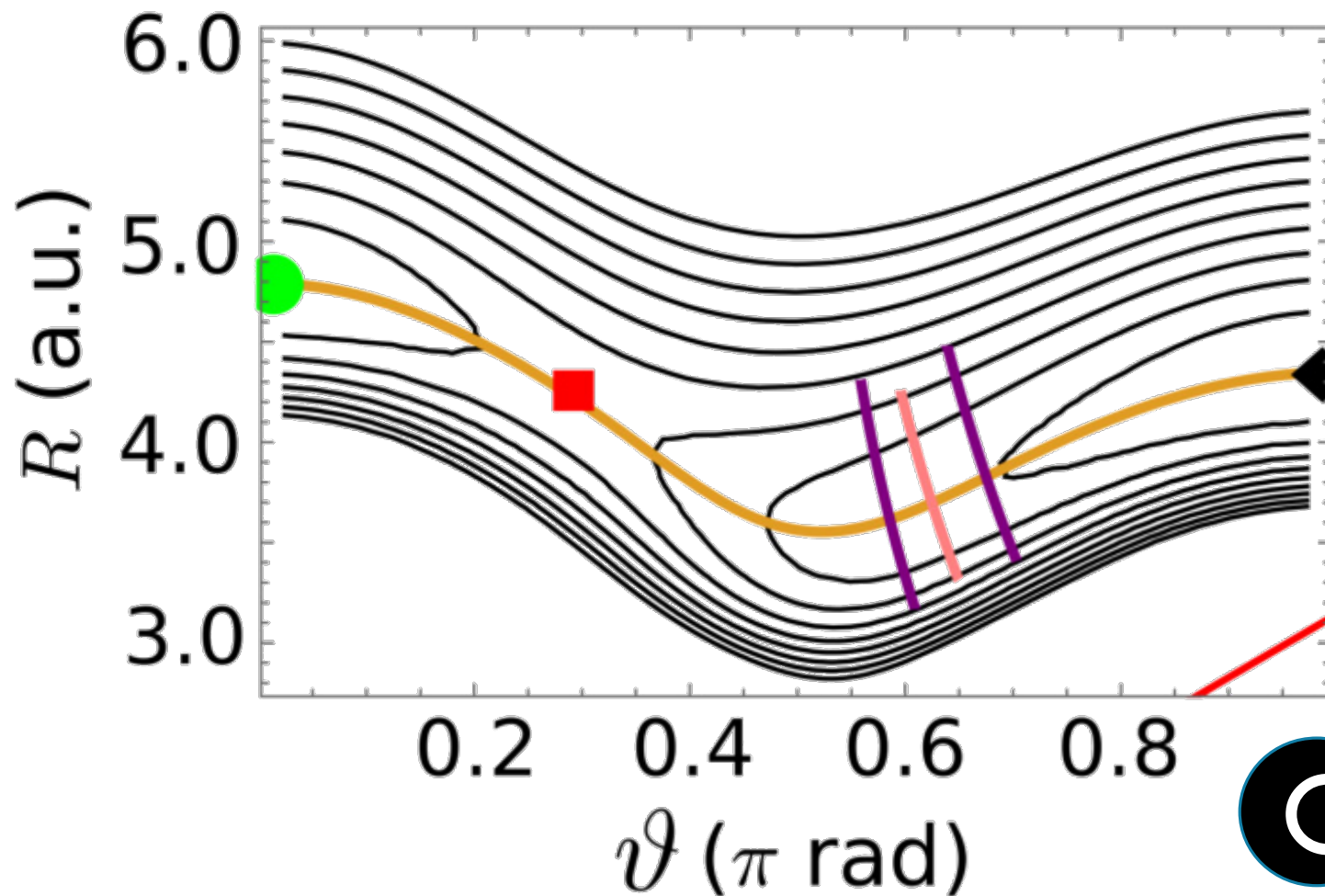
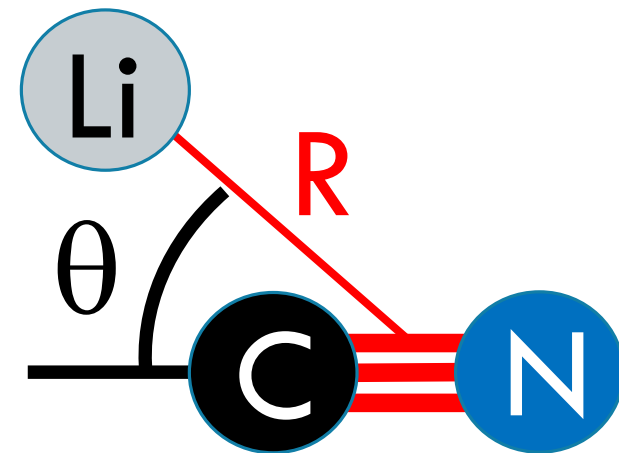
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Absolute minimum



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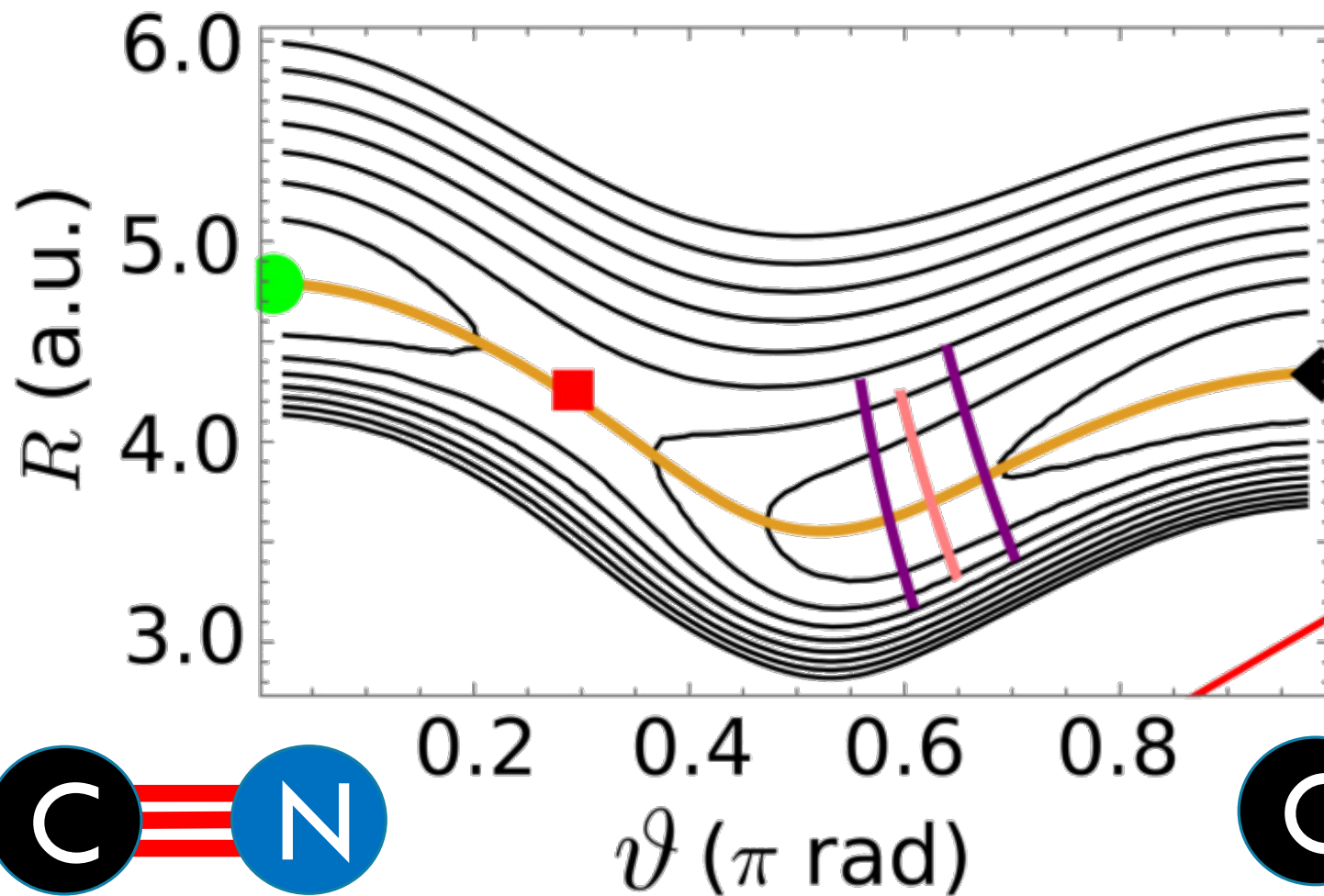
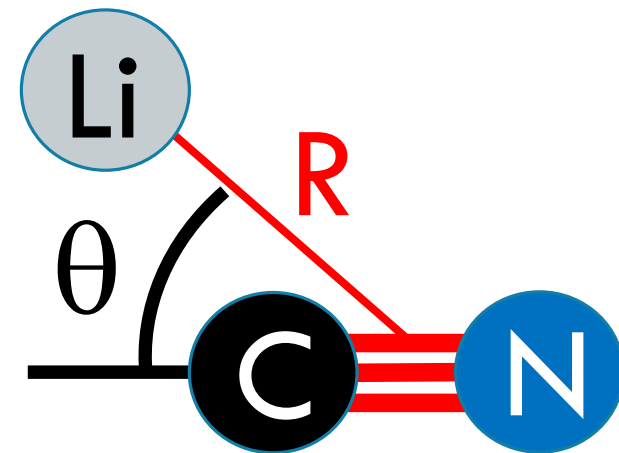
Absolute  
minimum



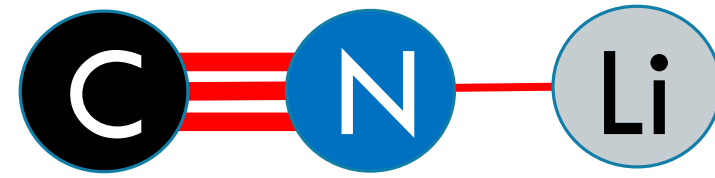
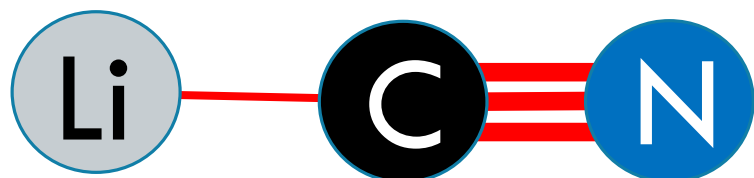
Relative  
minimum



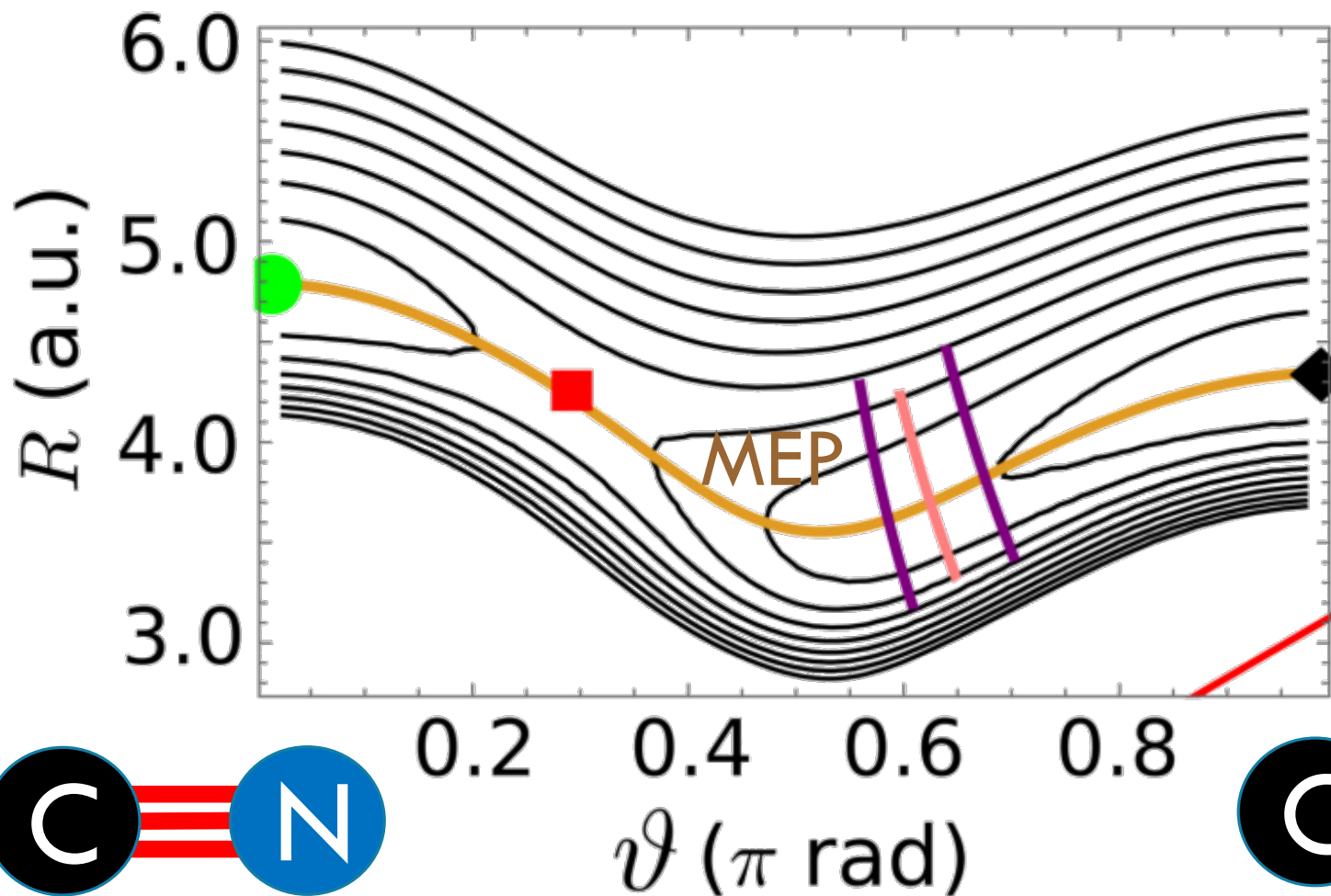
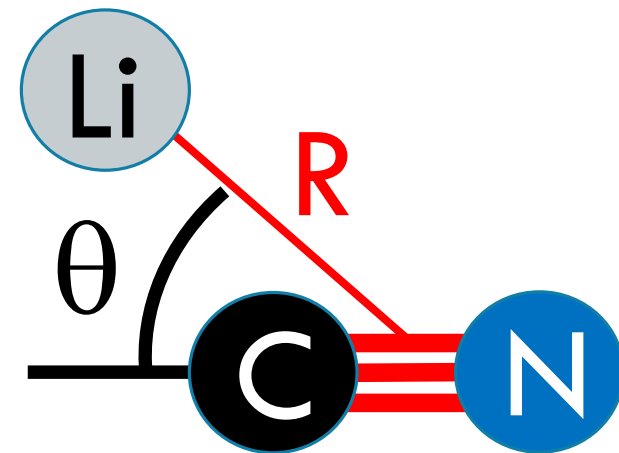
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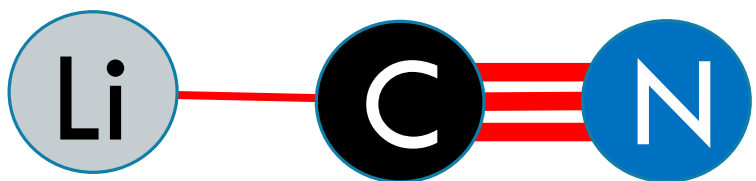
Absolute minimum



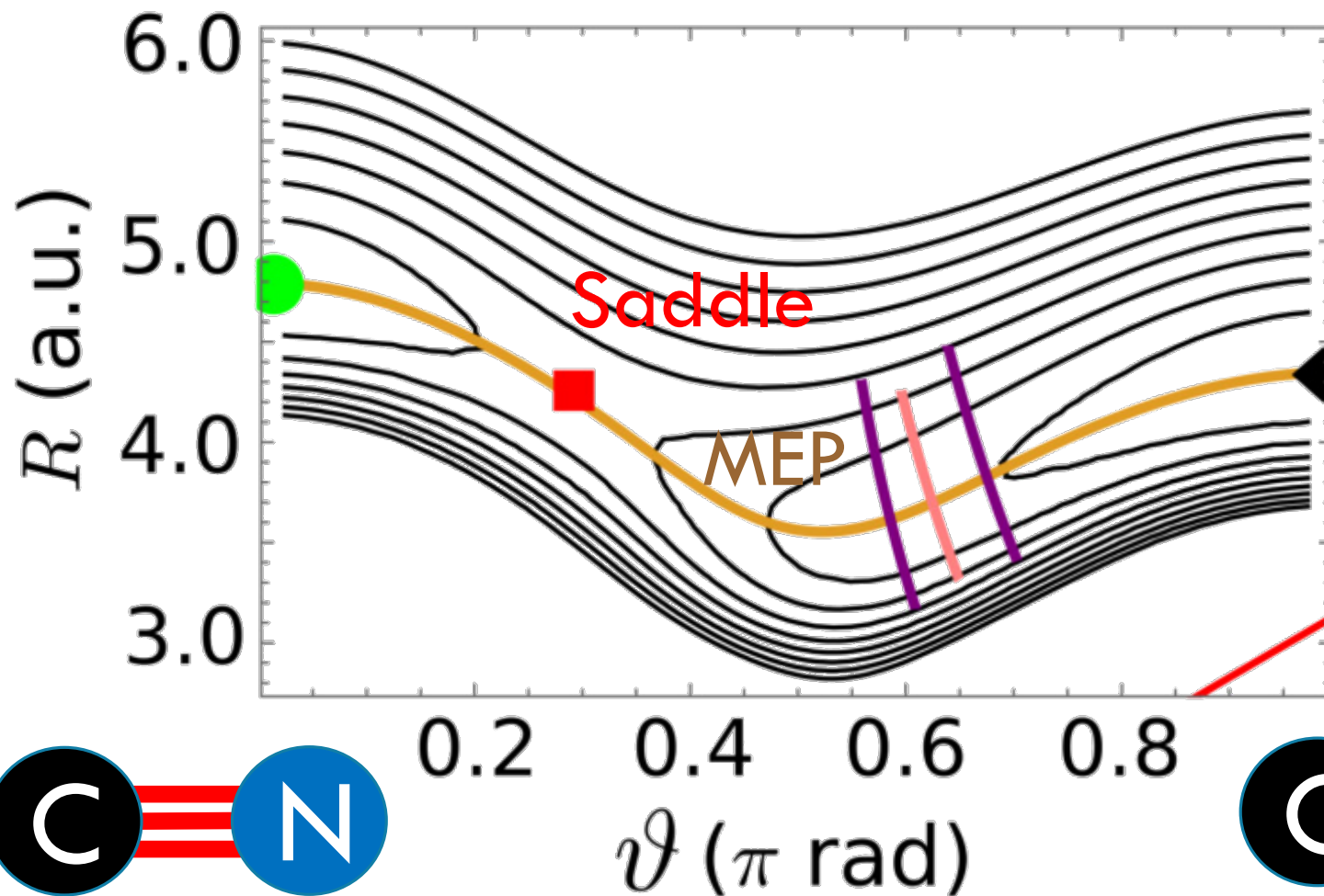
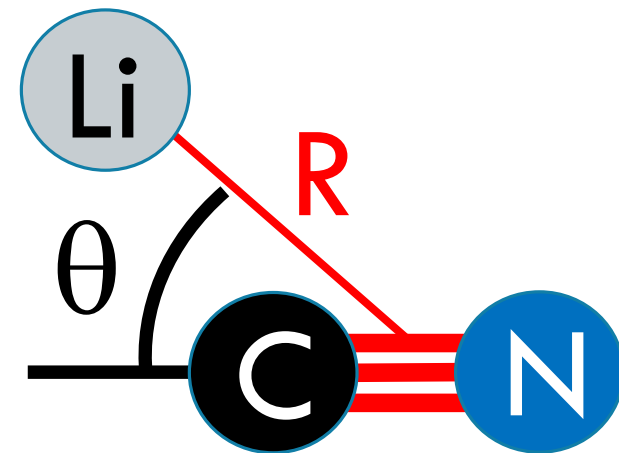
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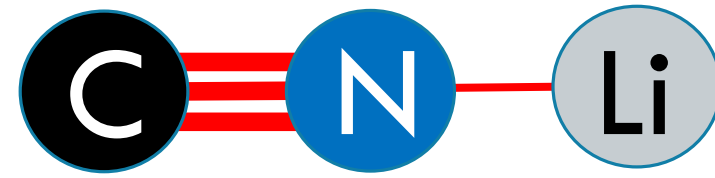
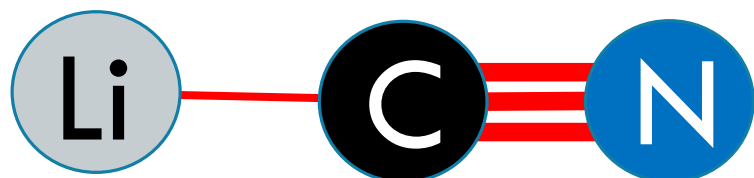
Absolute minimum



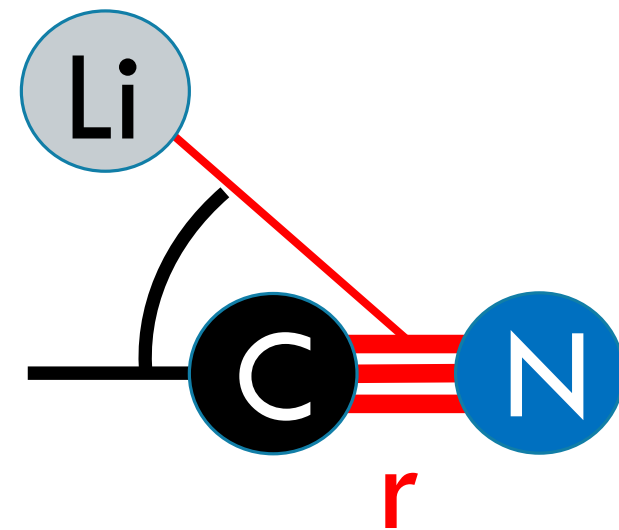
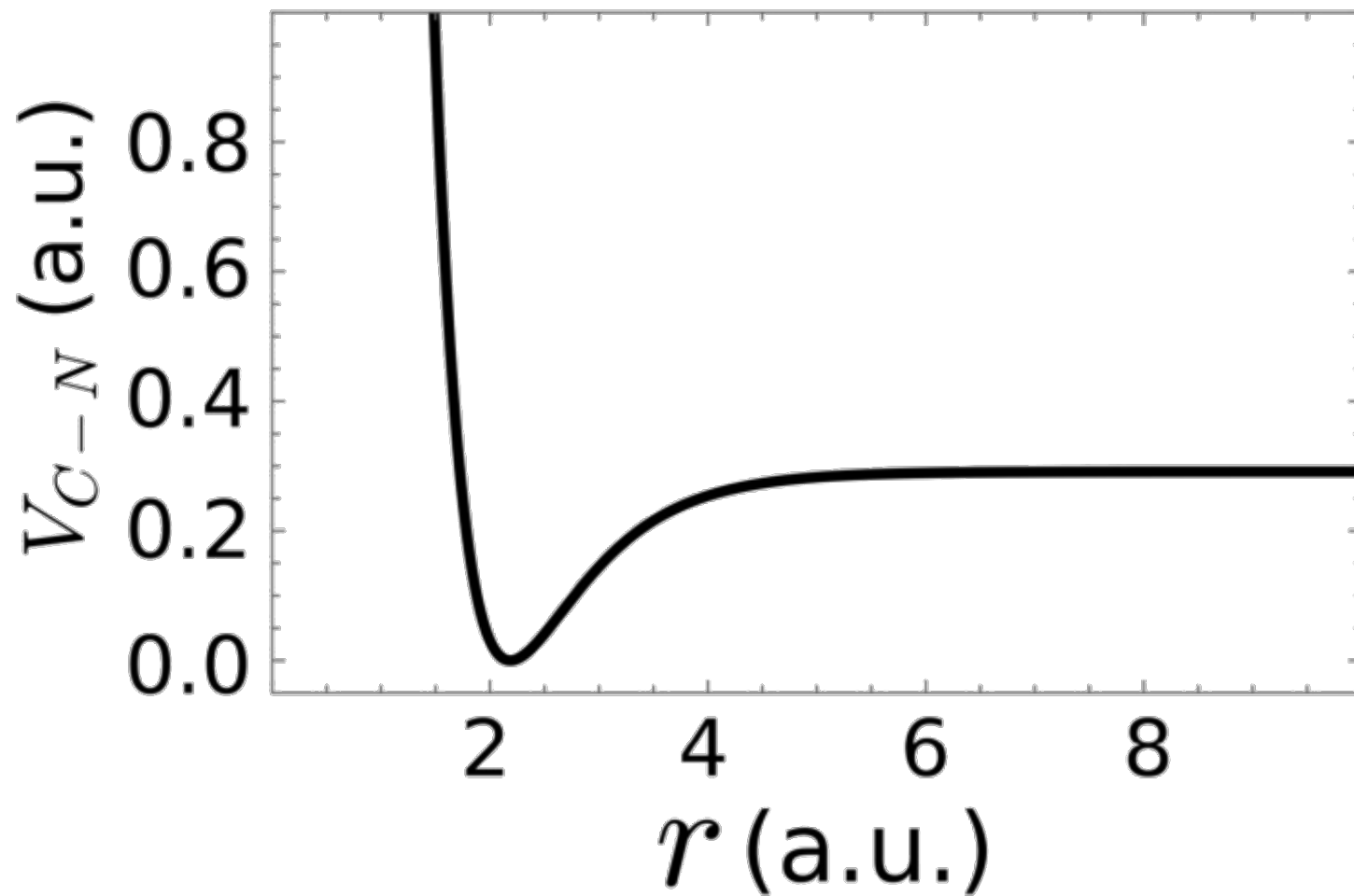
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Absolute minimum



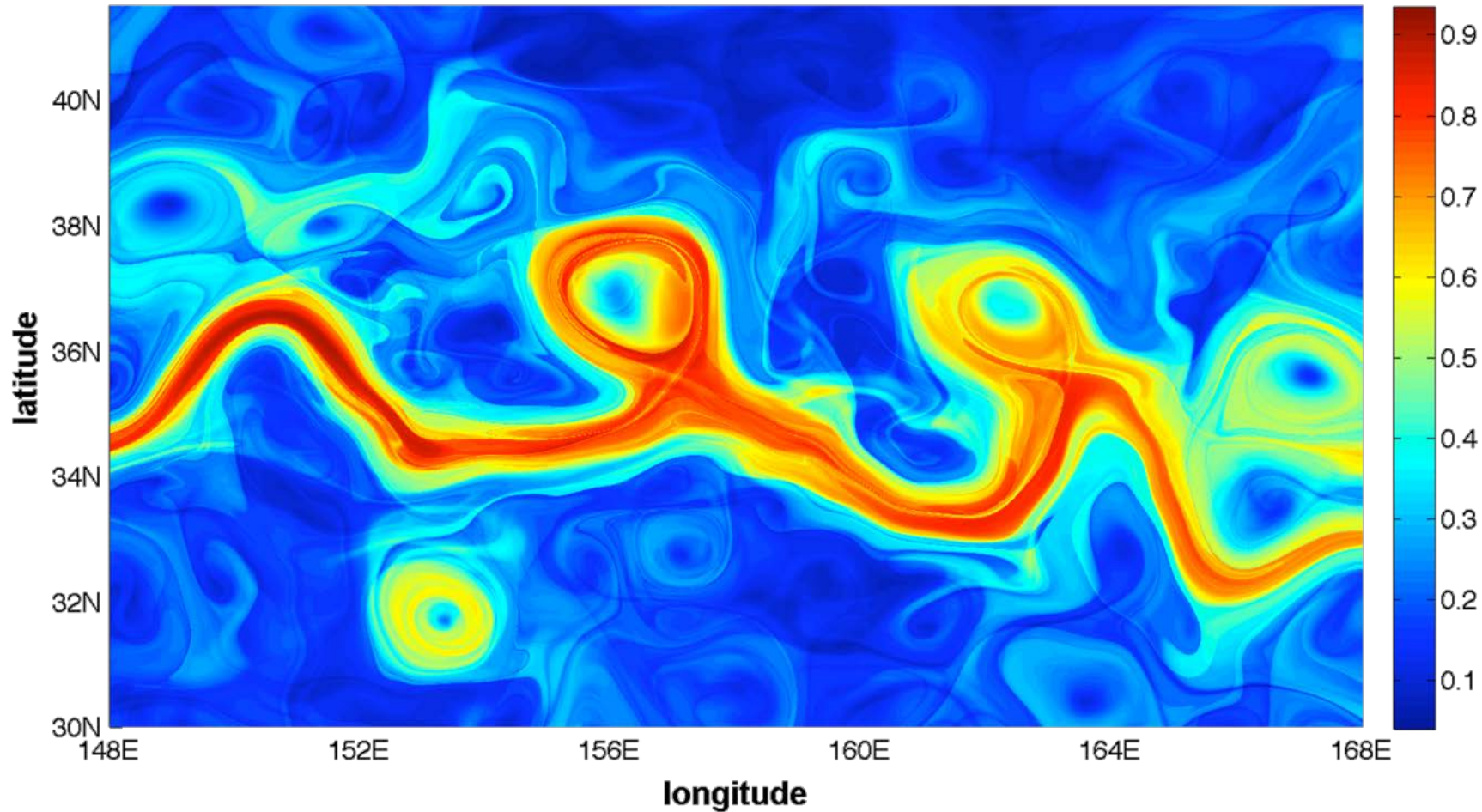
# POTENTIAL ENERGY SURFACE



The image features a hand in the foreground holding a glowing blue gear. The background is filled with various gears, some of which are glowing blue and others are faint outlines. A person's hands are visible in the background, suggesting a technical or engineering context. The overall theme is related to methodology, engineering, or technology.

# Methodology

# LAGRANGIAN DESCRIPTORS



Oceanic  
flows

Figure:  
C. Mendoza, A. M. Mancho,  
Nonlin. Processes Geophys.  
**19**, 449, 2012

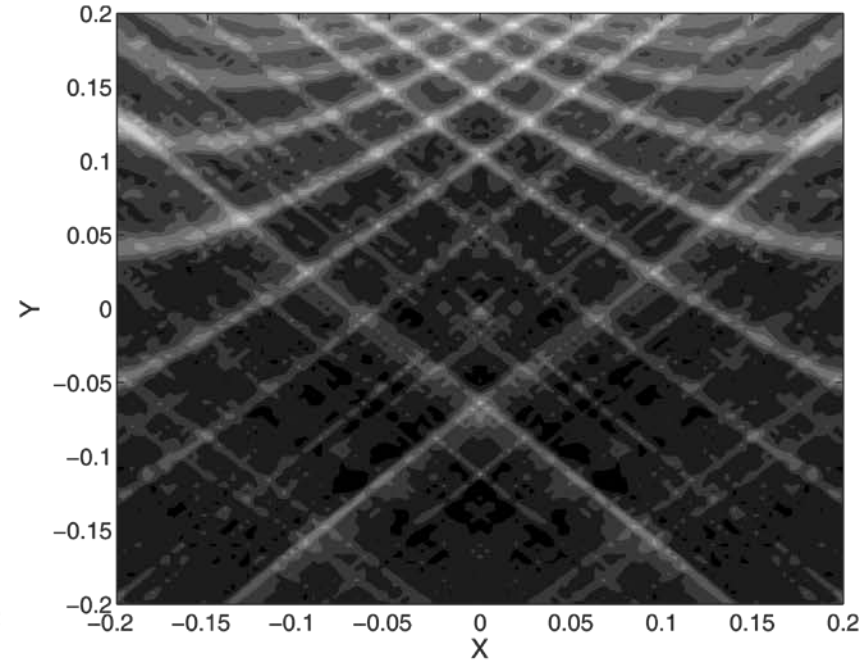
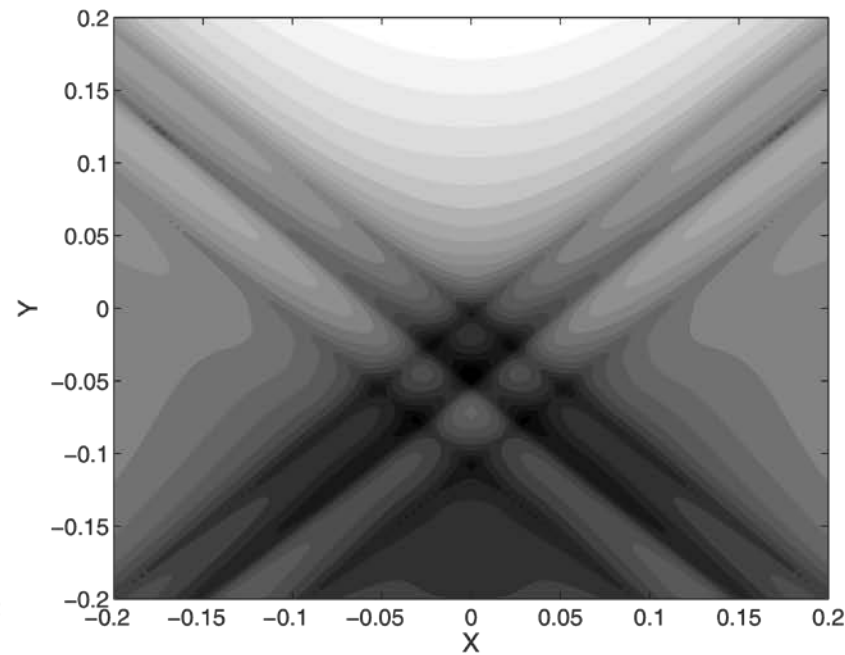
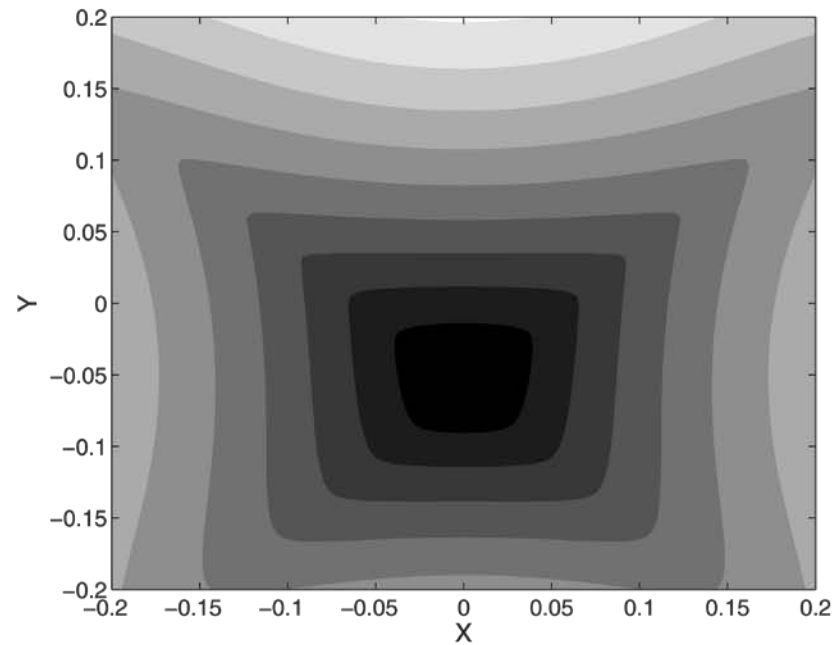
# LAGRANGIAN DESCRIPTORS

$$\dot{\mathbf{z}} = f(\mathbf{z}_0, t)$$

$$M(\mathbf{z}_0, \tau) = \int_{-\tau}^{\tau} \sqrt{\sum_{i=1}^N |\dot{z}_i(t)|^2} dt$$

# EXAMPLE: INVARIANT MANIFOLDS IN DUFFING EQ.

$$\dot{x} = y, \quad \dot{y} = x - x^3 + \varepsilon \sin(t)$$



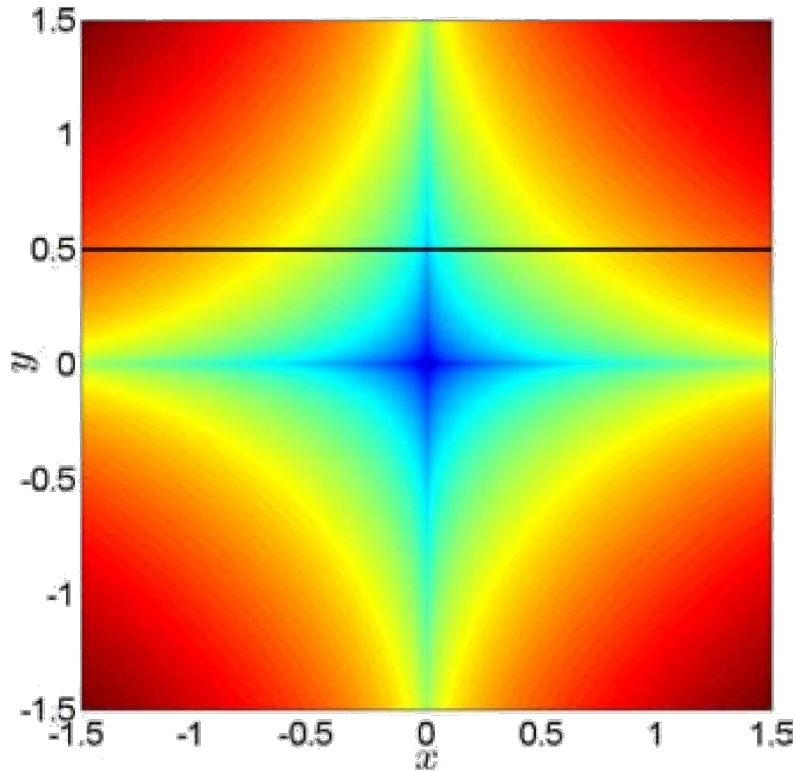


## LAGRANGIAN DESCRIPTORS: P-NORM

$$M(\mathbf{z}_0, \tau) = \int_{-\tau}^{\tau} \sum_{i=1}^N |\dot{z}_i(t)|^p dt$$

C. Lopesino, F. Balibrea-Iniesta, V. J. García-Garrido, S. Wiggins  
and A. M. Mancho, *Int. J. Bifur. and Chaos* **27**, 1730001 (2017)

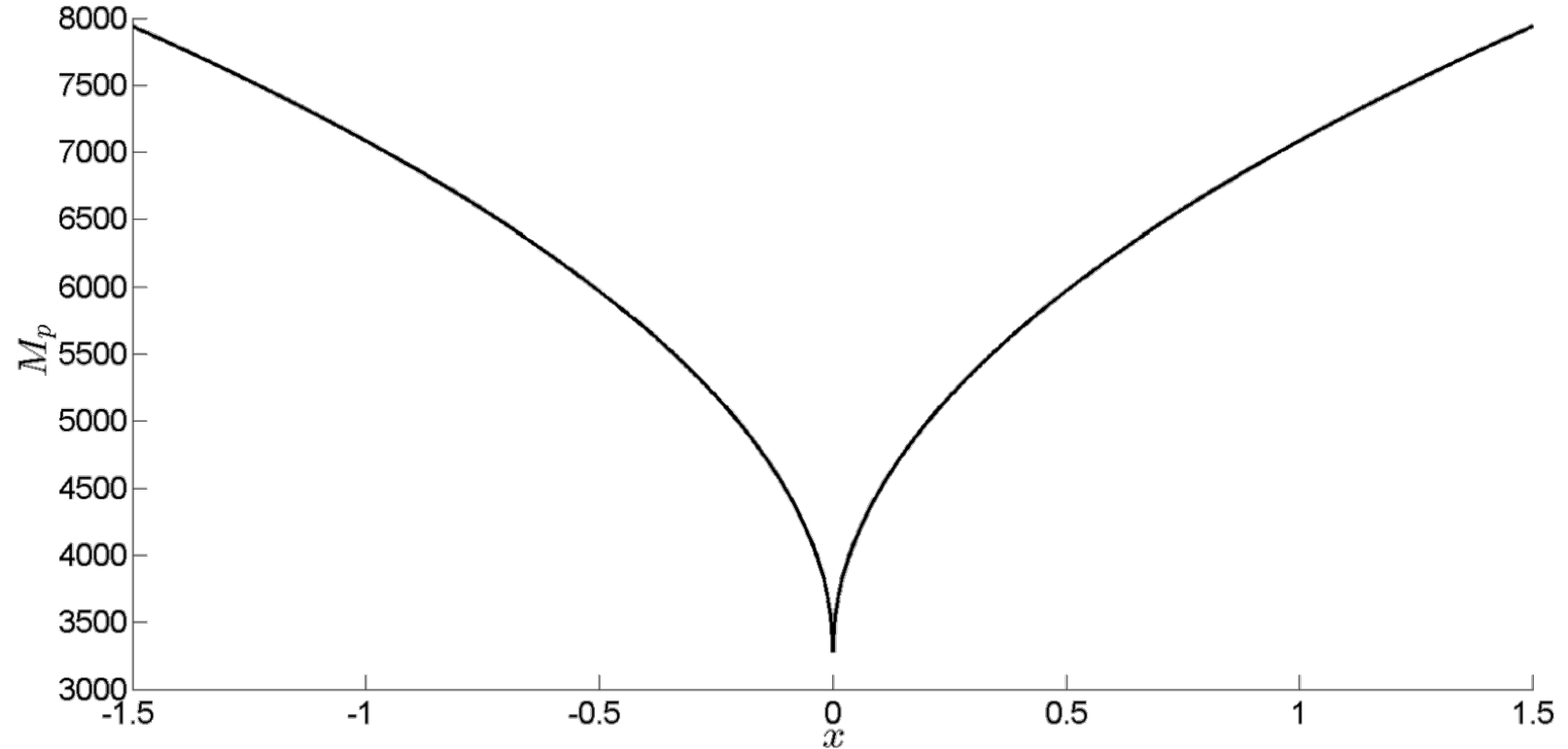
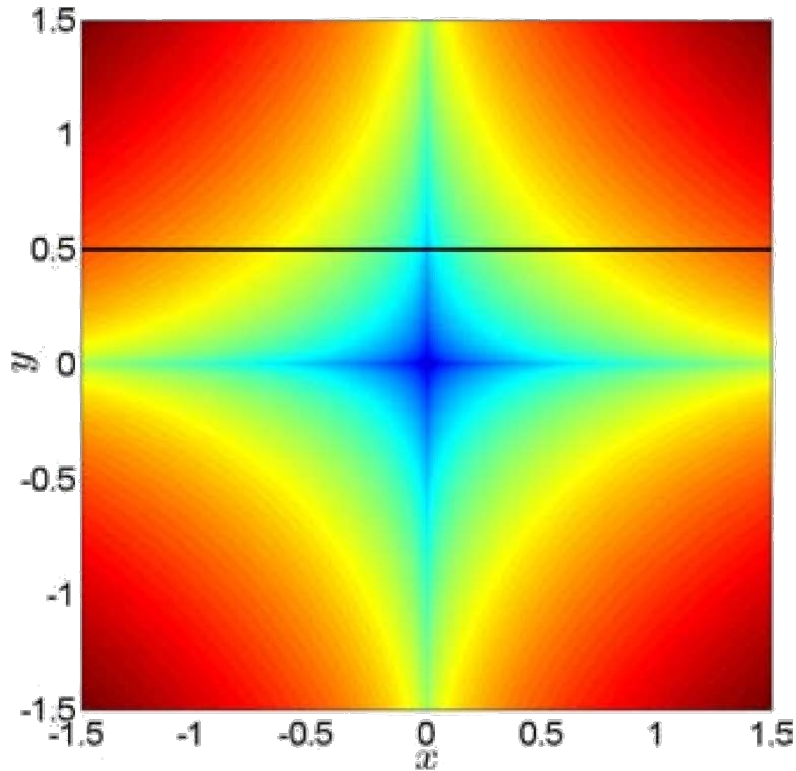
# INVARIANT MANIFOLDS = SINGULARITIES



$$\begin{cases} \dot{x} = \lambda x \\ \dot{y} = -\lambda y \end{cases}, \quad \lambda > 0$$

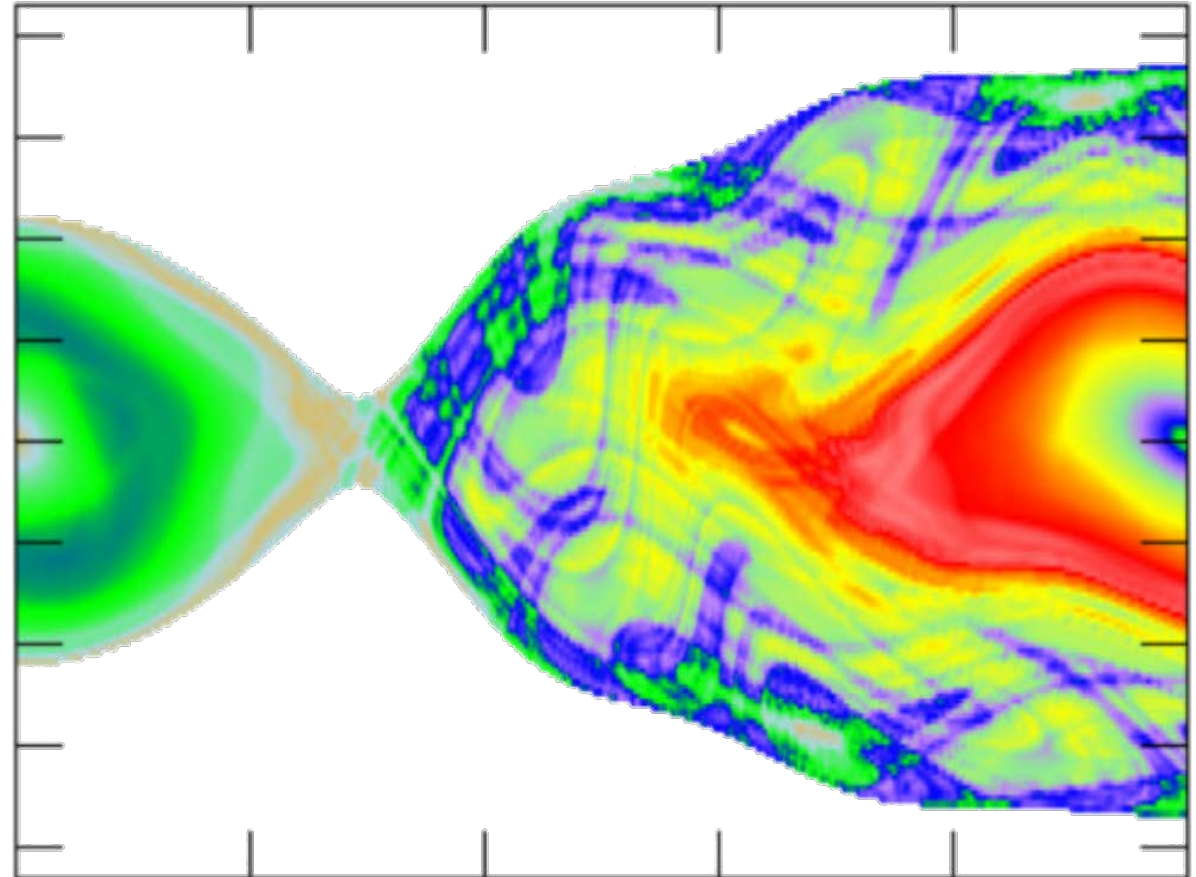
C. Lopesino, F. Balibrea-Iniesta, V. J. García-Garrido, S. Wiggins  
and A. M. Mancho, *Int. J. Bifur. and Chaos* **27**, 1730001 (2017)

# INVARIANT MANIFOLDS = SINGULARITIES



C. Lopesino, F. Balibrea-Iniesta, V. J. García-Garrido, S. Wiggins  
and A. M. Mancho, *Int. J. Bifur. and Chaos* **27**, 1730001 (2017)

# Results

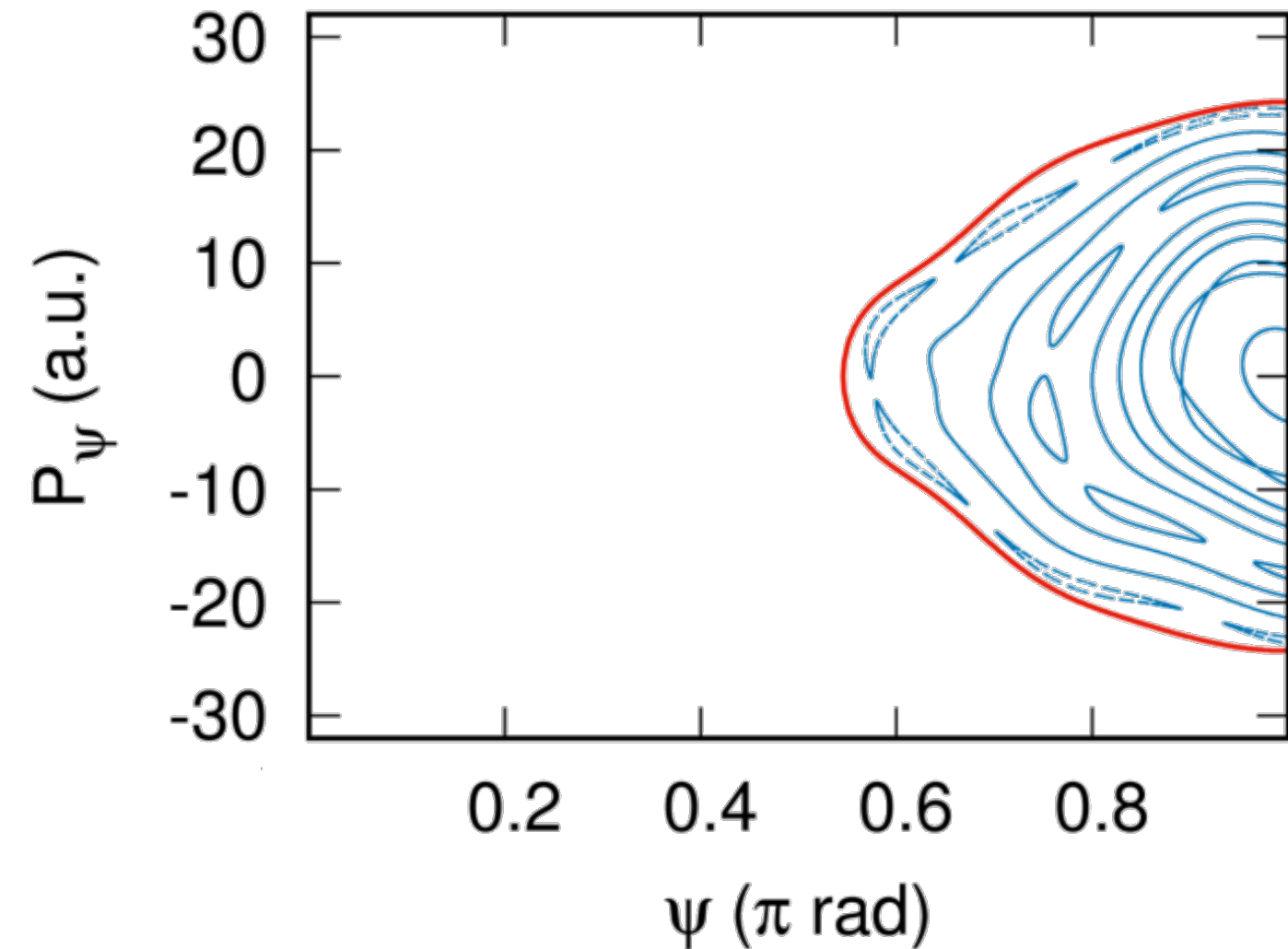


# Results

1. System with 2 dof
2. Saddle-node bifurcation
3. System with 3 dof

# POINCARÉ SUPERFICIE OF SECTION

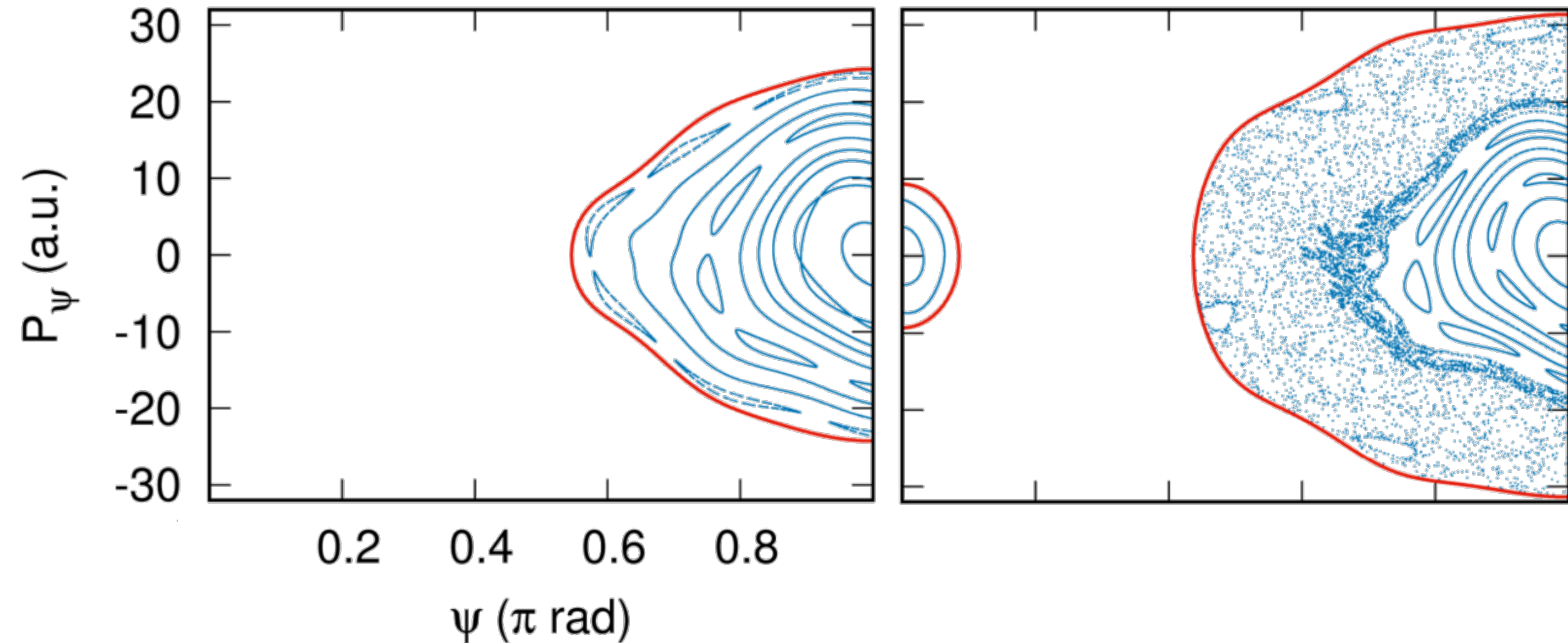
$$E = 1500 \text{ cm}^{-1}$$



# POINCARÉ SUPERFICIE OF SECTION

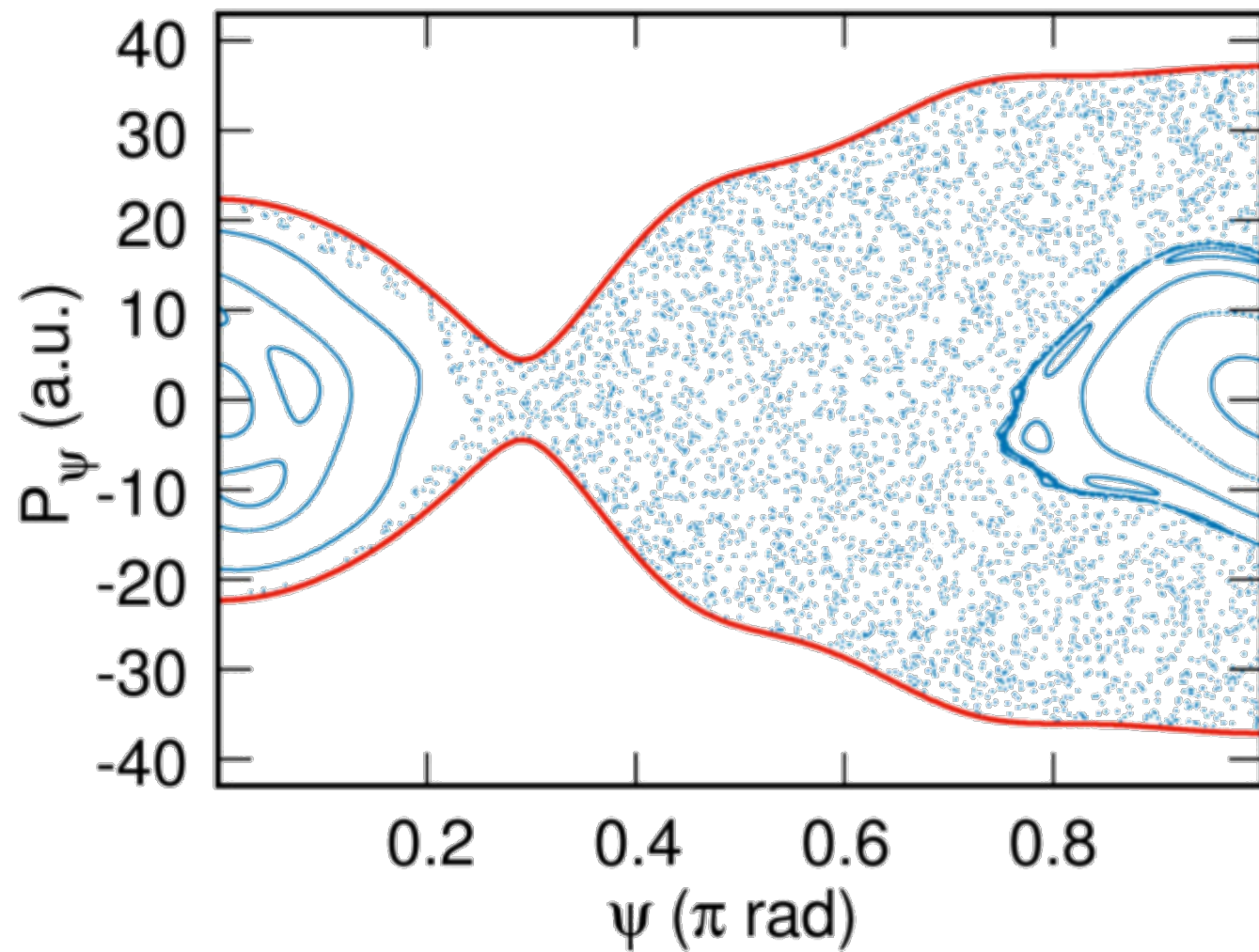
$$E = 1500 \text{ cm}^{-1}$$

$$E = 2500 \text{ cm}^{-1}$$



$$E = 3500 \text{ cm}^{-1}$$

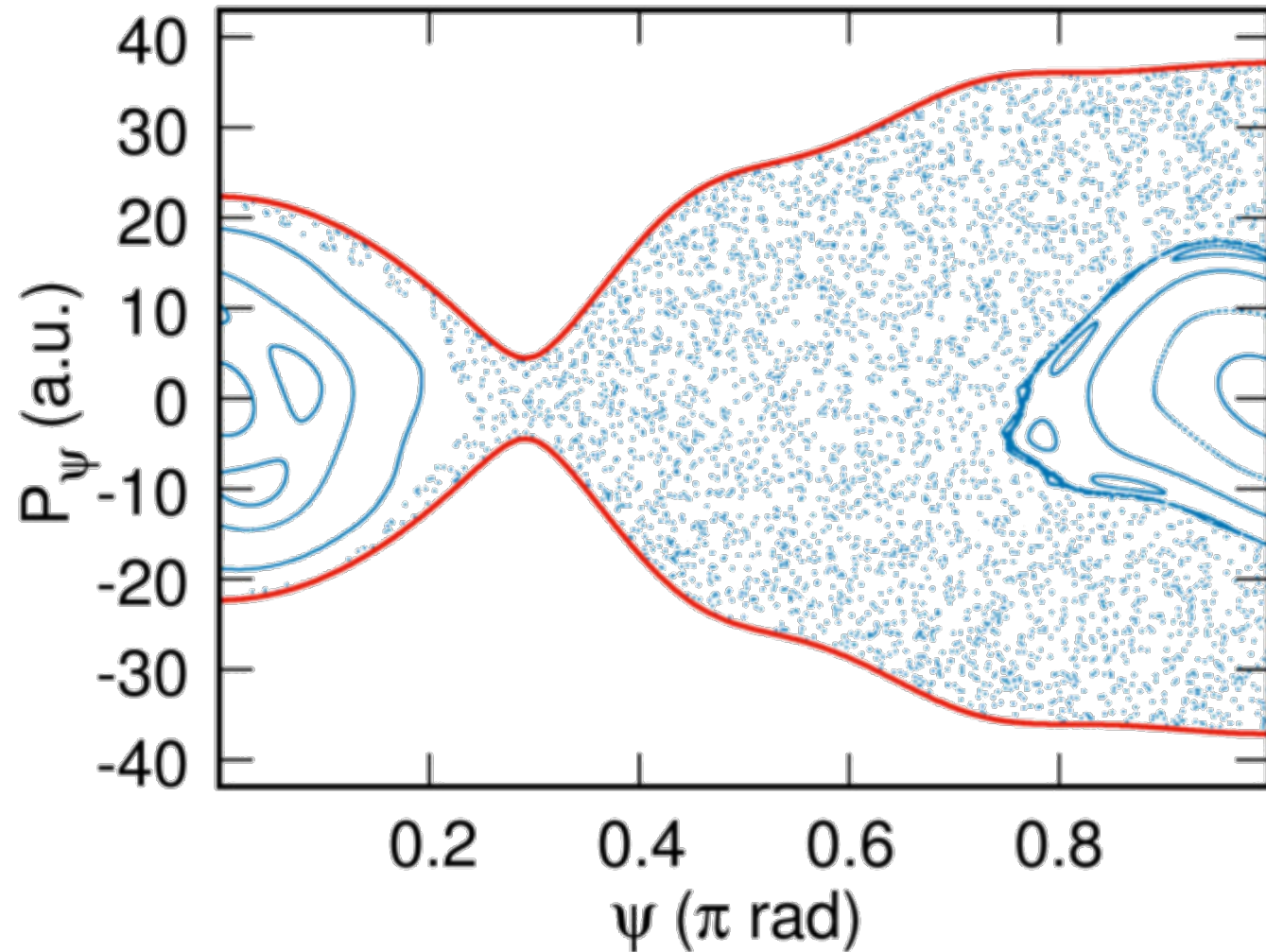
SSP



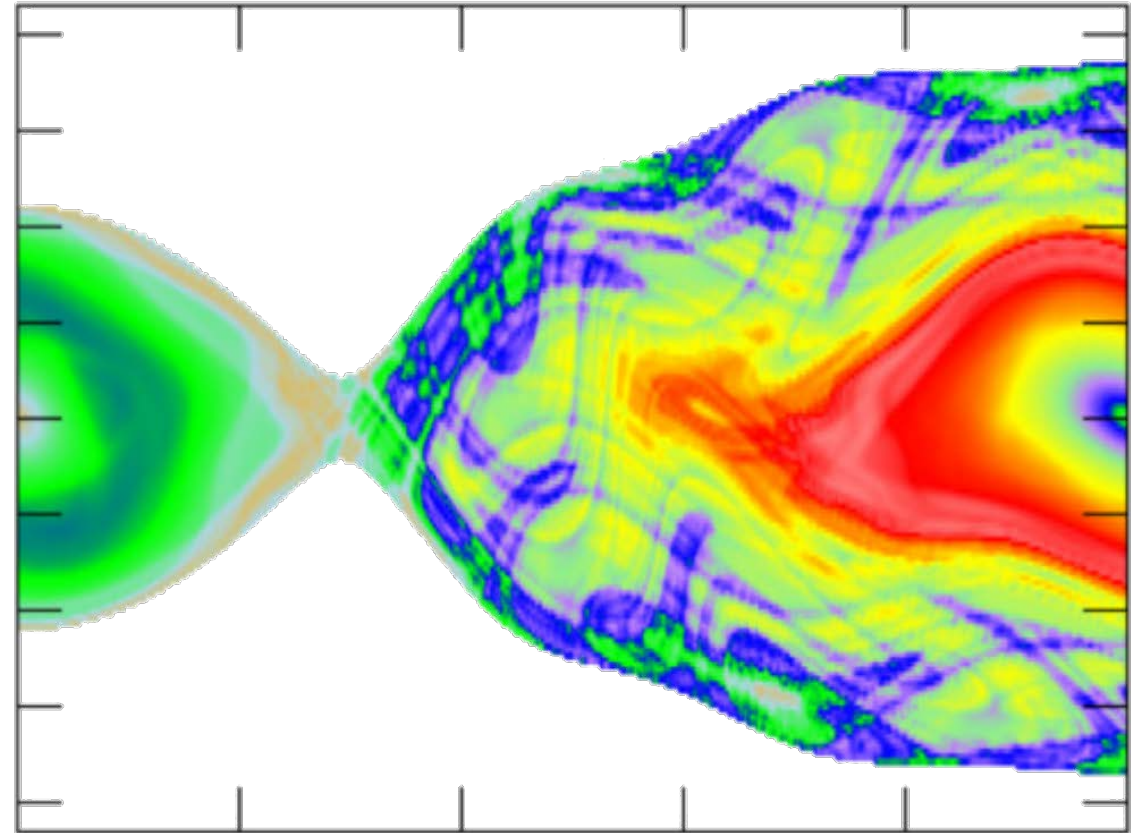


$$E = 3500 \text{ cm}^{-1}$$

SSP



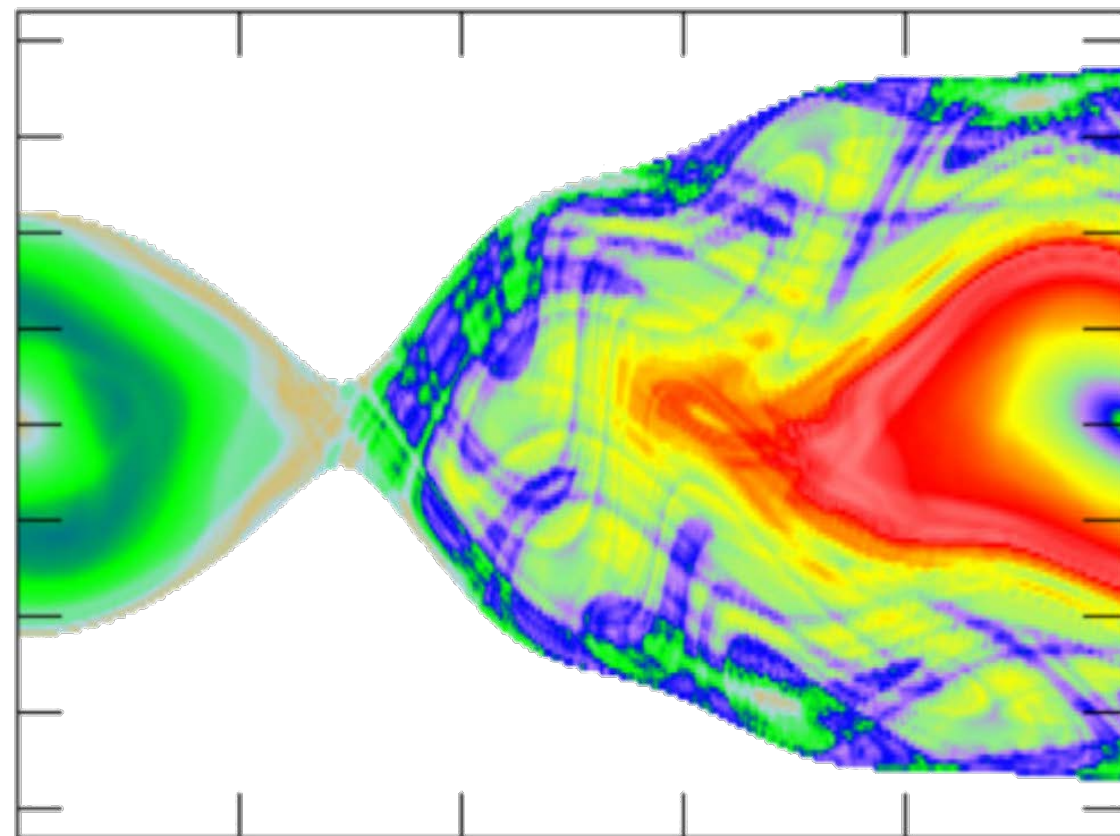
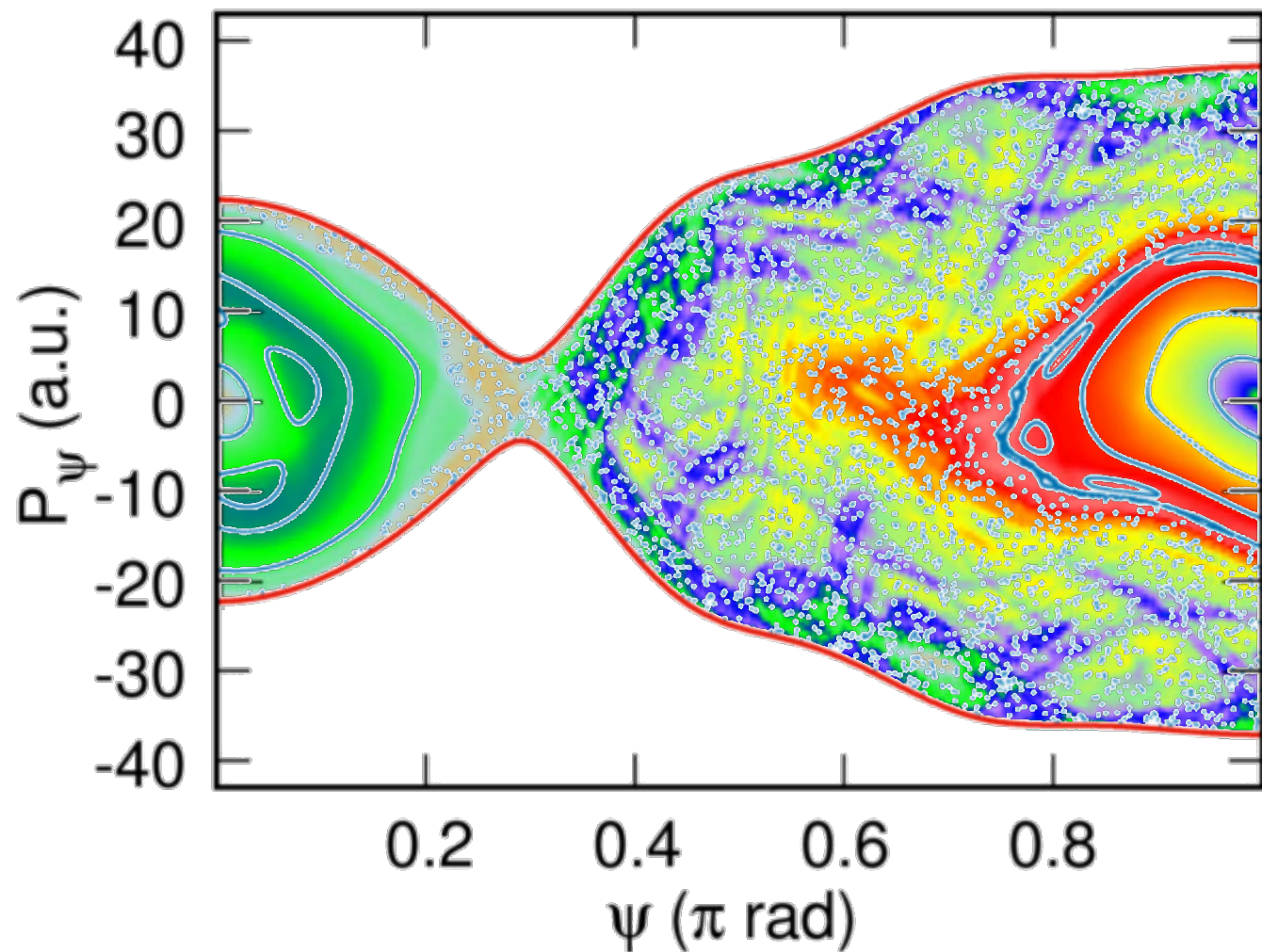
Lagrangian Descr.



$$E = 3500 \text{ cm}^{-1}$$

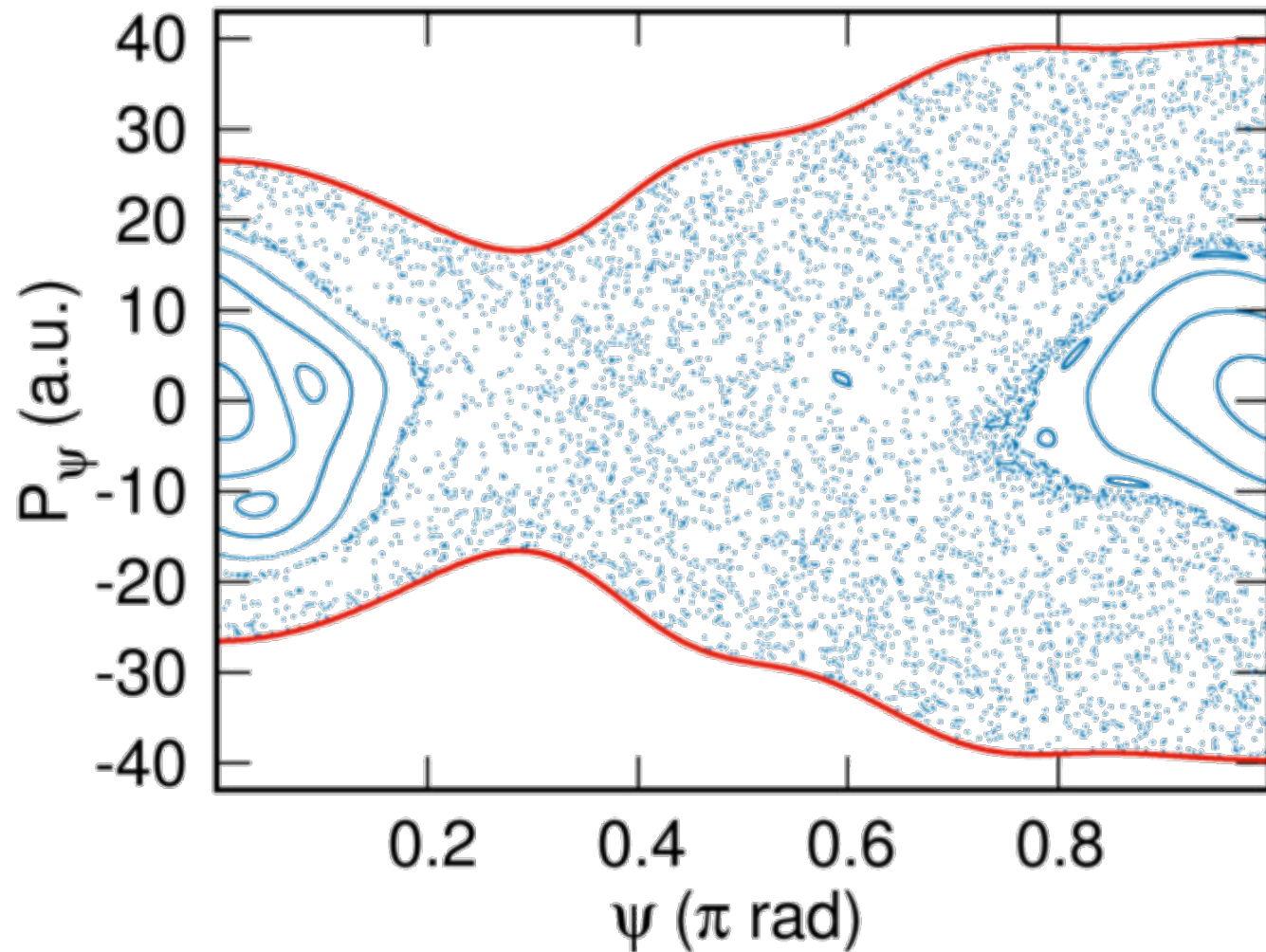
SSP

Lagrangian Descr.

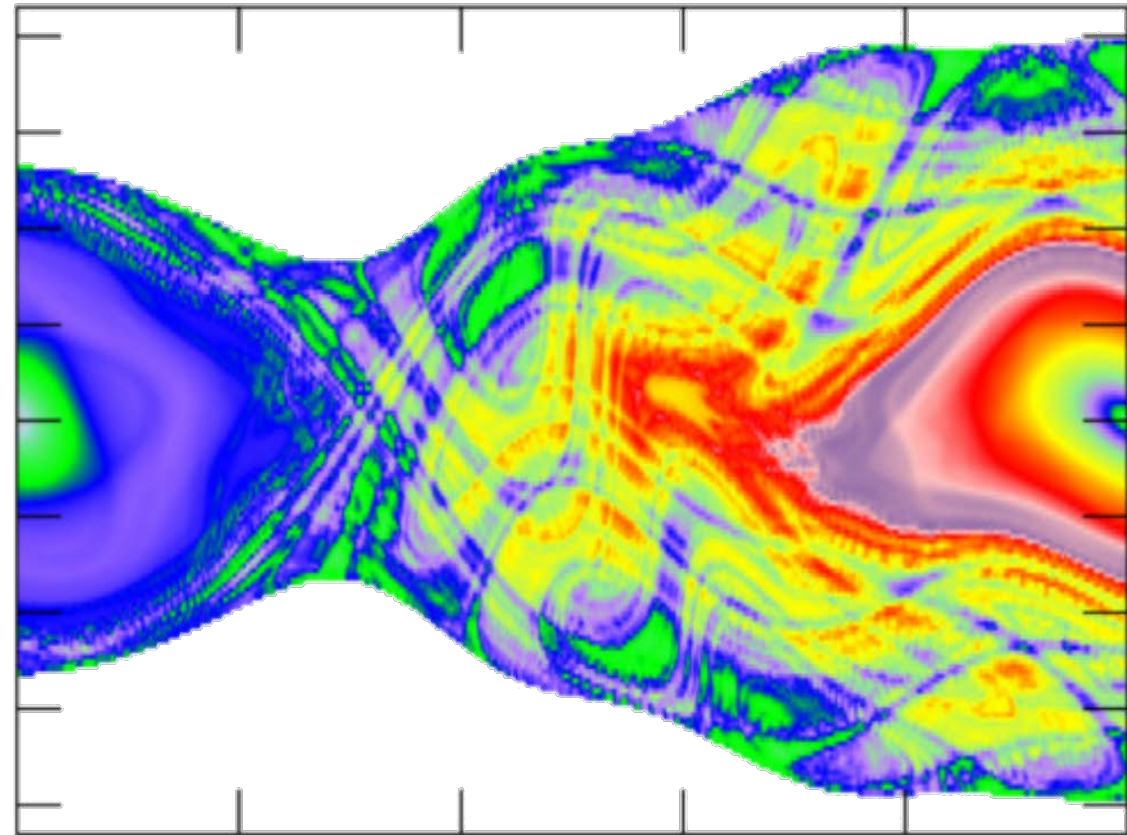


$$E = 4000 \text{ cm}^{-1}$$

SSP



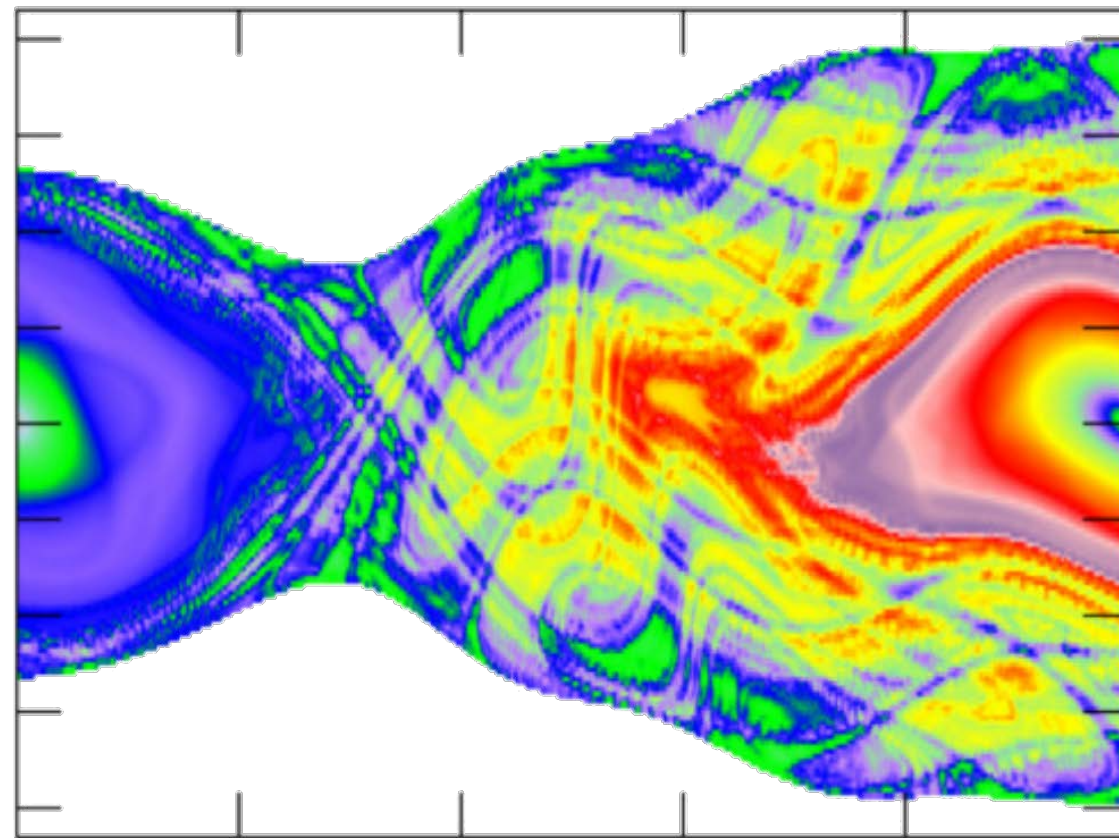
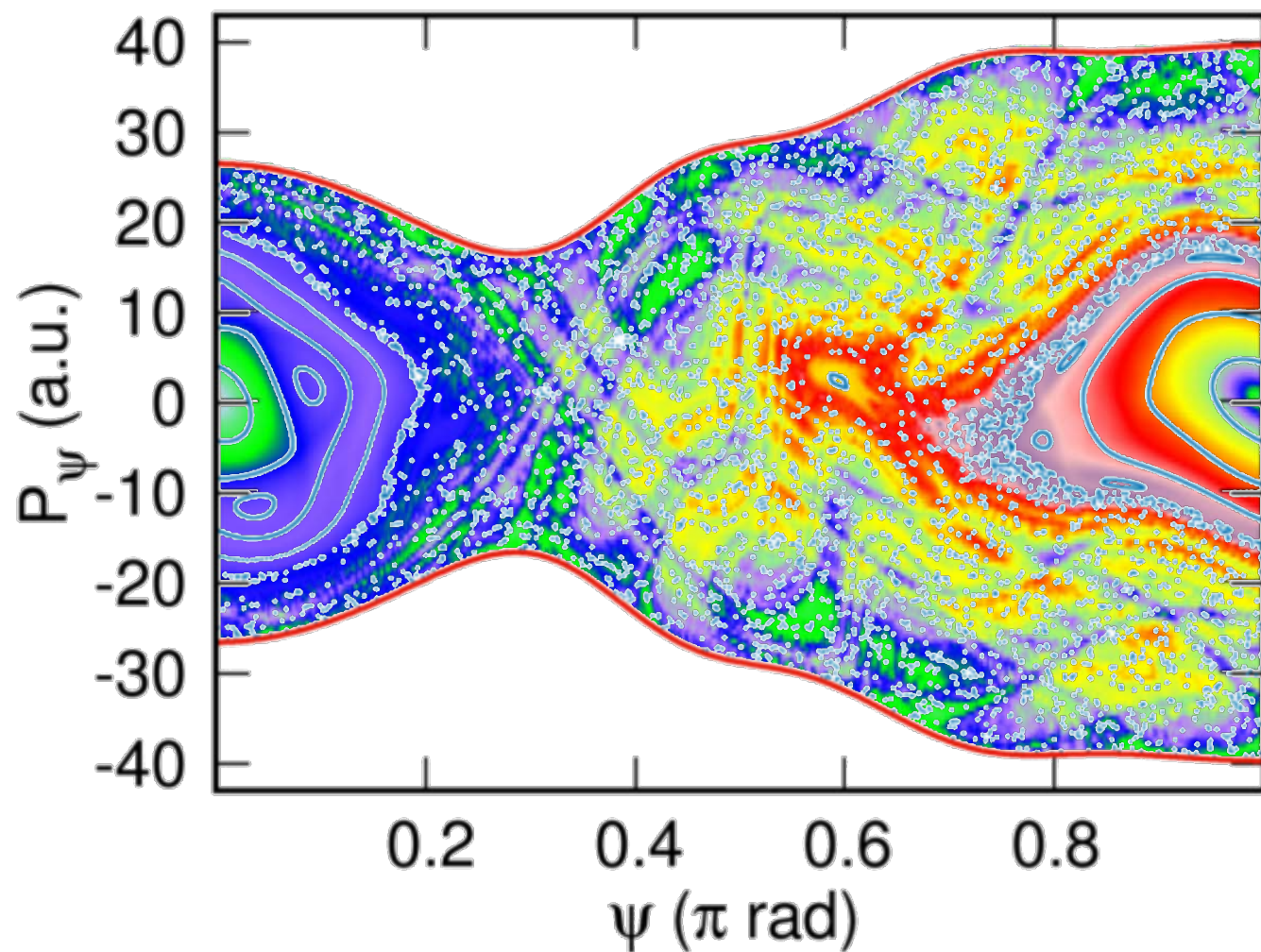
Lagrangian Descr.



$$E = 4000 \text{ cm}^{-1}$$

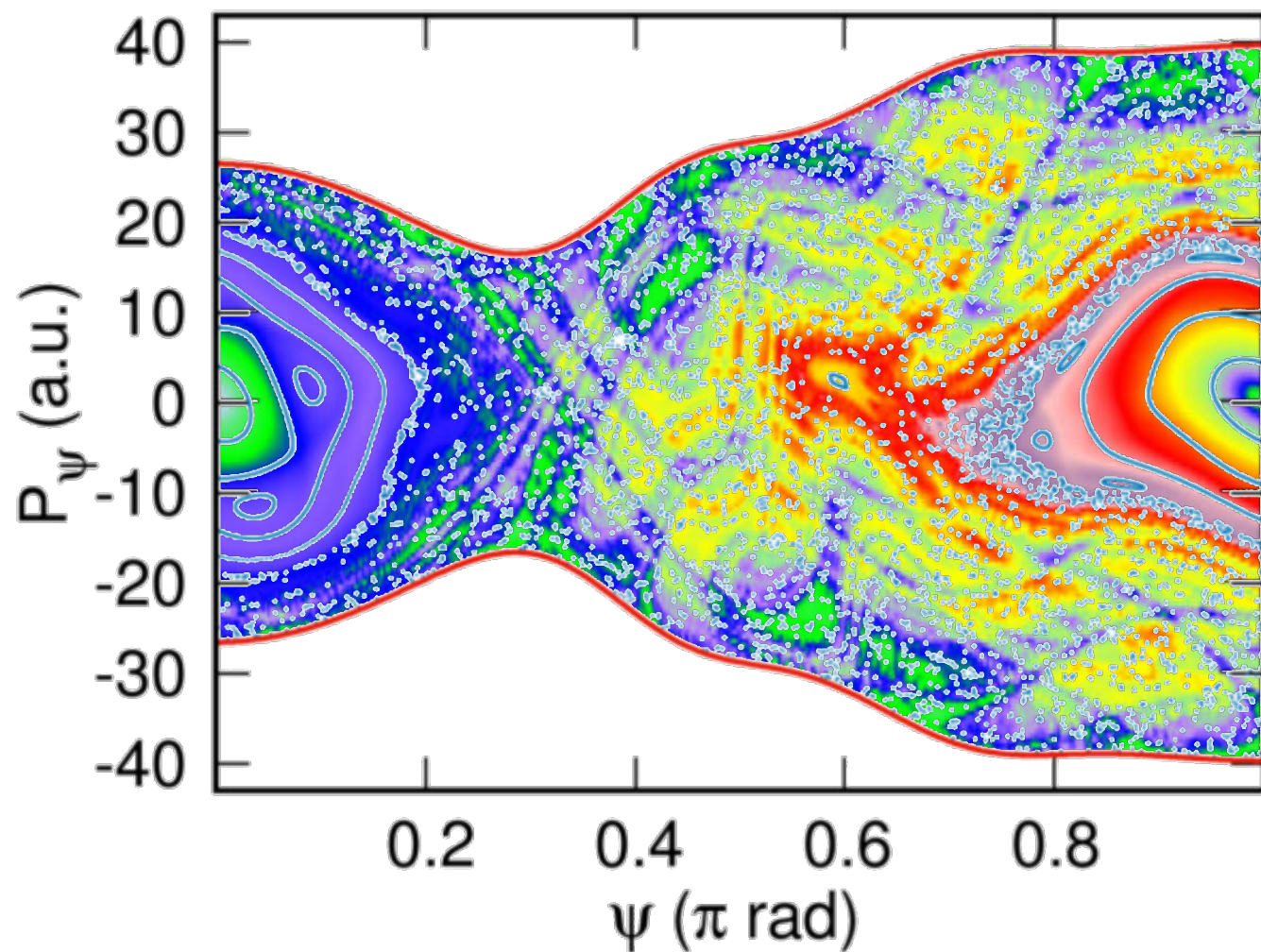
SSP

Lagrangian Descr.

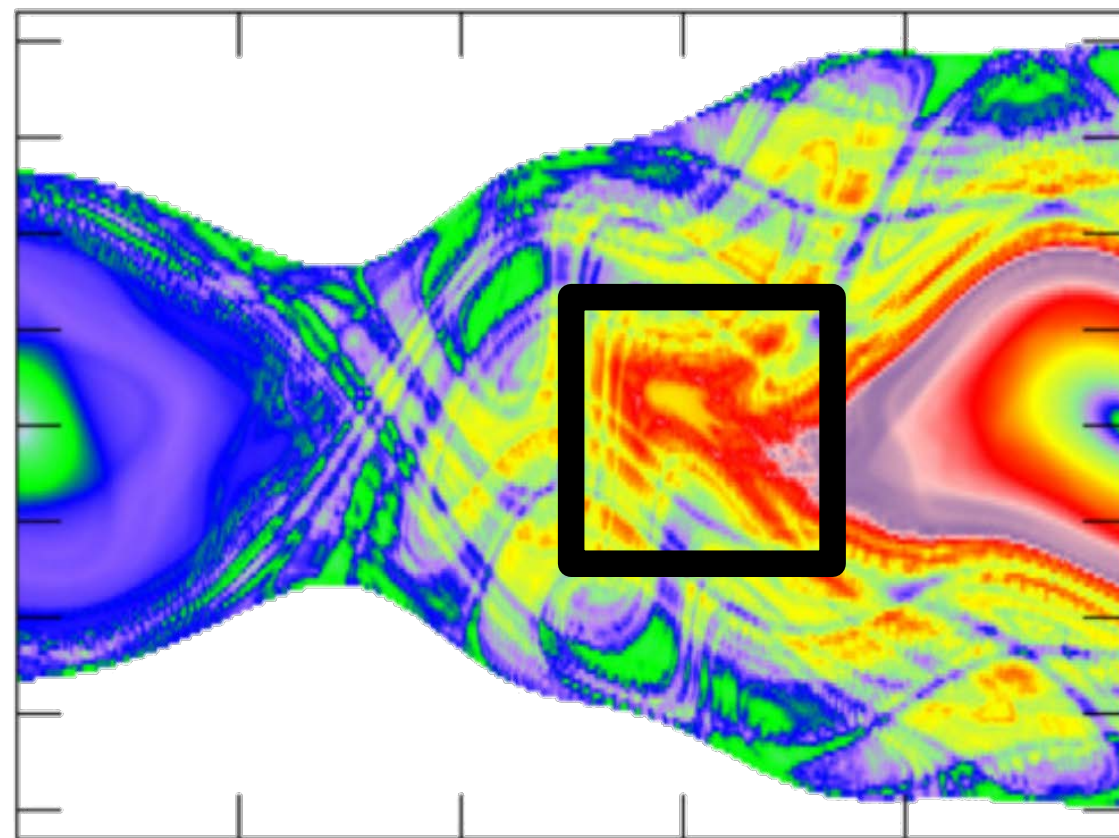


$$E = 4000 \text{ cm}^{-1}$$

SSP

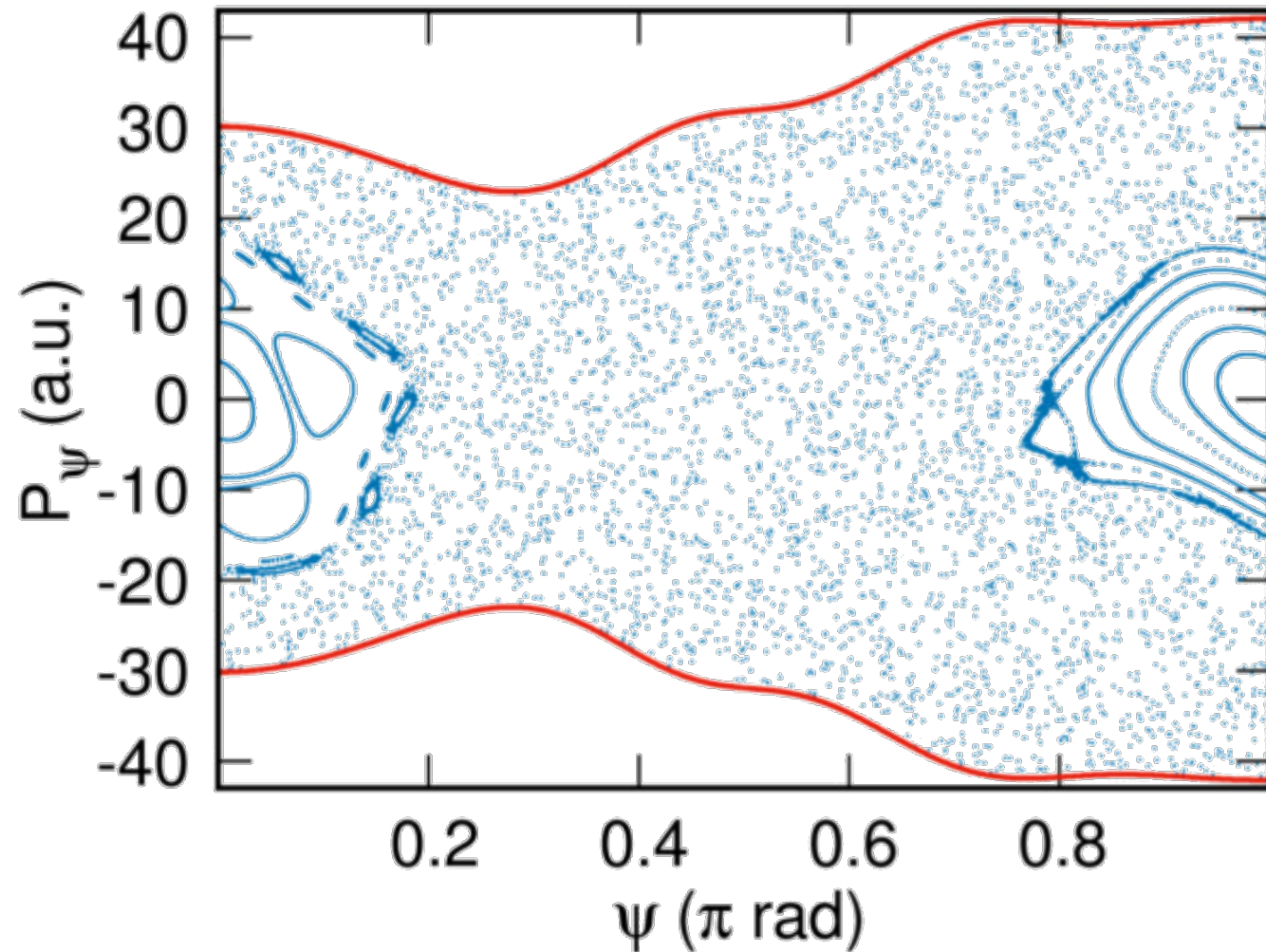


Lagrangian Descr.

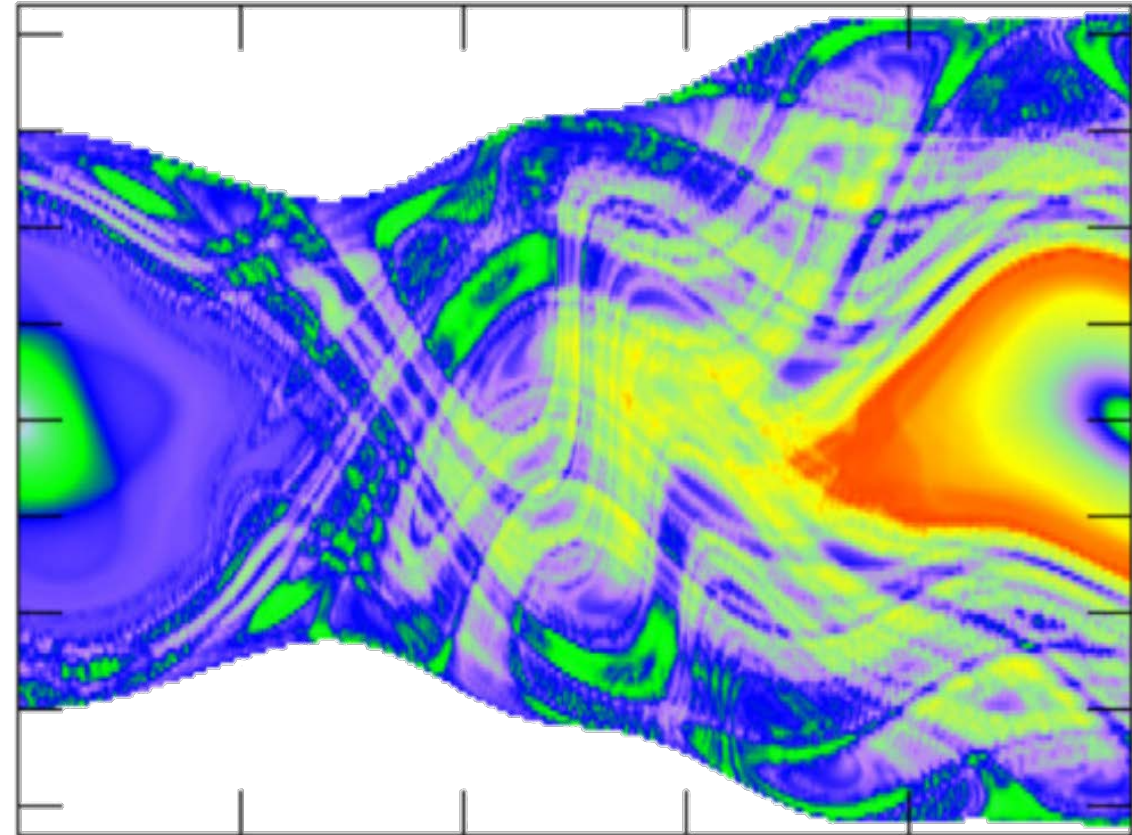


$$E = 4500 \text{ cm}^{-1}$$

SSP



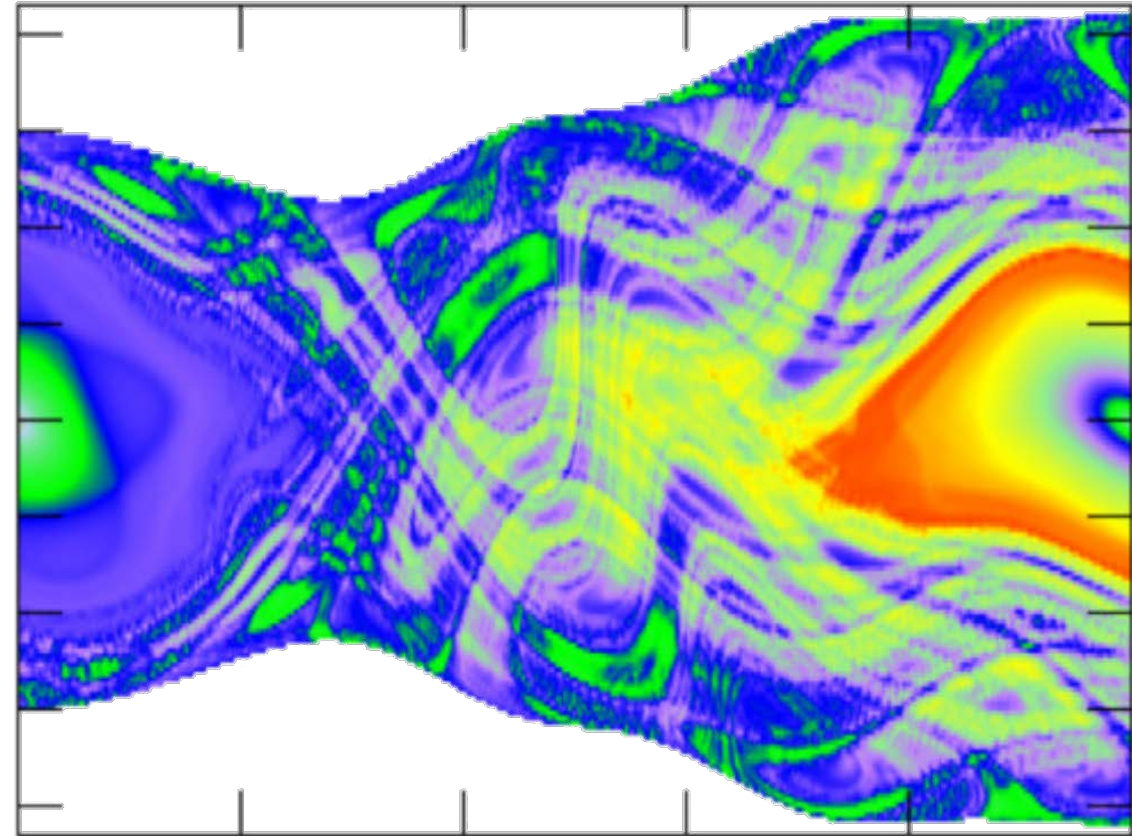
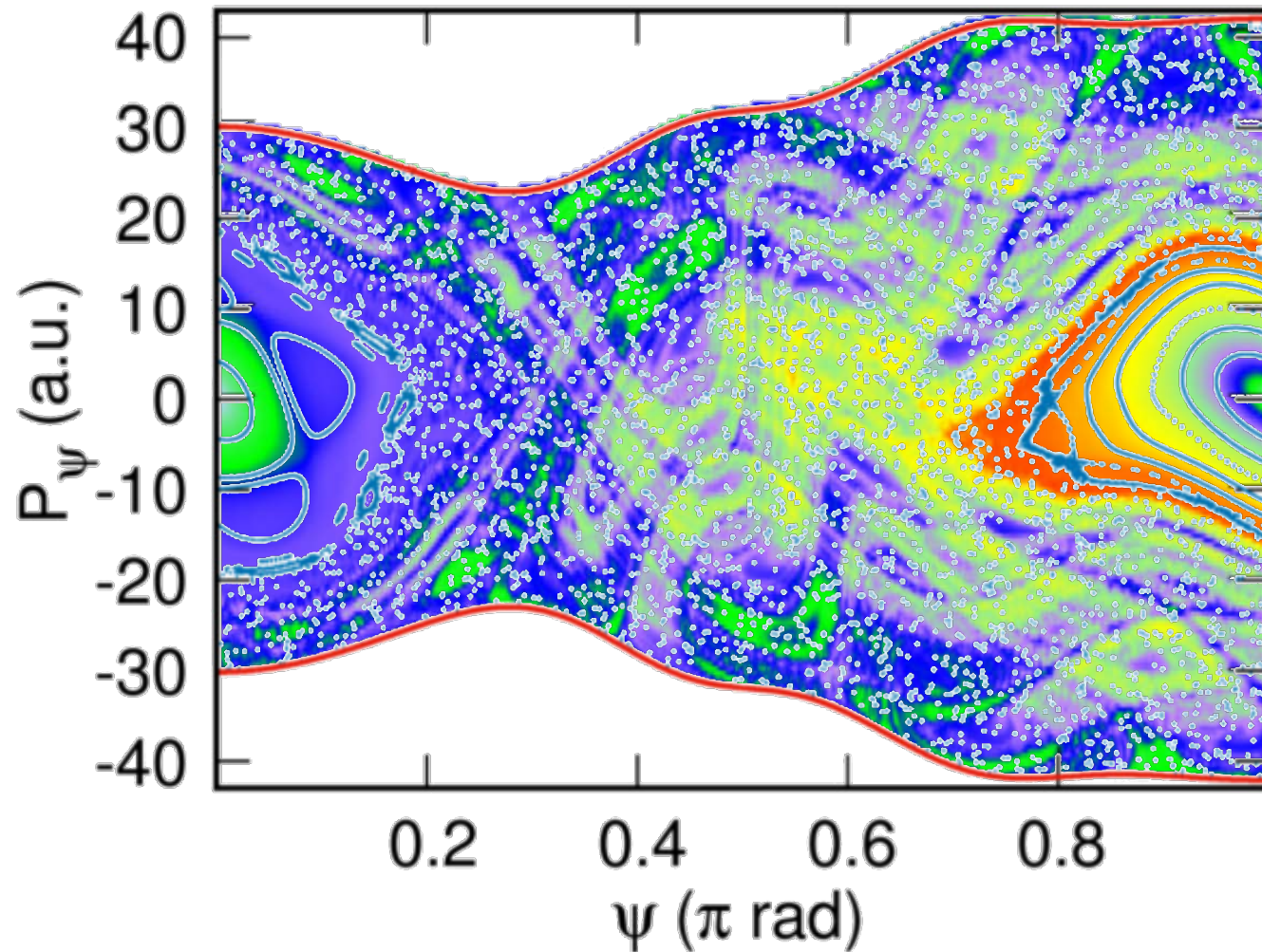
Lagrangian Descr.



$$E = 4500 \text{ cm}^{-1}$$

SSP

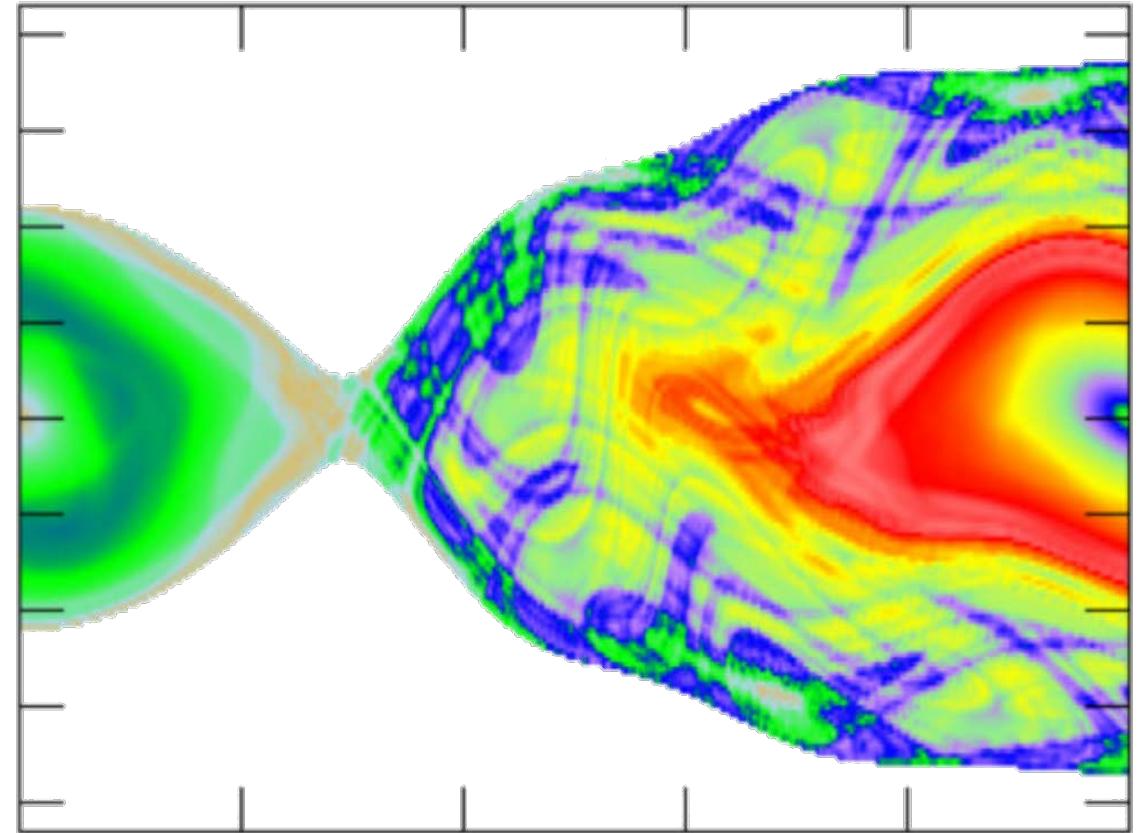
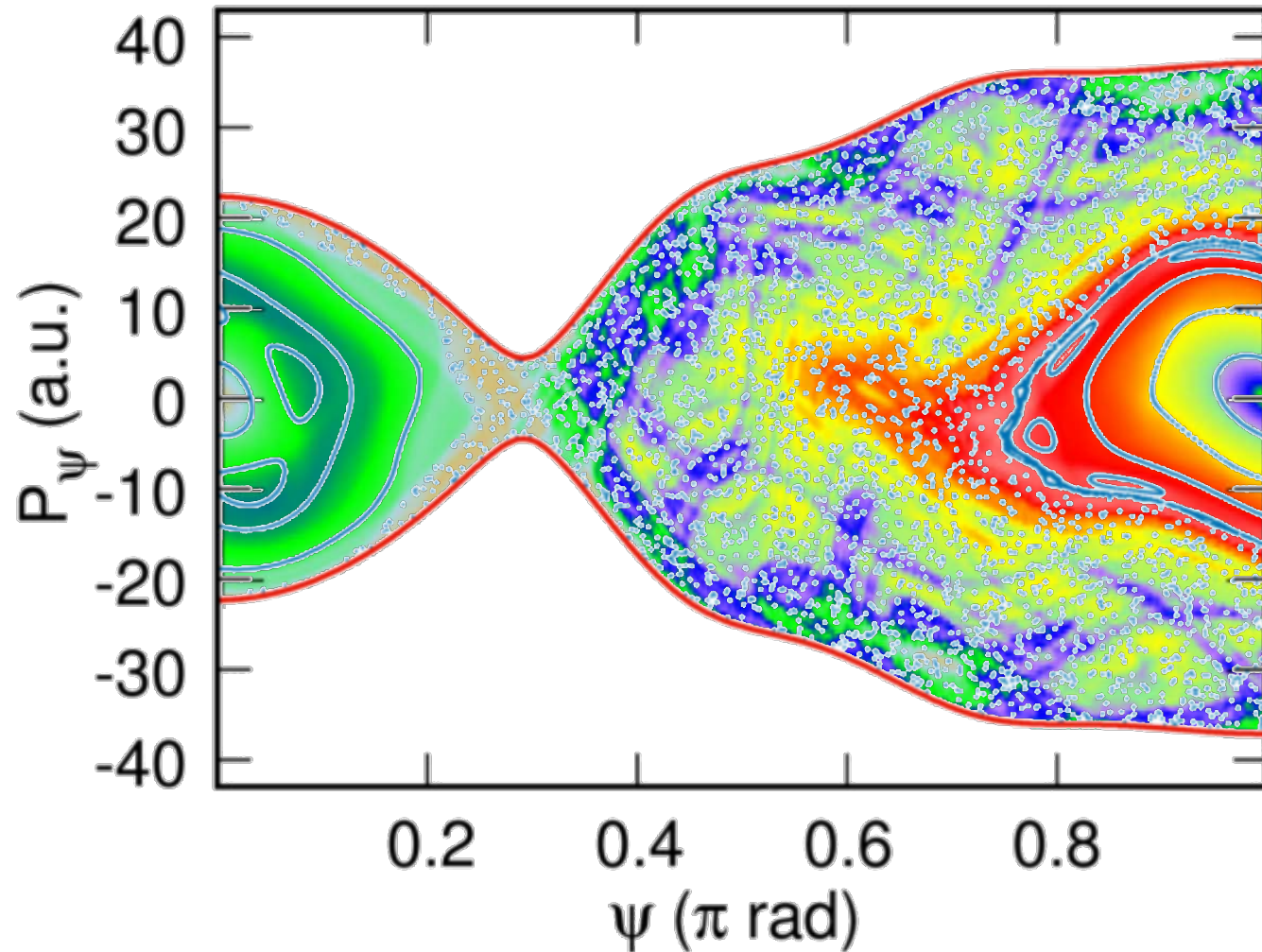
Lagrangian Descr.



$$E = 3500 \text{ cm}^{-1}$$

SSP

Lagrangian Descr.

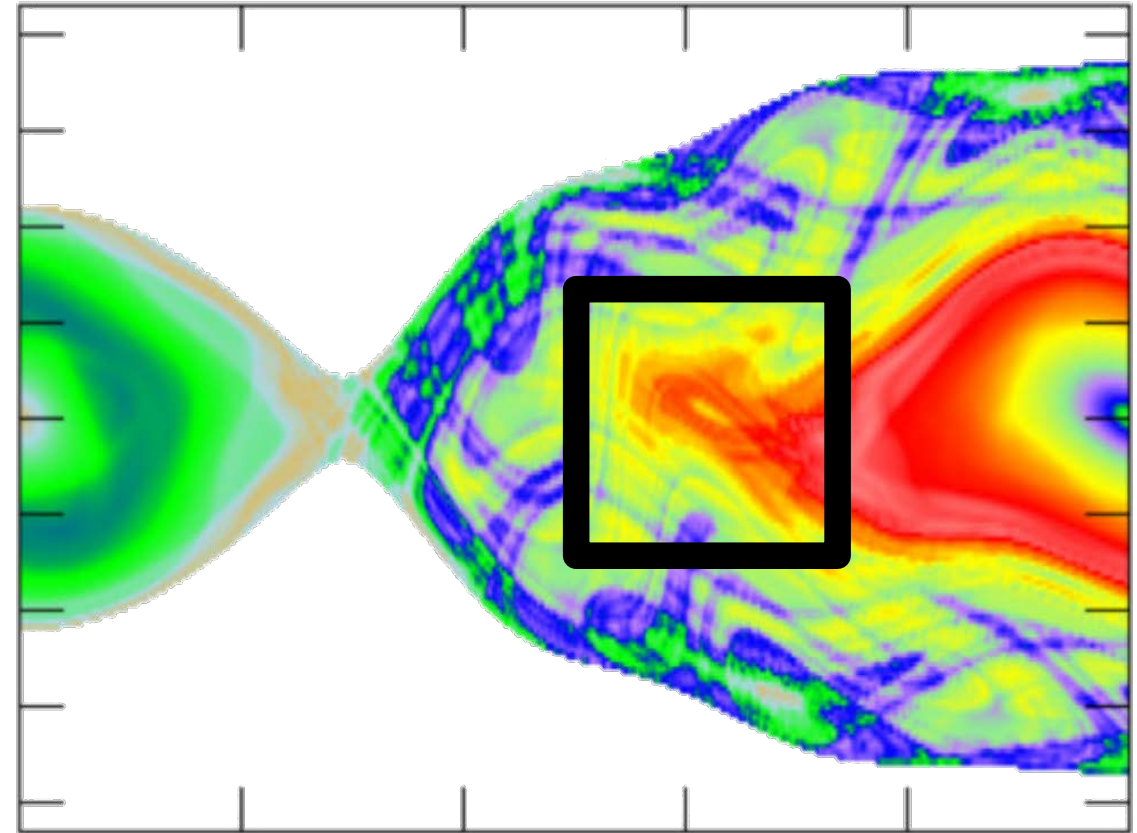
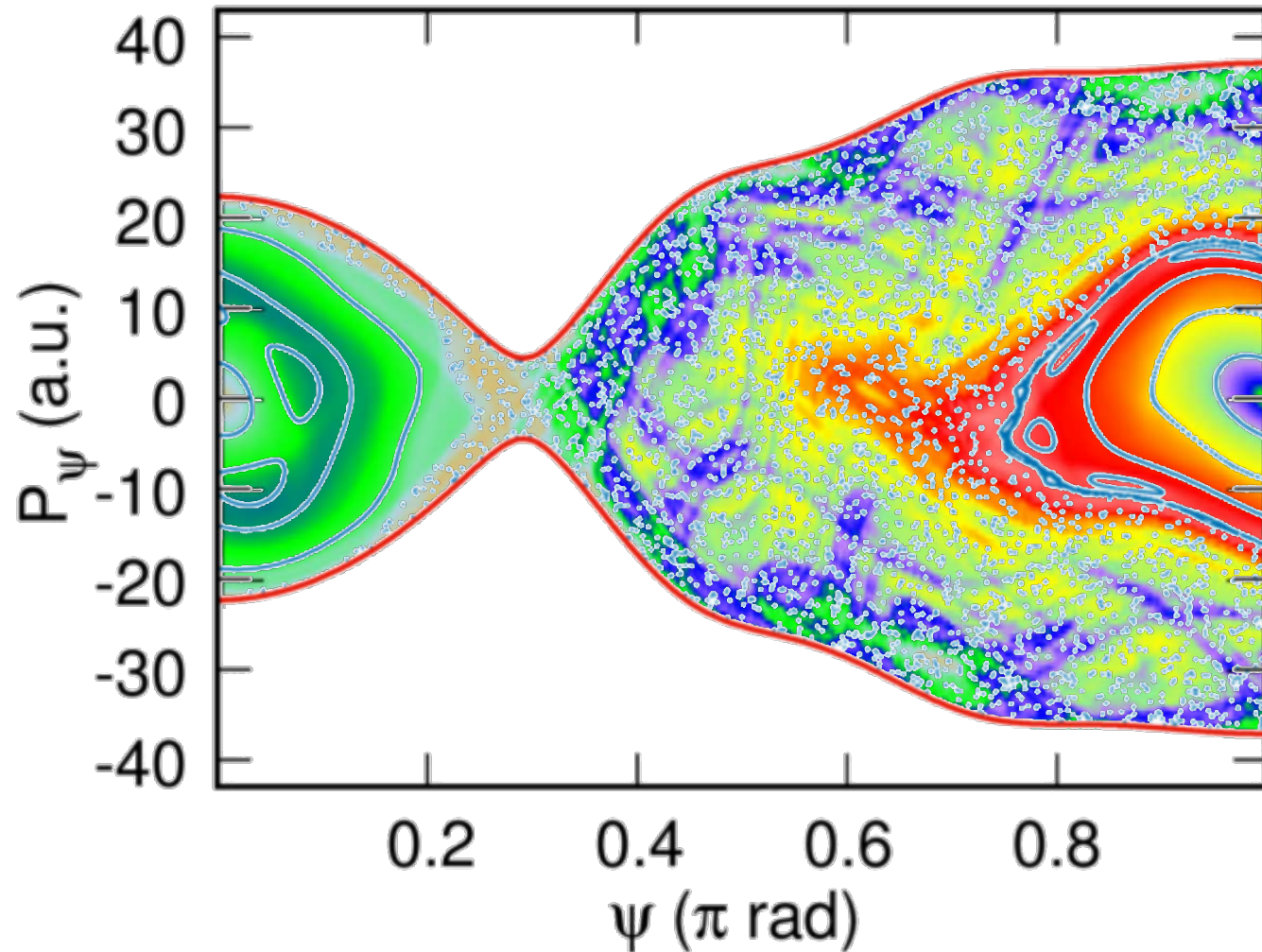




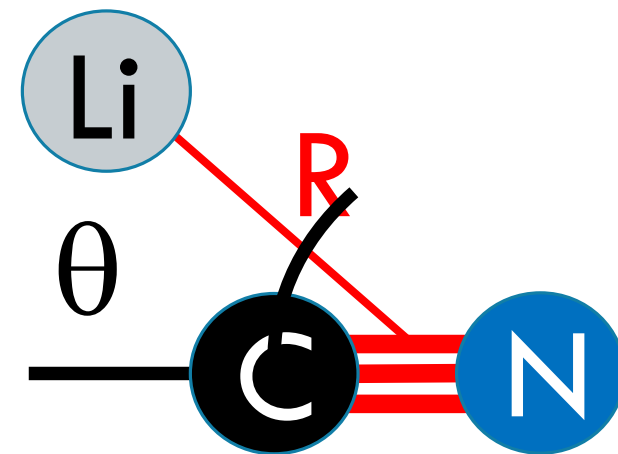
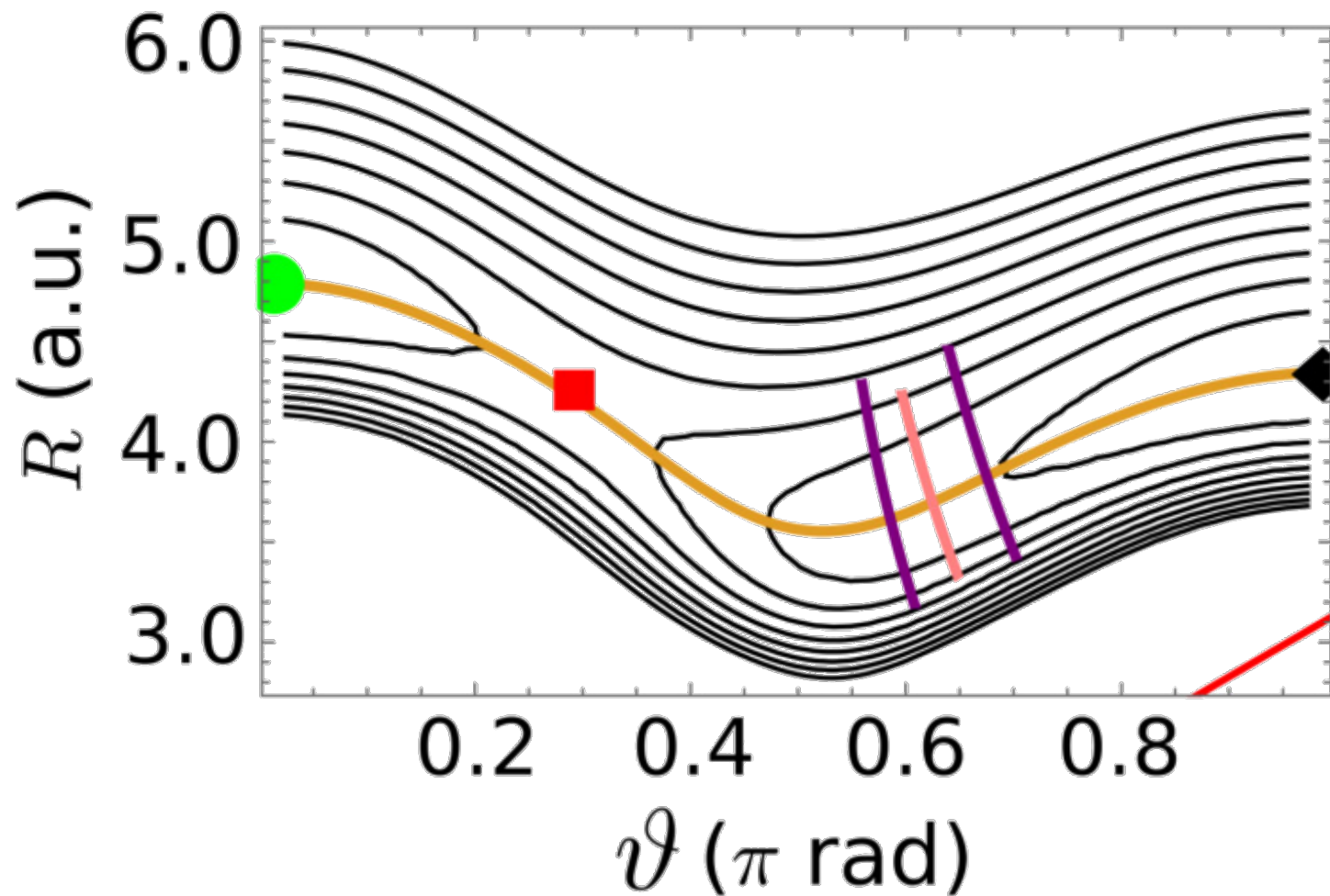
$$E = 3500 \text{ cm}^{-1}$$

SSP

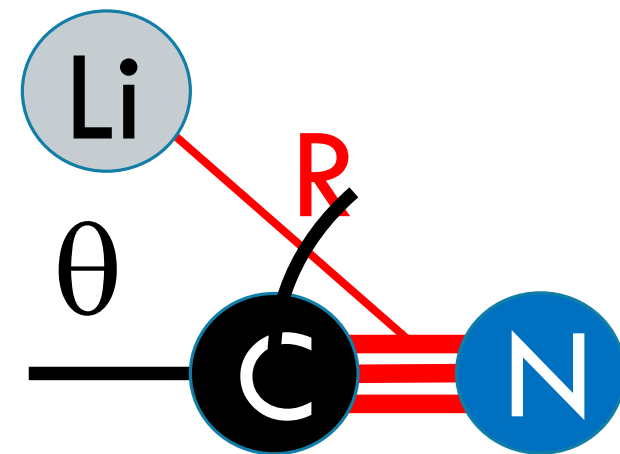
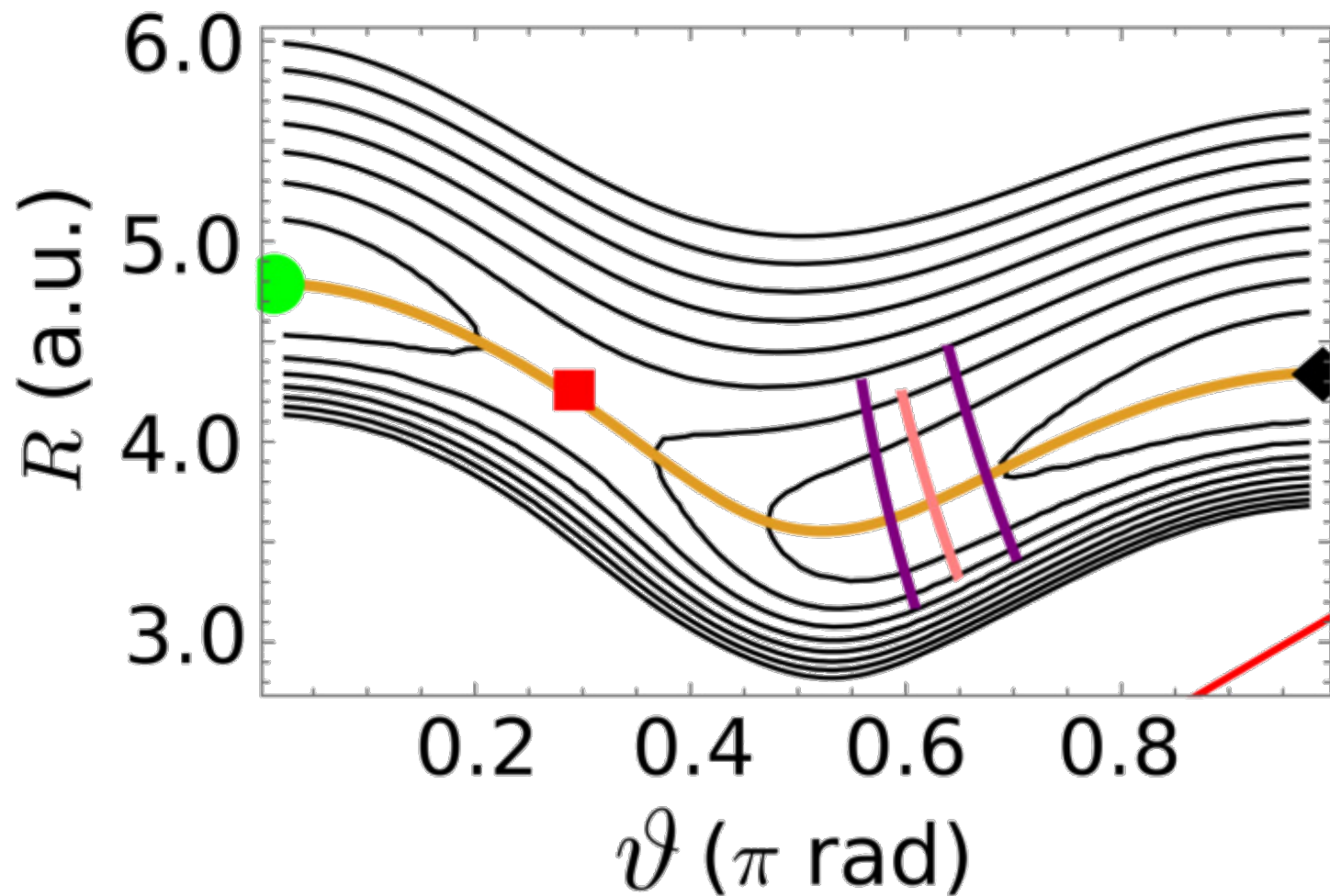
Lagrangian Descr.



# POTENTIAL ENERGY SURFACE

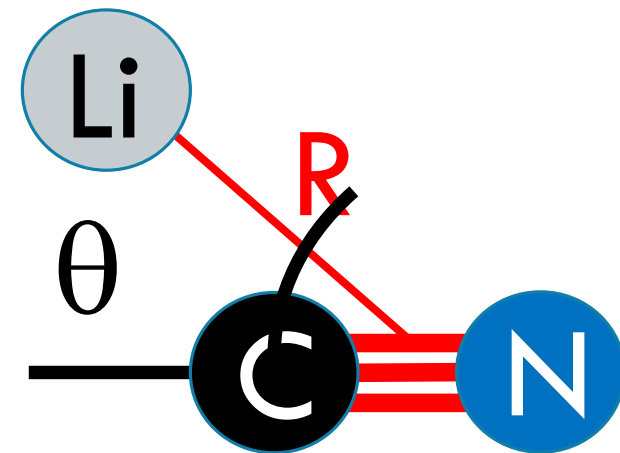
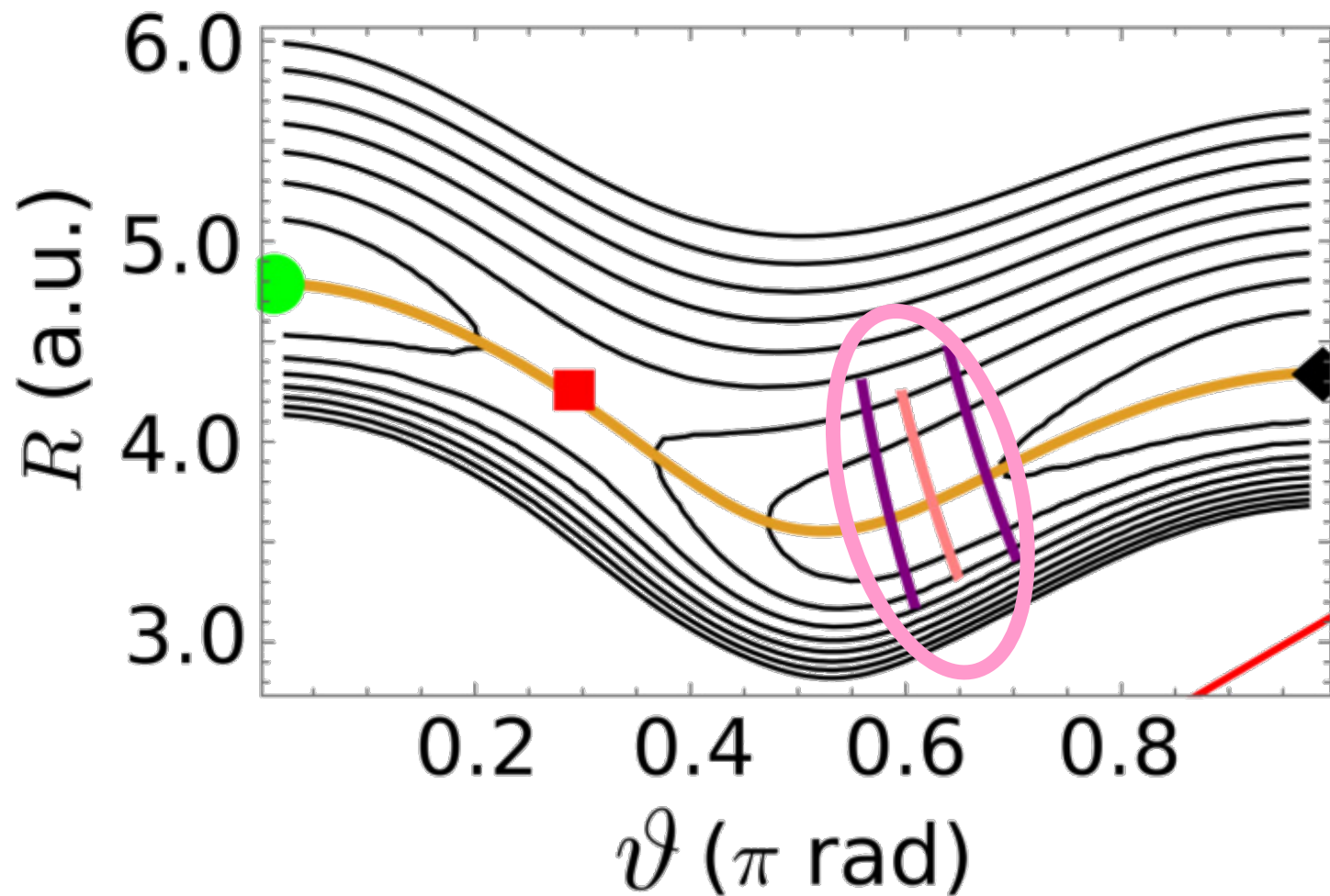


# POTENTIAL ENERGY SURFACE



**Periodic orbits**

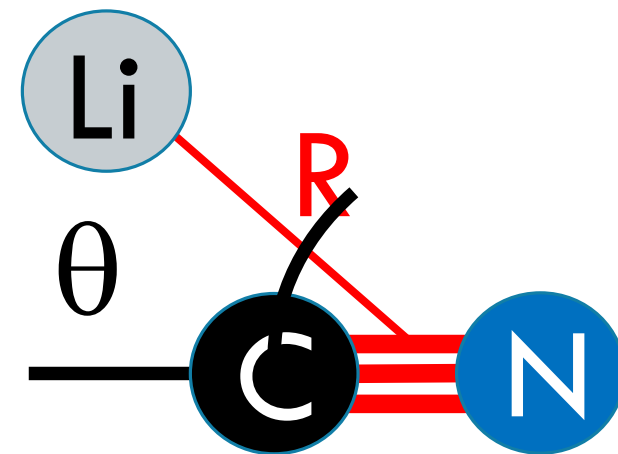
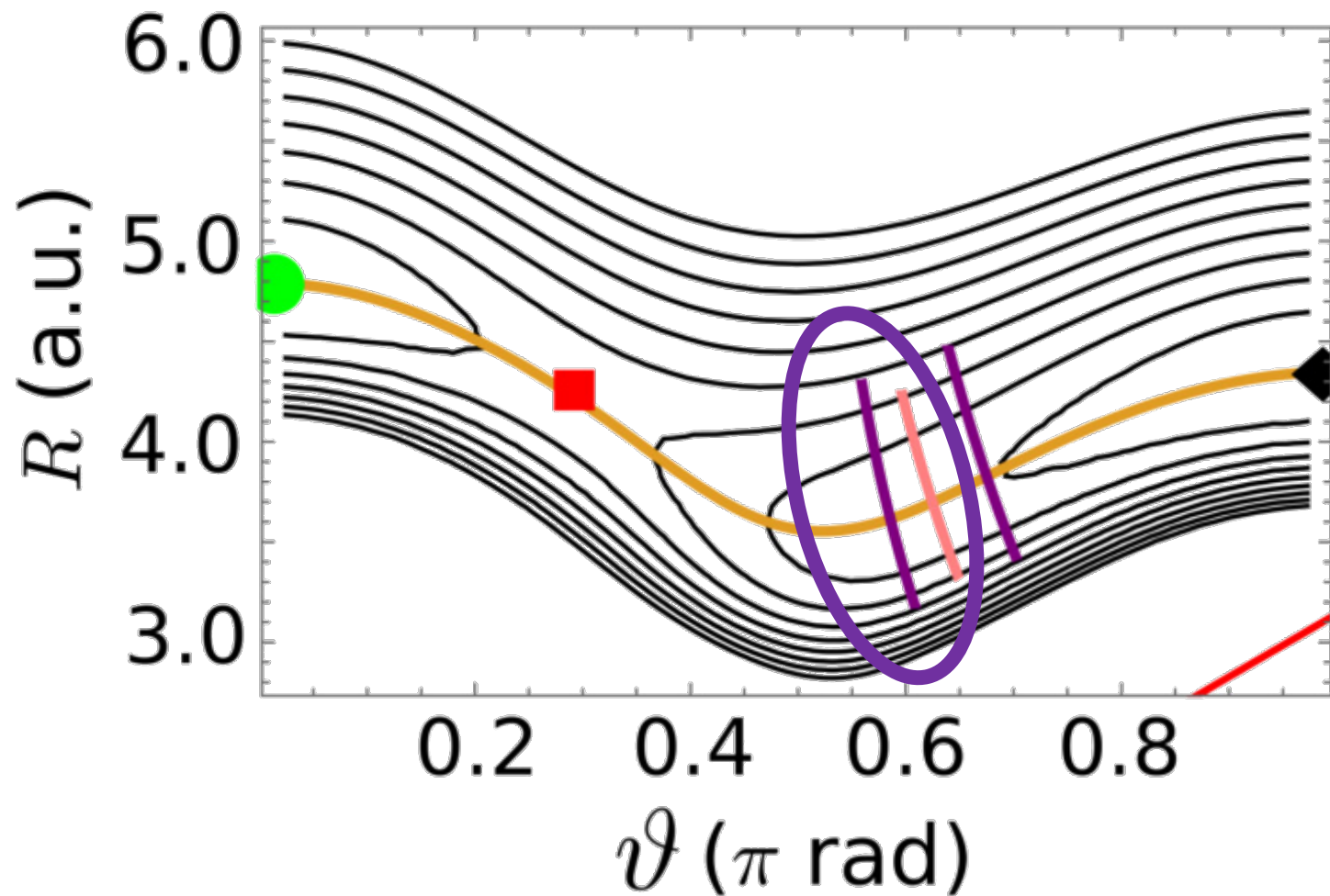
# POTENTIAL ENERGY SURFACE



**Periodic orbits**

Center: marginally stable

# POTENTIAL ENERGY SURFACE

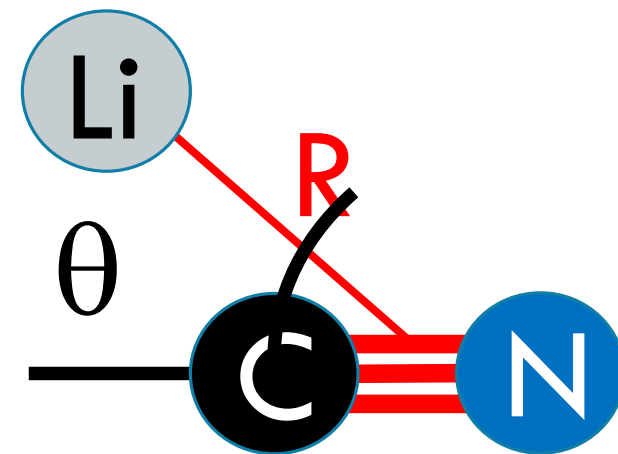
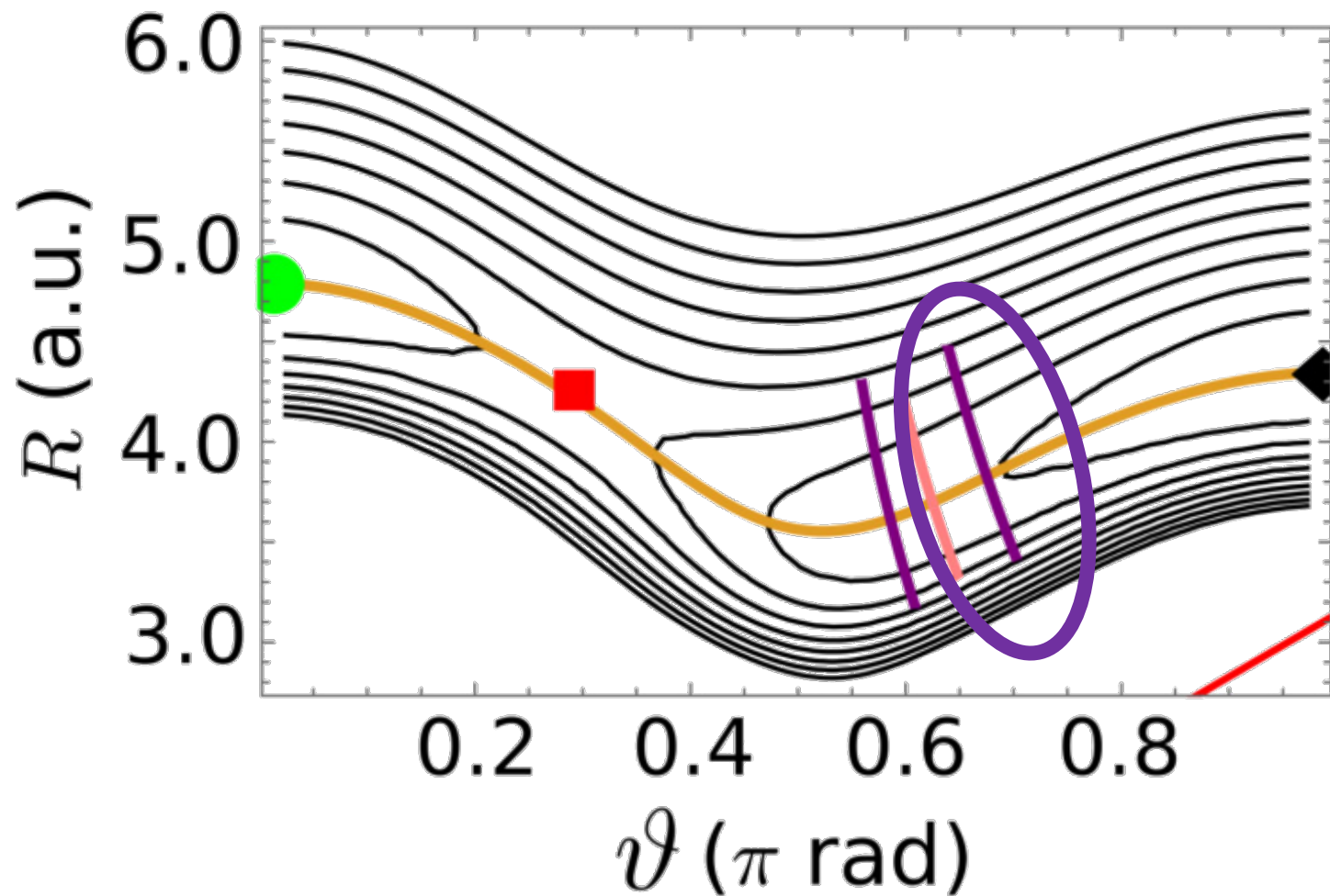


## Periodic orbits

Center: marginally stable

Left: Stable

# POTENTIAL ENERGY SURFACE

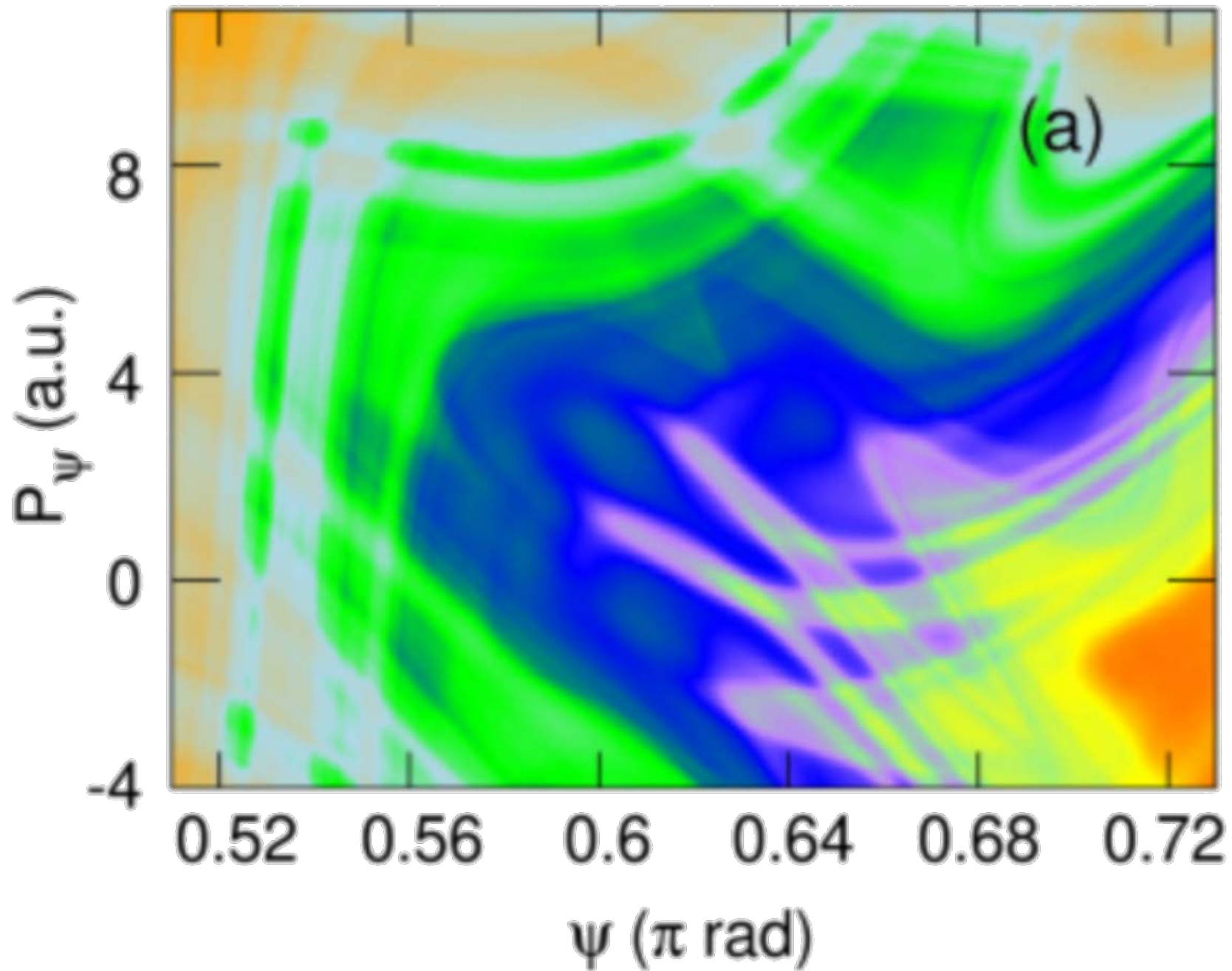


## Periodic orbits

Center: marginally stable

Left: Stable

Right: Unstable

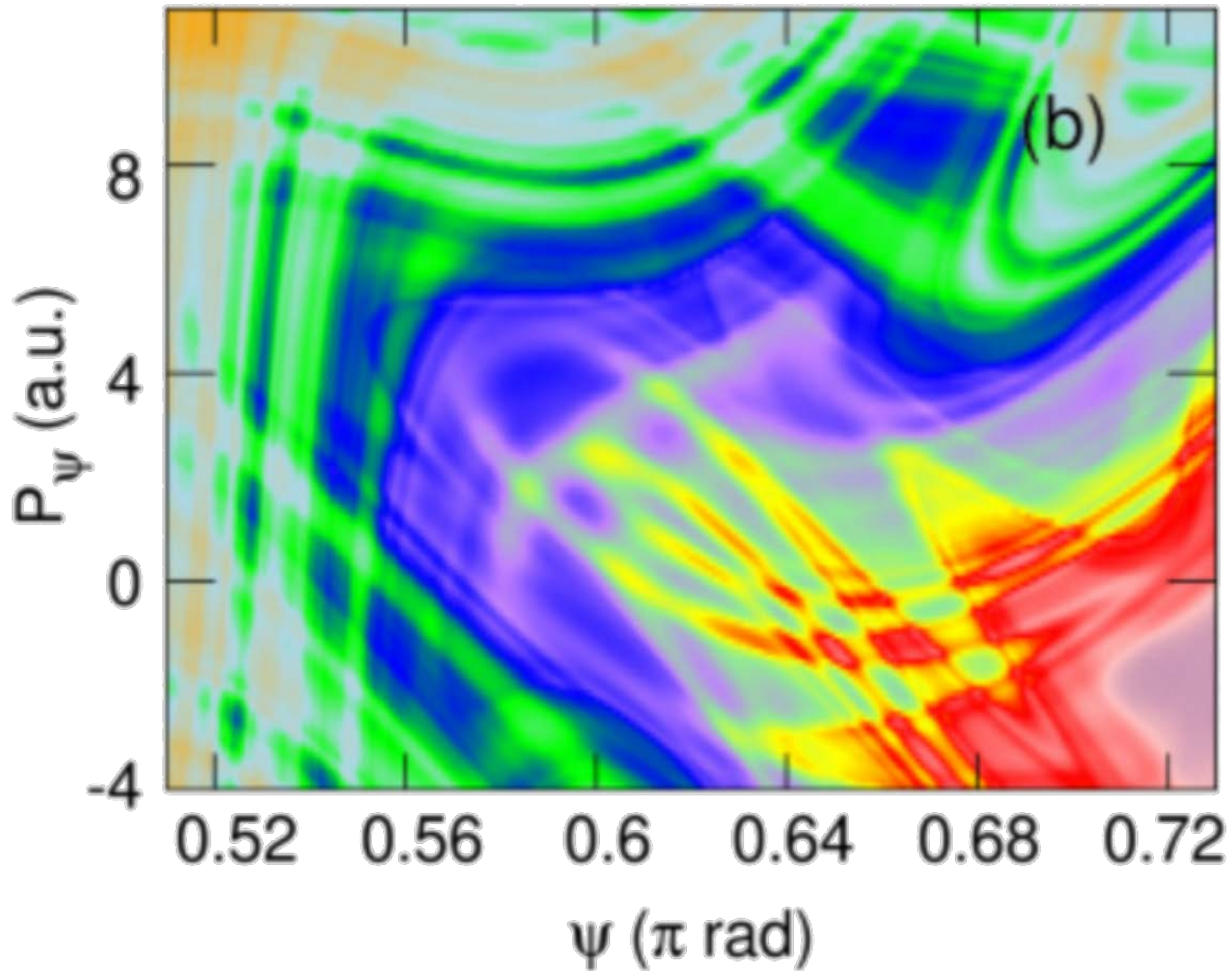


## SADDLE-NODE BIFURCATION

$$E = 3000 \text{ cm}^{-1}$$

$$p = 0.4$$

$$\tau = 2 \cdot 10^4$$



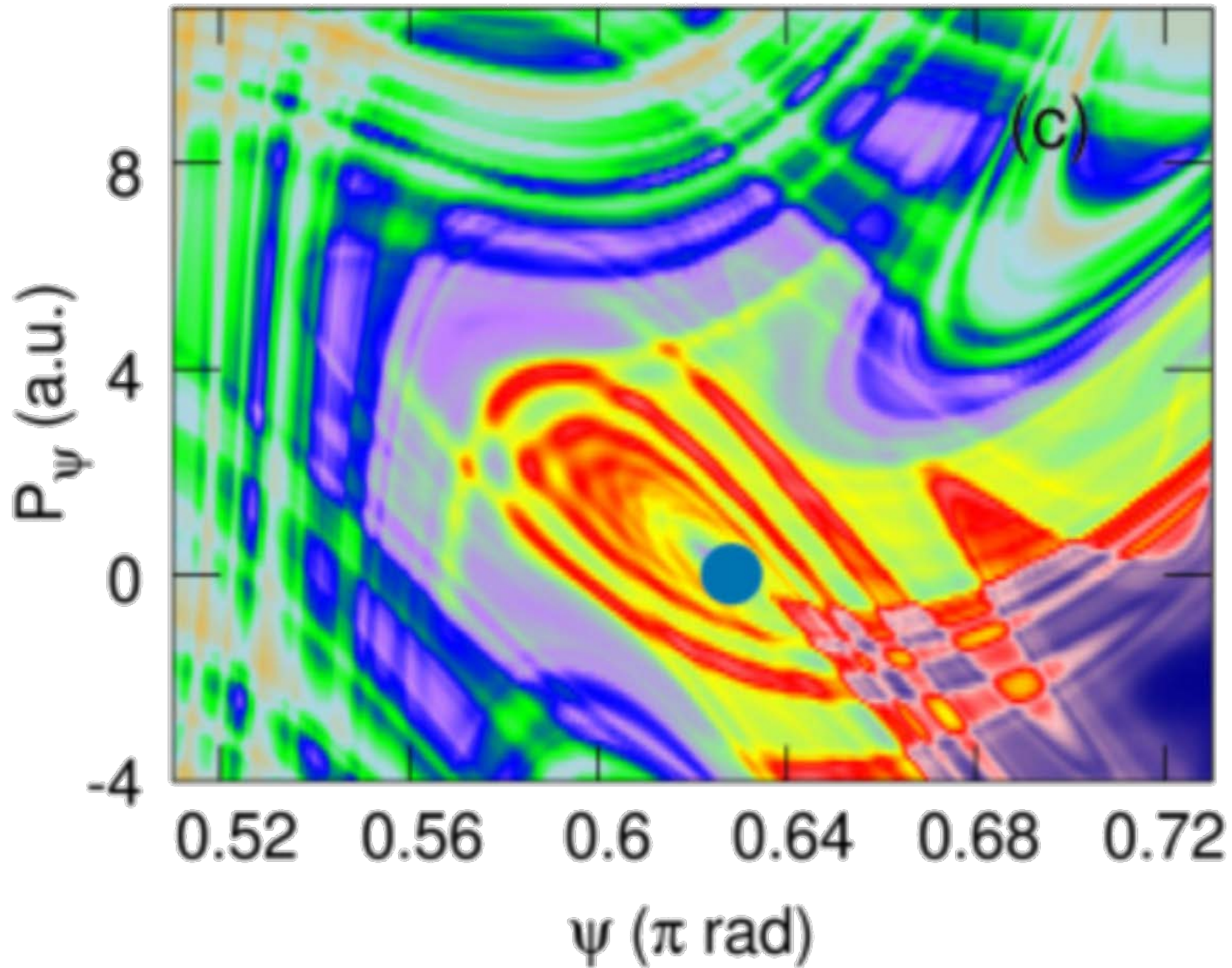
## SADDLE-NODE BIFURCATION

$$E = 3200 \text{ cm}^{-1}$$

$$p = 0.4$$

$$\tau = 2 \cdot 10^4$$



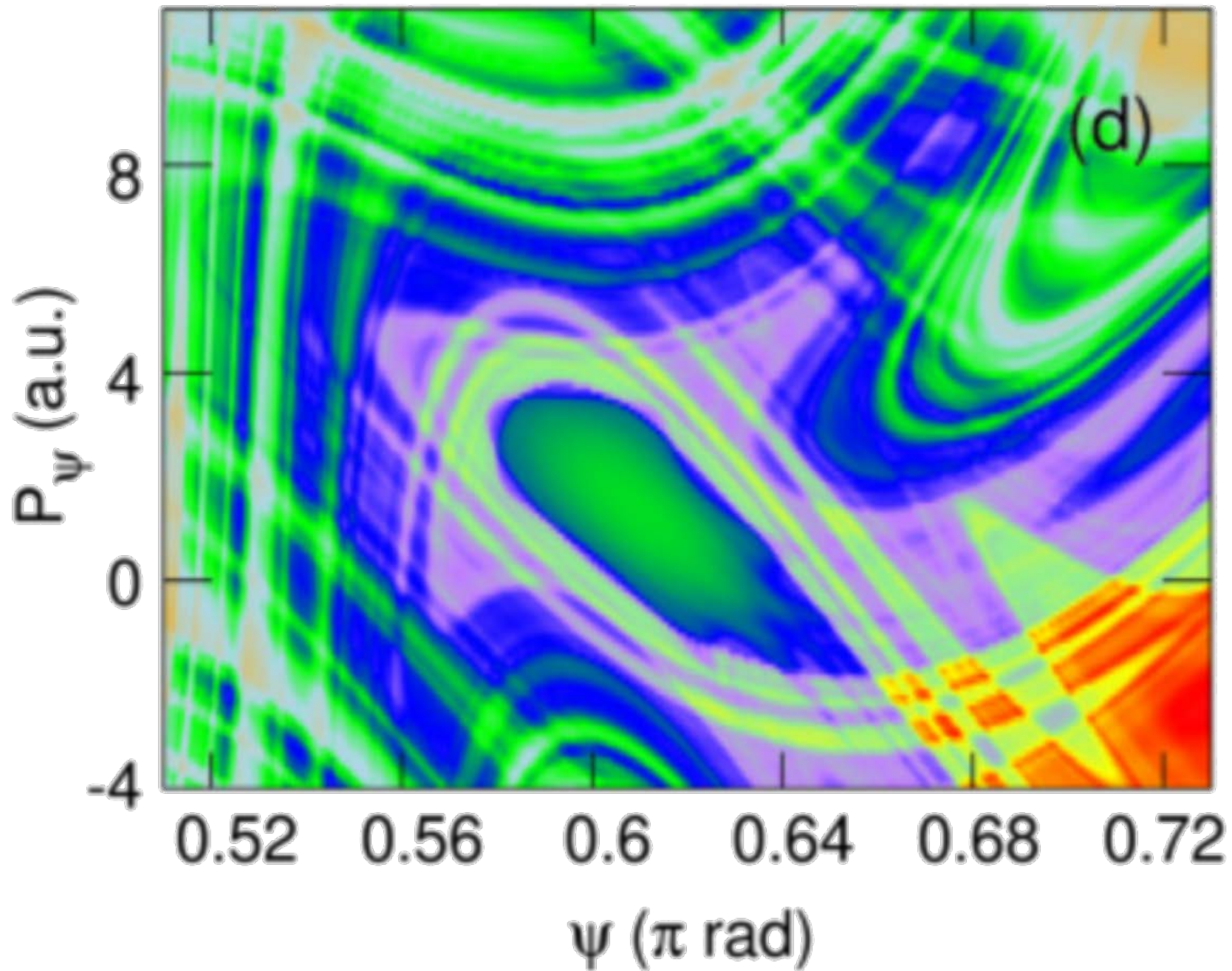


## SADDLE-NODE BIFURCATION

$$E \simeq 3441 \text{ cm}^{-1}$$

$$p = 0.4$$

$$\tau = 2 \cdot 10^4$$

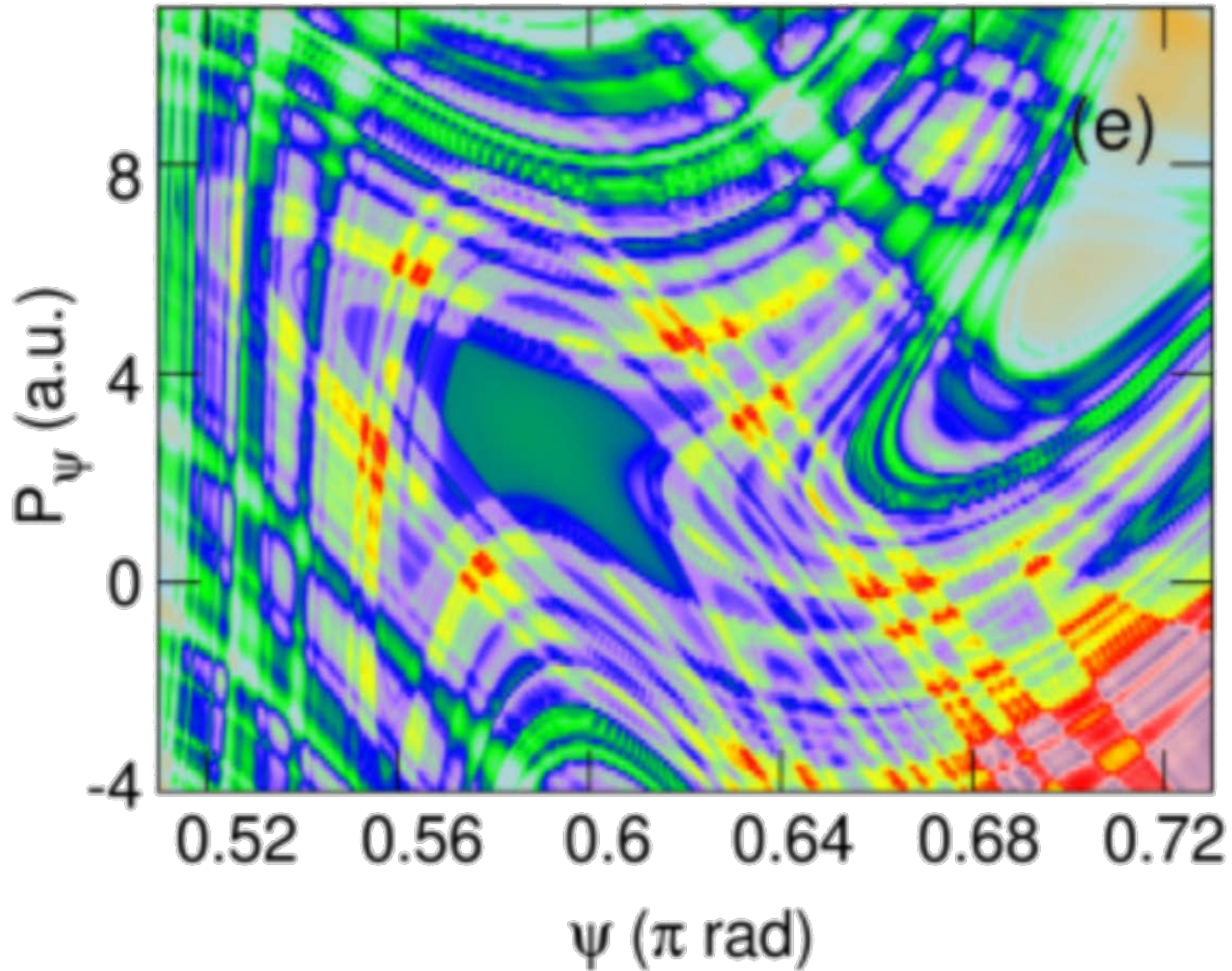


## SADDLE-NODE BIFURCATION

$$E = 3700 \text{ cm}^{-1}$$

$$p = 0.4$$

$$\tau = 2 \cdot 10^4$$

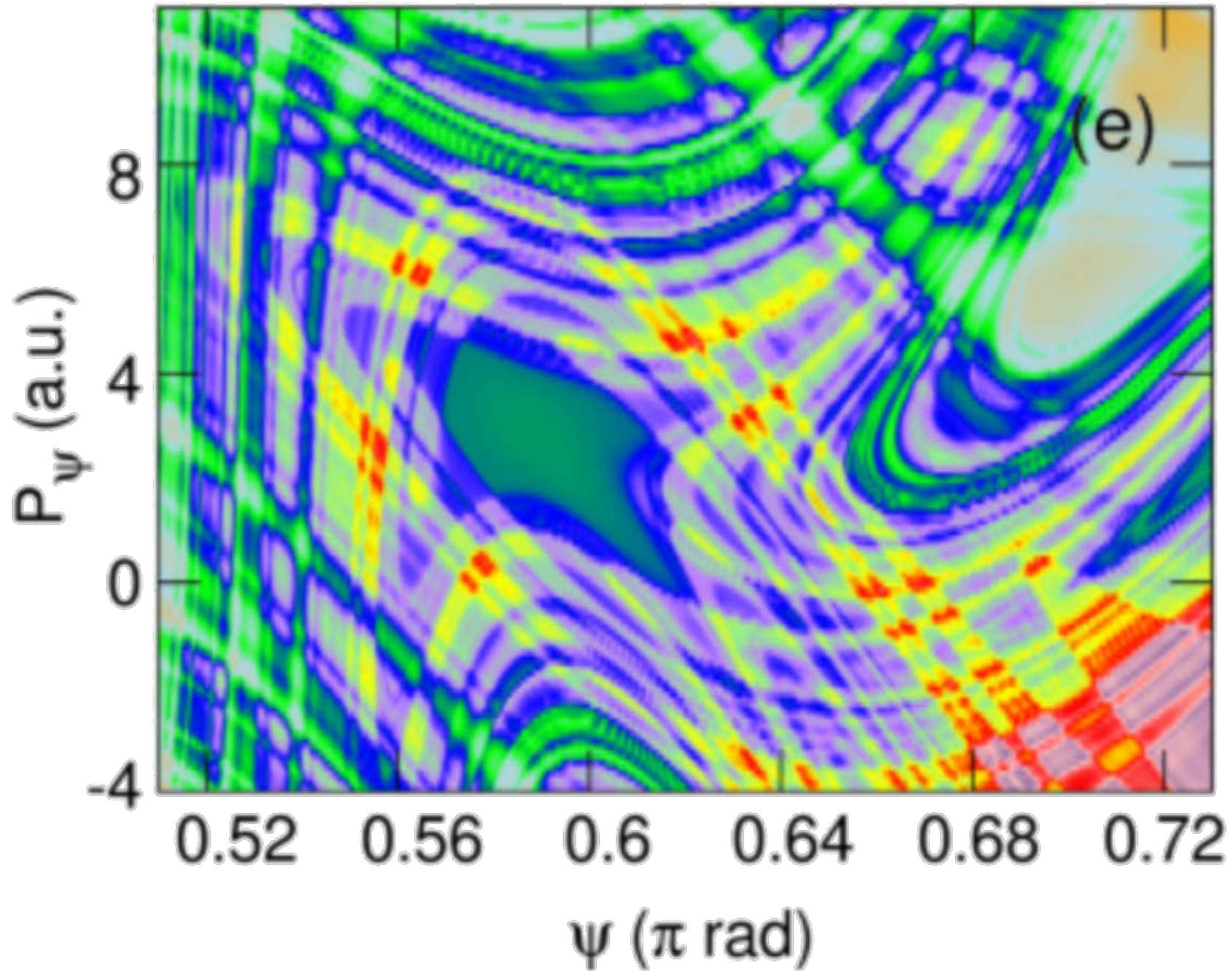


## SADDLE-NODE BIFURCATION

$$E \simeq 4162 \text{ cm}^{-1}$$

$$p = 0.4$$

$$\tau = 2 \cdot 10^4$$

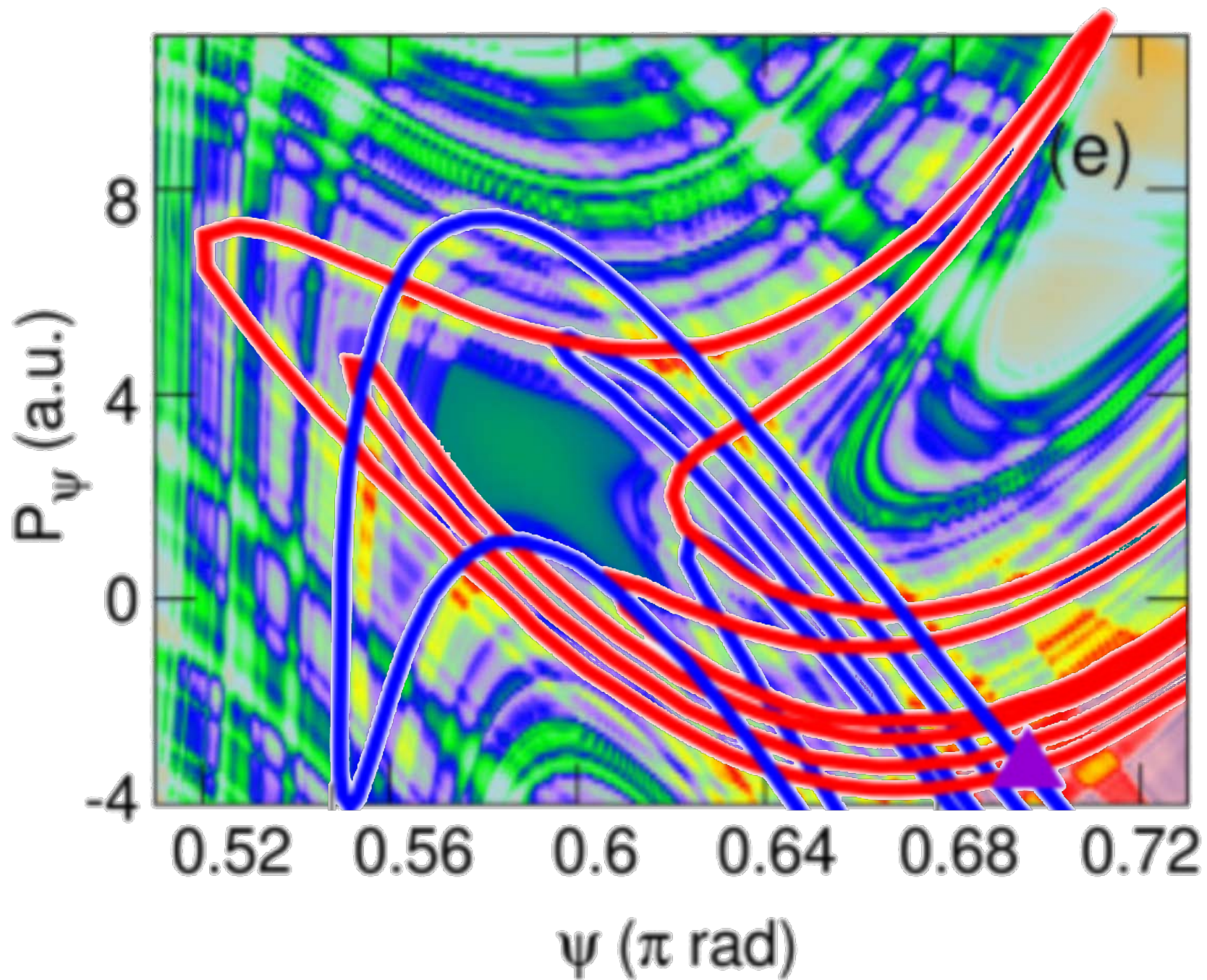


## SADDLE-NODE BIFURCATION

$$E \simeq 4162 \text{ cm}^{-1}$$

$$p = 0.4$$

$$\tau = 2 \cdot 10^4$$

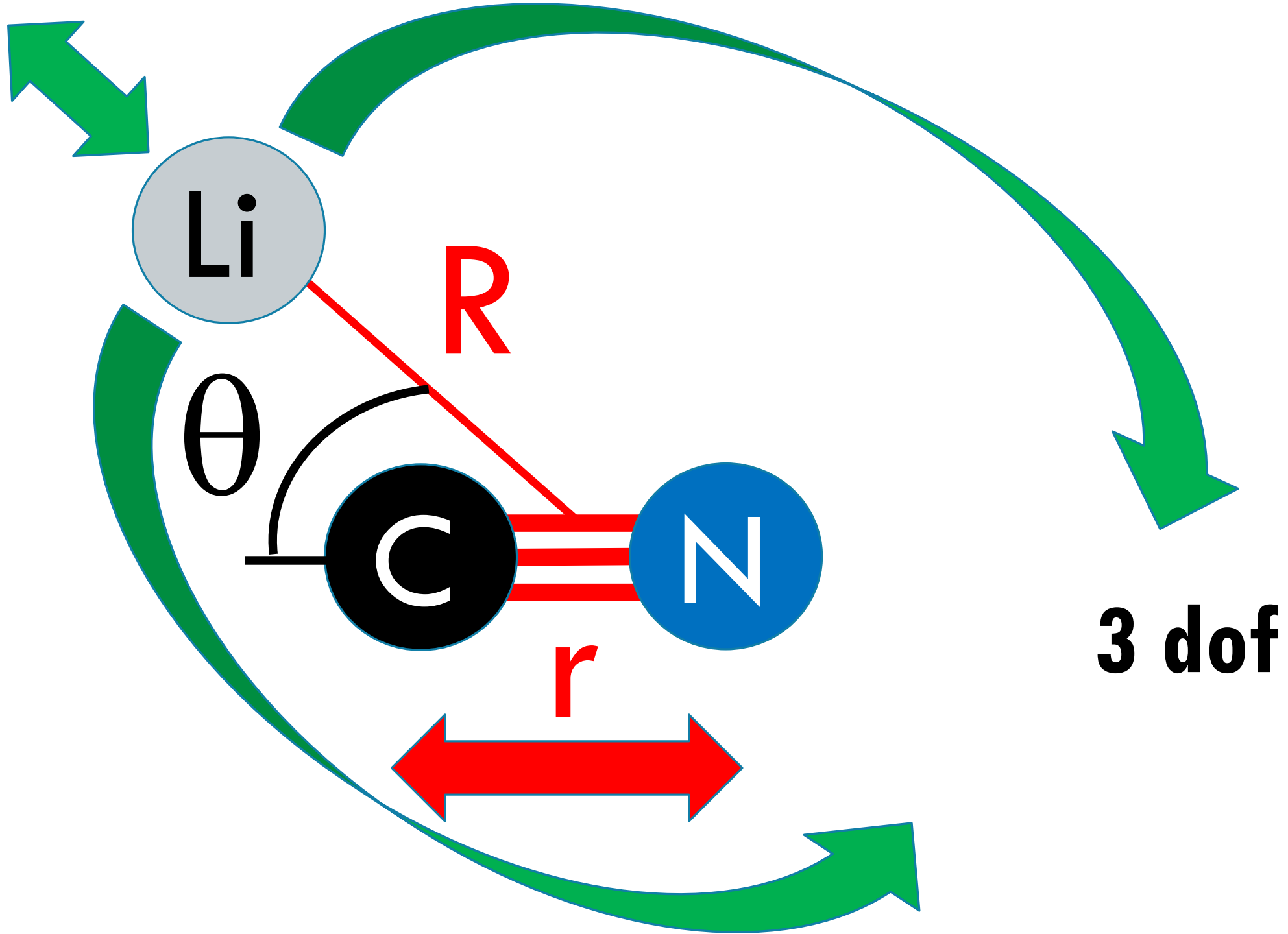


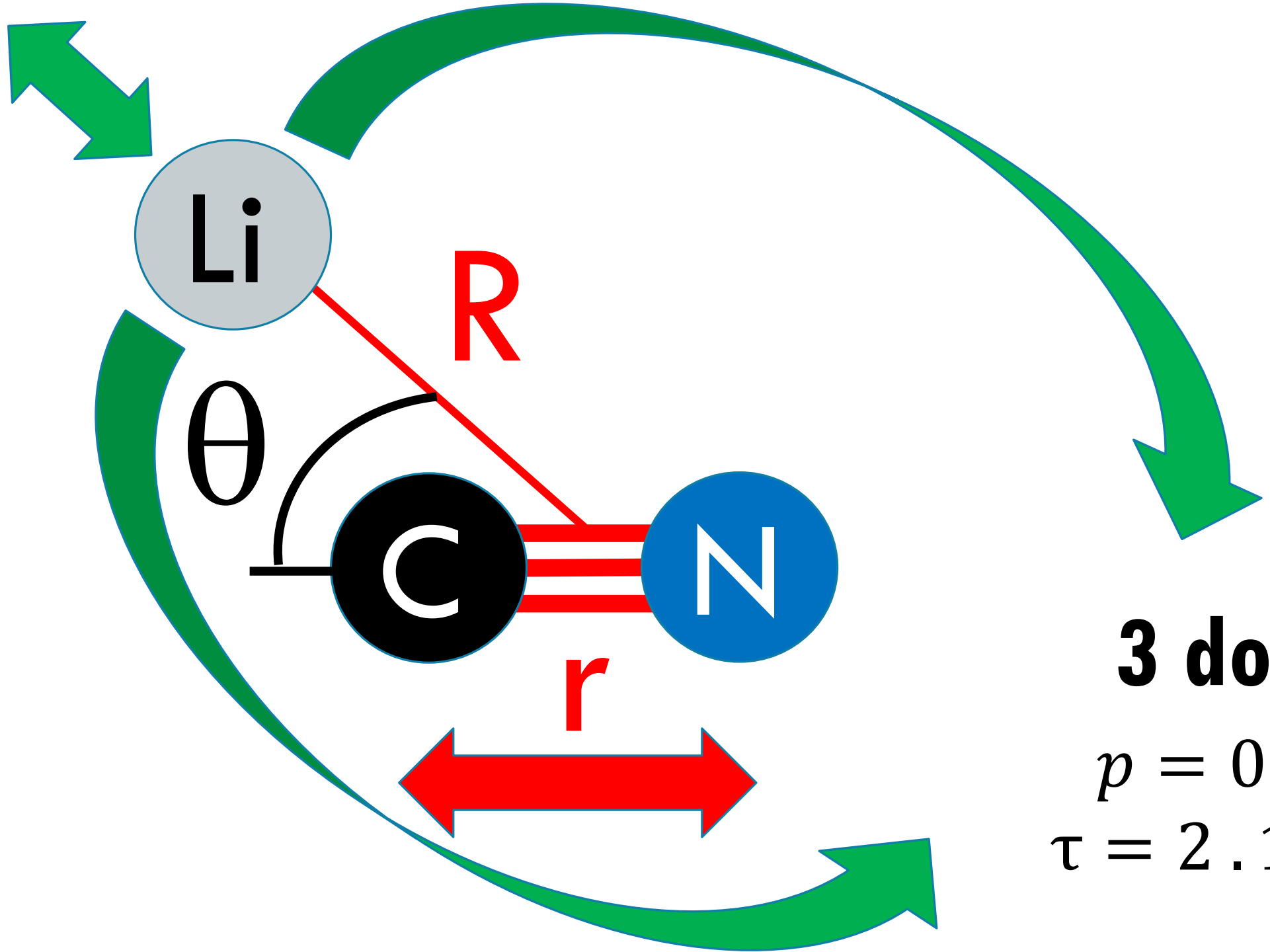
## SADDLE-NODE BIFURCATION

$$E \simeq 4162 \text{ cm}^{-1}$$

$$p = 0.4$$

$$\tau = 2 \cdot 10^4$$





**3 dof**

$$p = 0.4$$

$$\tau = 2 \cdot 10^4$$

## 3-DOF SYSTEM

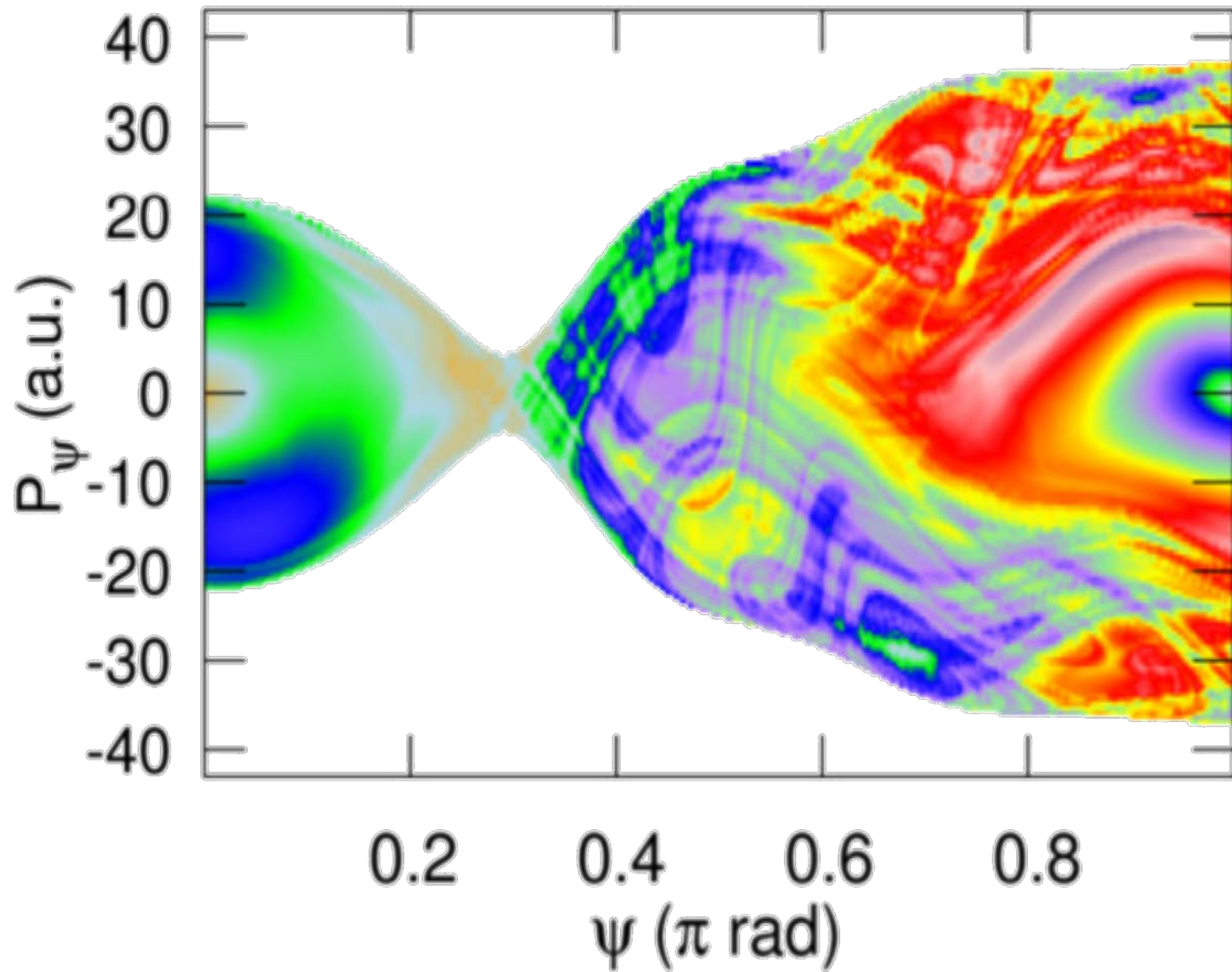
$$H = \frac{P_R^2}{2\mu_1} + \frac{P_r^2}{2\mu_2} + \left( \frac{1}{\mu_1 R^2} + \frac{1}{\mu_2 r^2} \right) \frac{P_\theta^2}{2} + V(R, r, \theta)$$



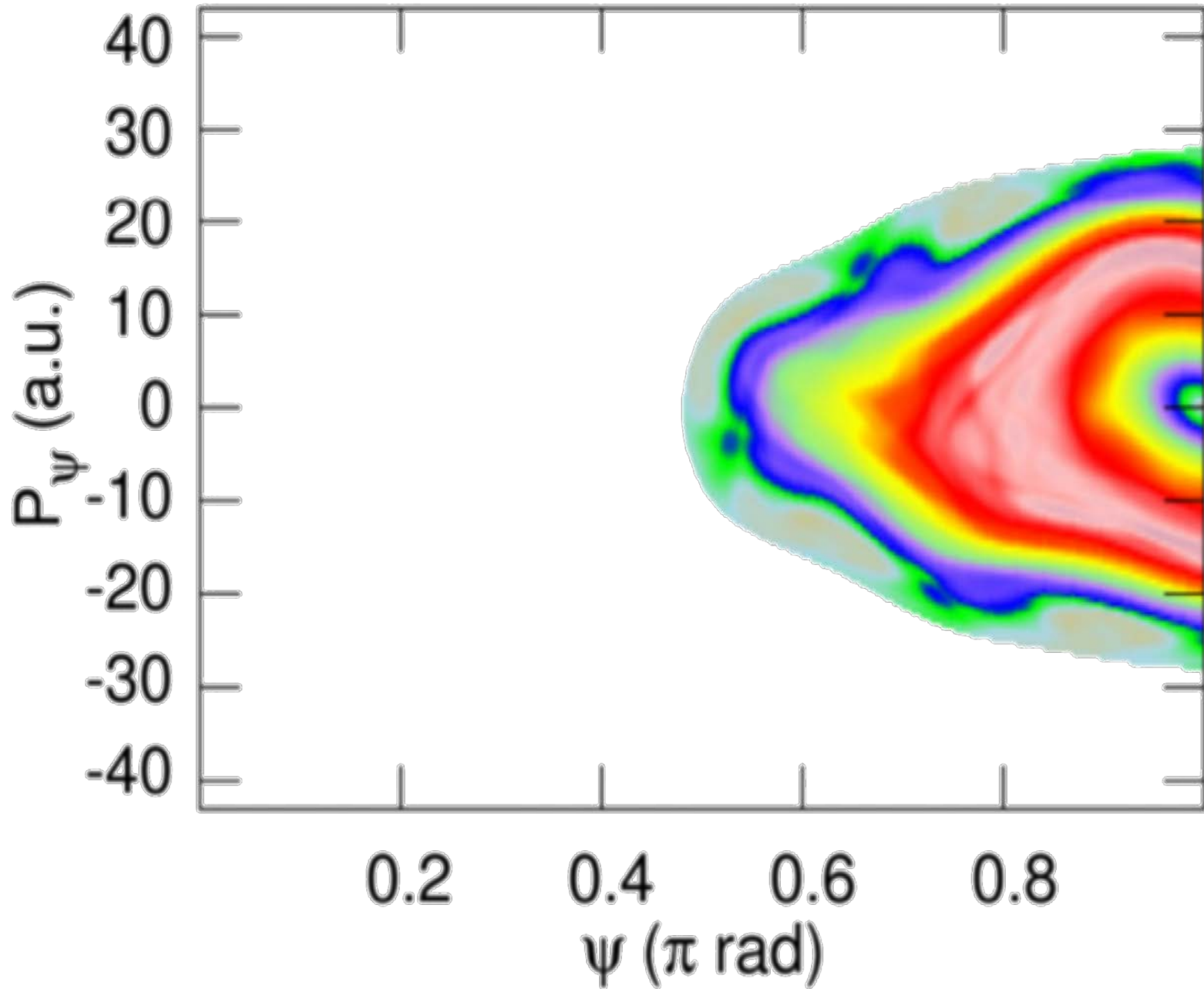
## 3-DOF SYSTEM

$$H = \frac{P_R^2}{2\mu_1} + \frac{P_r^2}{2\mu_2} + \left( \frac{1}{\mu_1 R^2} + \frac{1}{\mu_2 r^2} \right) \frac{P_\theta^2}{2} + V(R, r, \theta)$$

The **more initial kinetic energy** is set in the r-dof, the **more regular** the phase space is in the other dofs's



$$E = 3500 \text{ cm}^{-1}$$
$$T_{CN}^{kin} = 0 \text{ cm}^{-1}$$



$$E = 3500 \text{ cm}^{-1}$$

$$T_{CN}^{kin} = 1500 \text{ cm}^{-1}$$

# CONCLUSIONS



# CONCLUSIONS



**Lagrangian descriptors** allow the identification of the invariant manifolds in **molecular systems**

# SPONSORS



**Comunidad  
de Madrid**





# NEW PERSPECTIVES INTO THE CHAOTIC DYNAMICS IN MOLECULES

**Fabio Revuelta**

**Grupo de Sistemas Complejos**

**Universidad Politécnica de Madrid (Spain)**

# POINCARÉ SURFACE OF SECTION

$$\rho = R - R_{\text{eq}}(\theta),$$

$$\vartheta = \theta,$$

$$P_{\rho} = P_R,$$

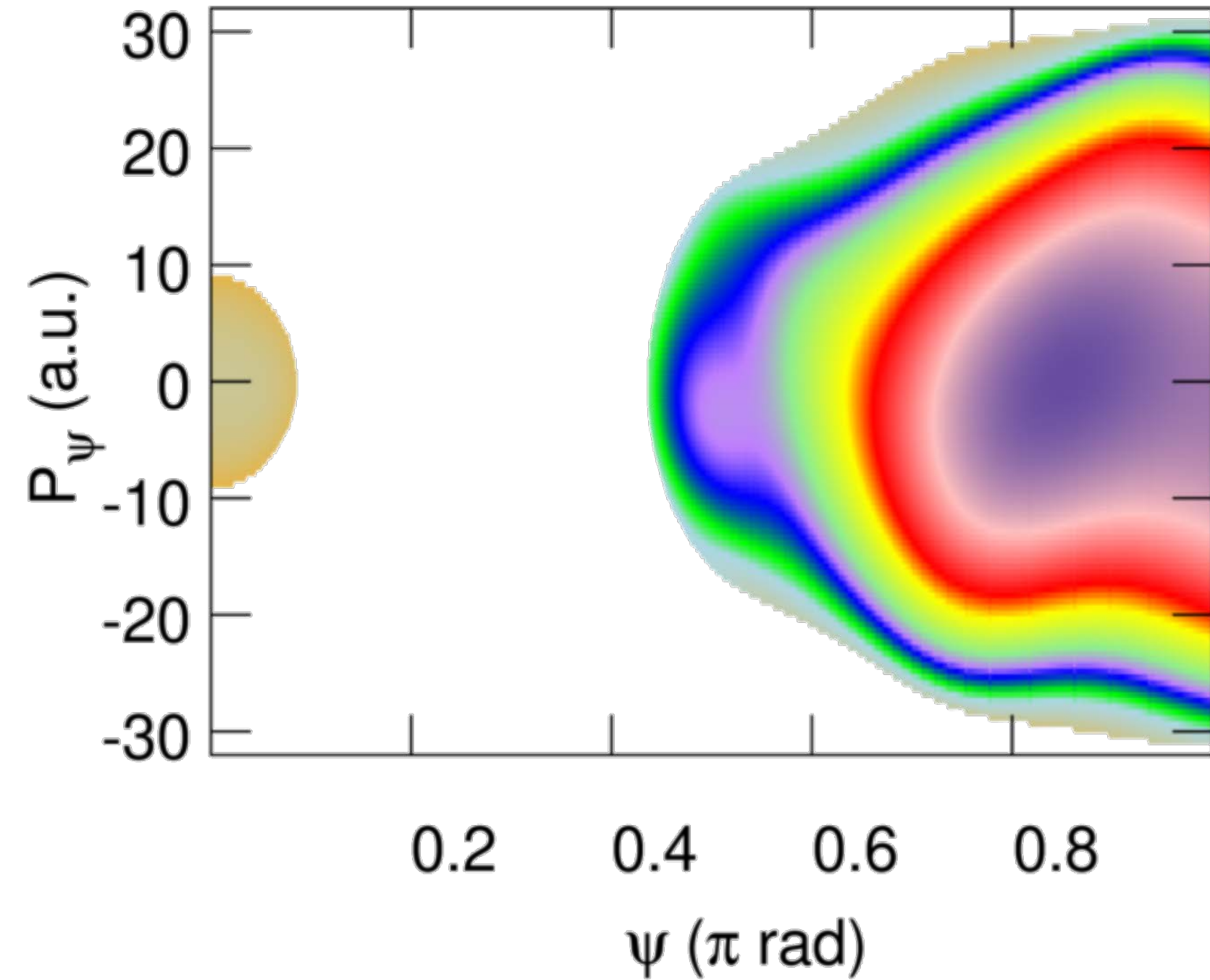
$$P_{\vartheta} = P_{\theta} + P_R \left( \frac{dR_{\text{eq}}(\theta)}{d\theta} \right)$$



# INFLUENCE OF THE INTEGRATION TIME

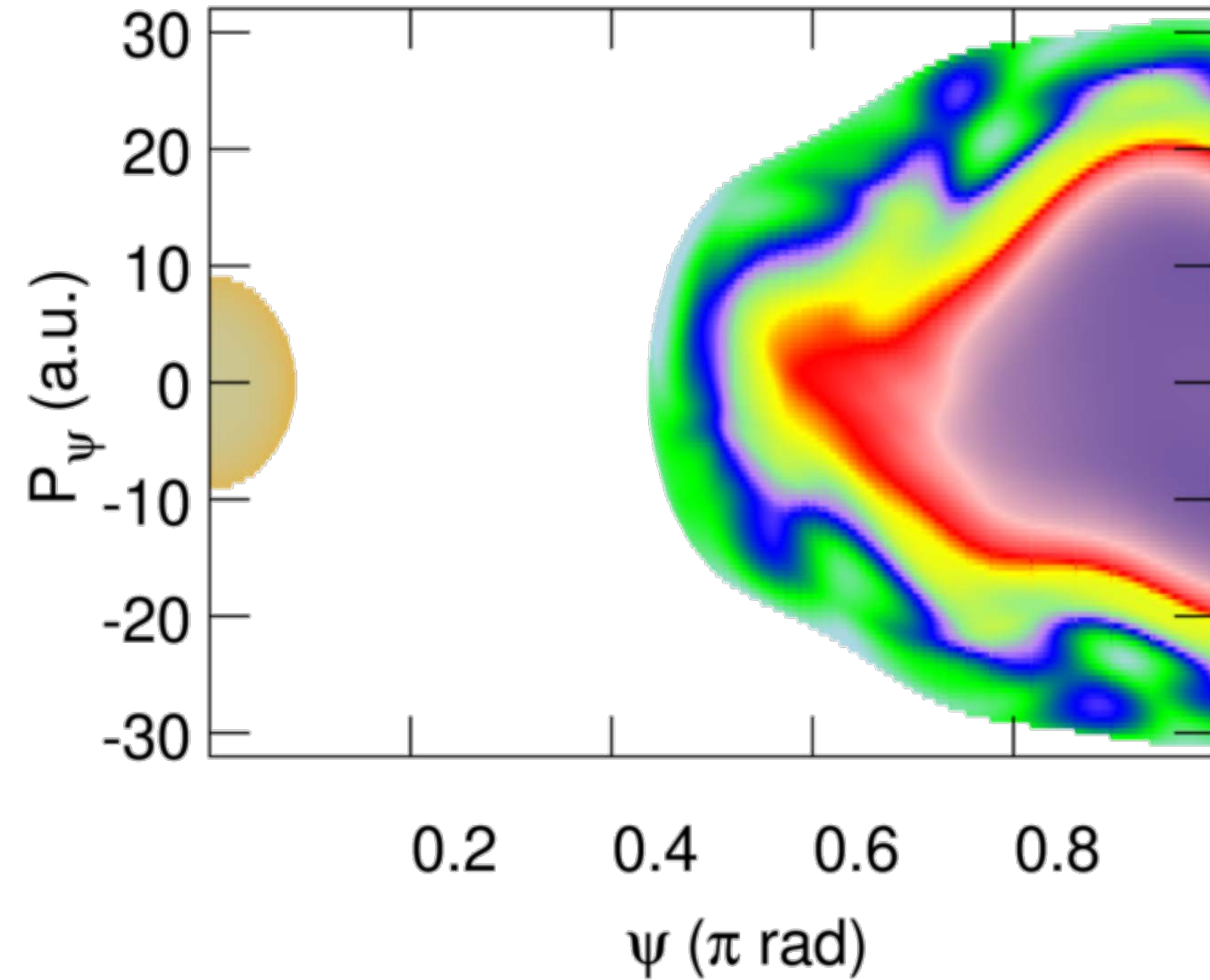


$\tau$  must be **long**  
enough... but **not too**  
**much**



## LAGRANGIAN DESCRIPTORS

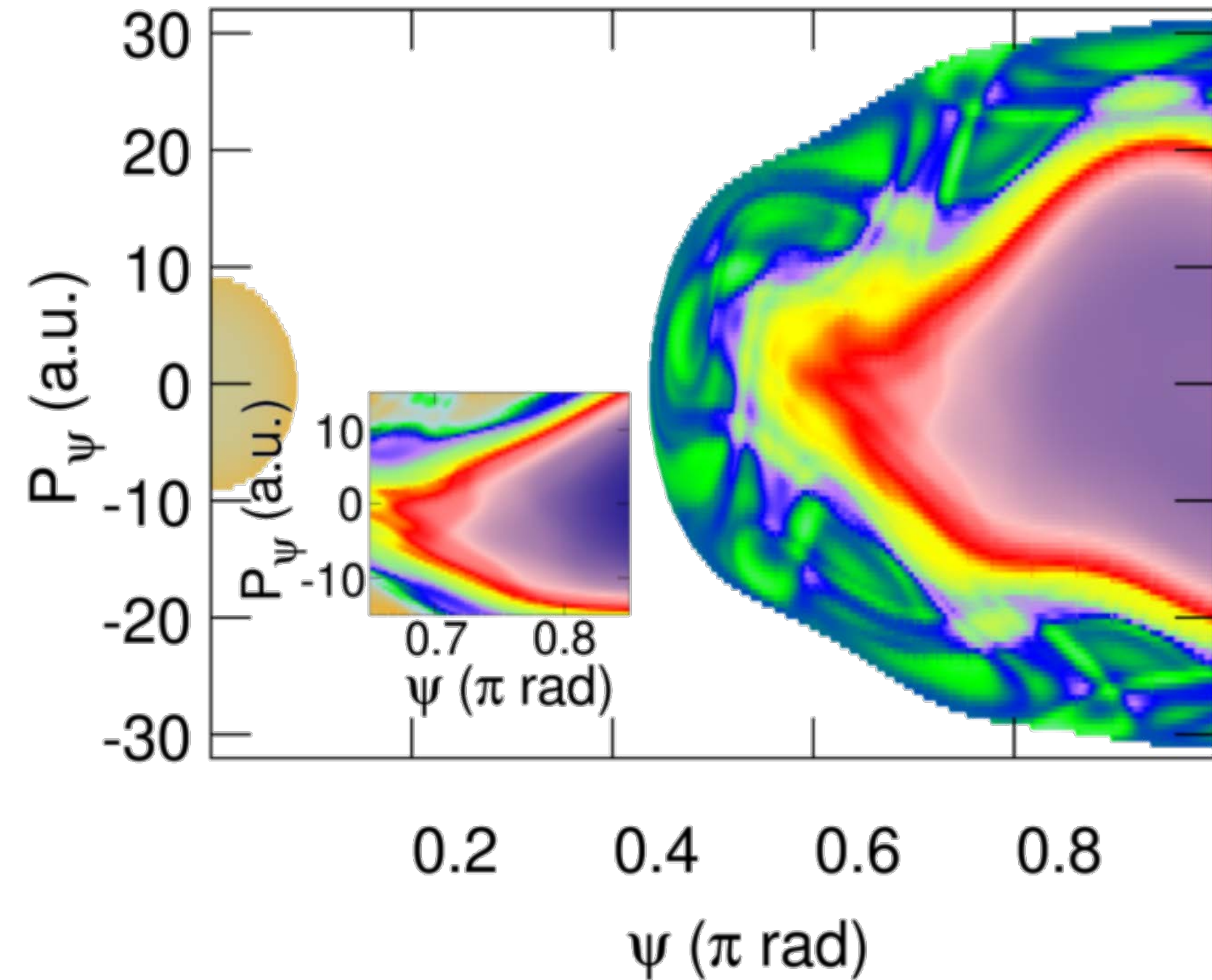
*Standard*  
 $\tau = 10^3$



## LAGRANGIAN DESCRIPTORS

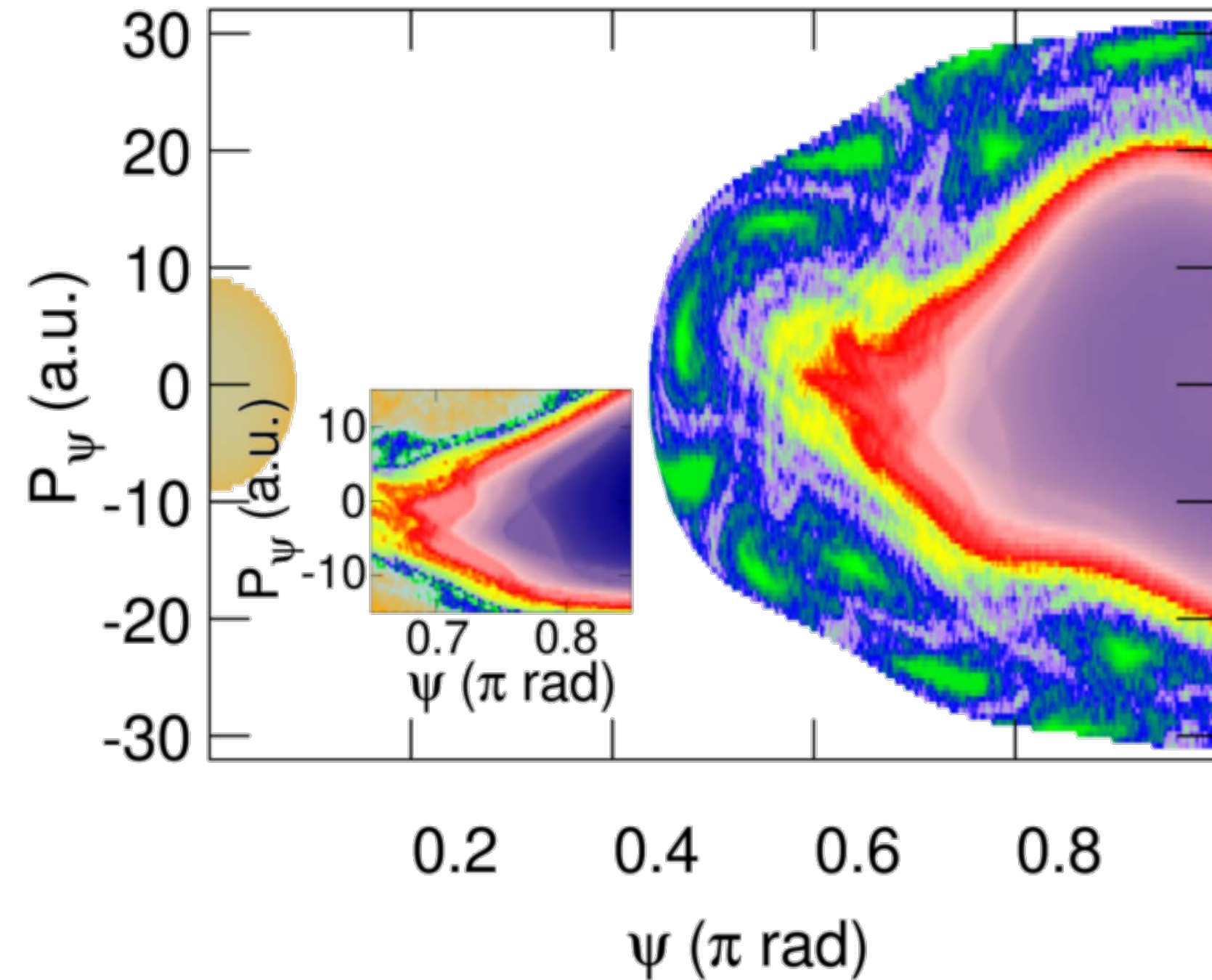
*Standard*

$$\tau = 10^4$$



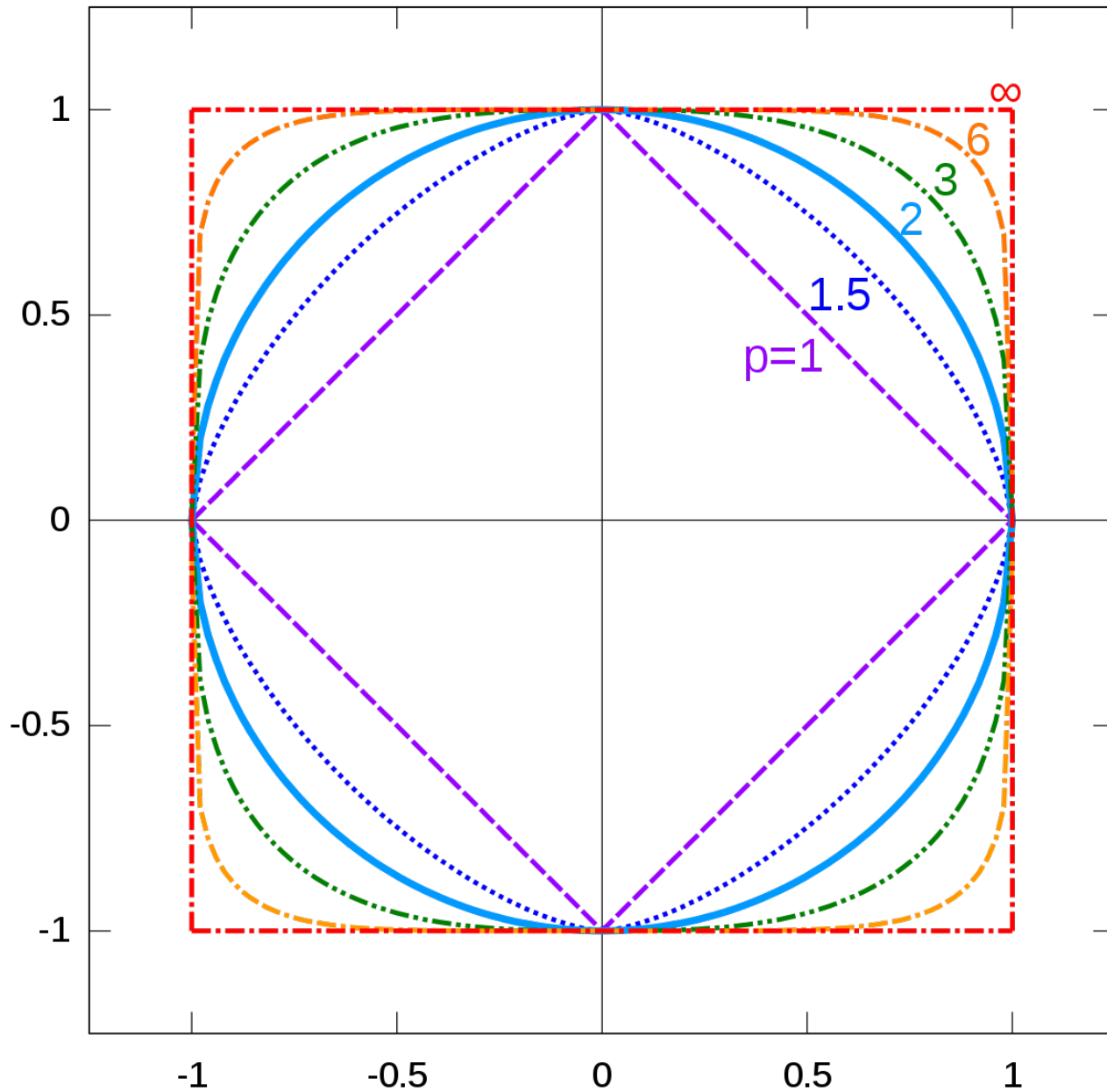
## LAGRANGIAN DESCRIPTORS

*Standard*  
 $\tau = 2 \cdot 10^4$



## LAGRANGIAN DESCRIPTORS

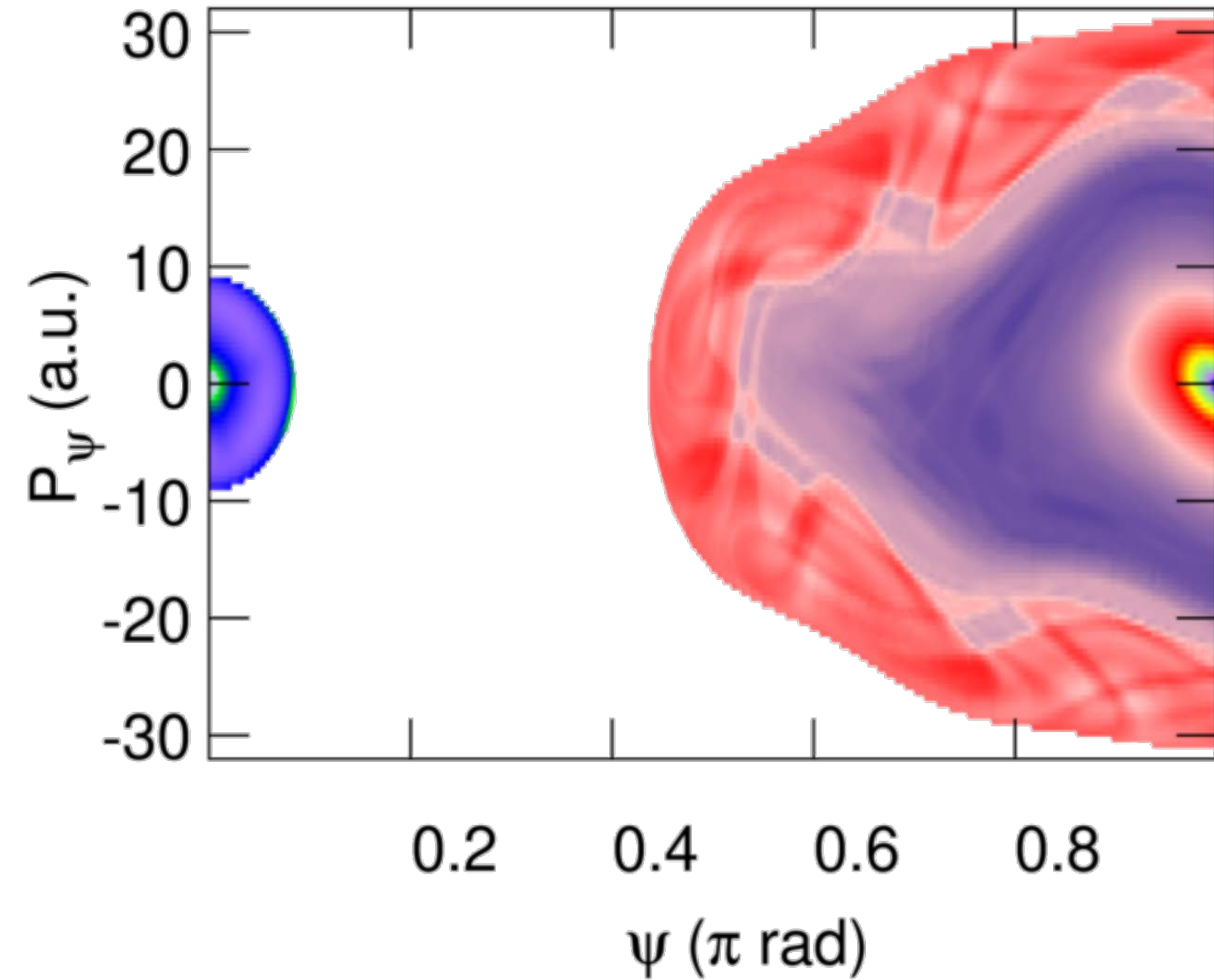
*Standard*  
 $\tau = 10^5$



# INFLUENCE OF THE VALUE OF P IN THE NORM

Image source:

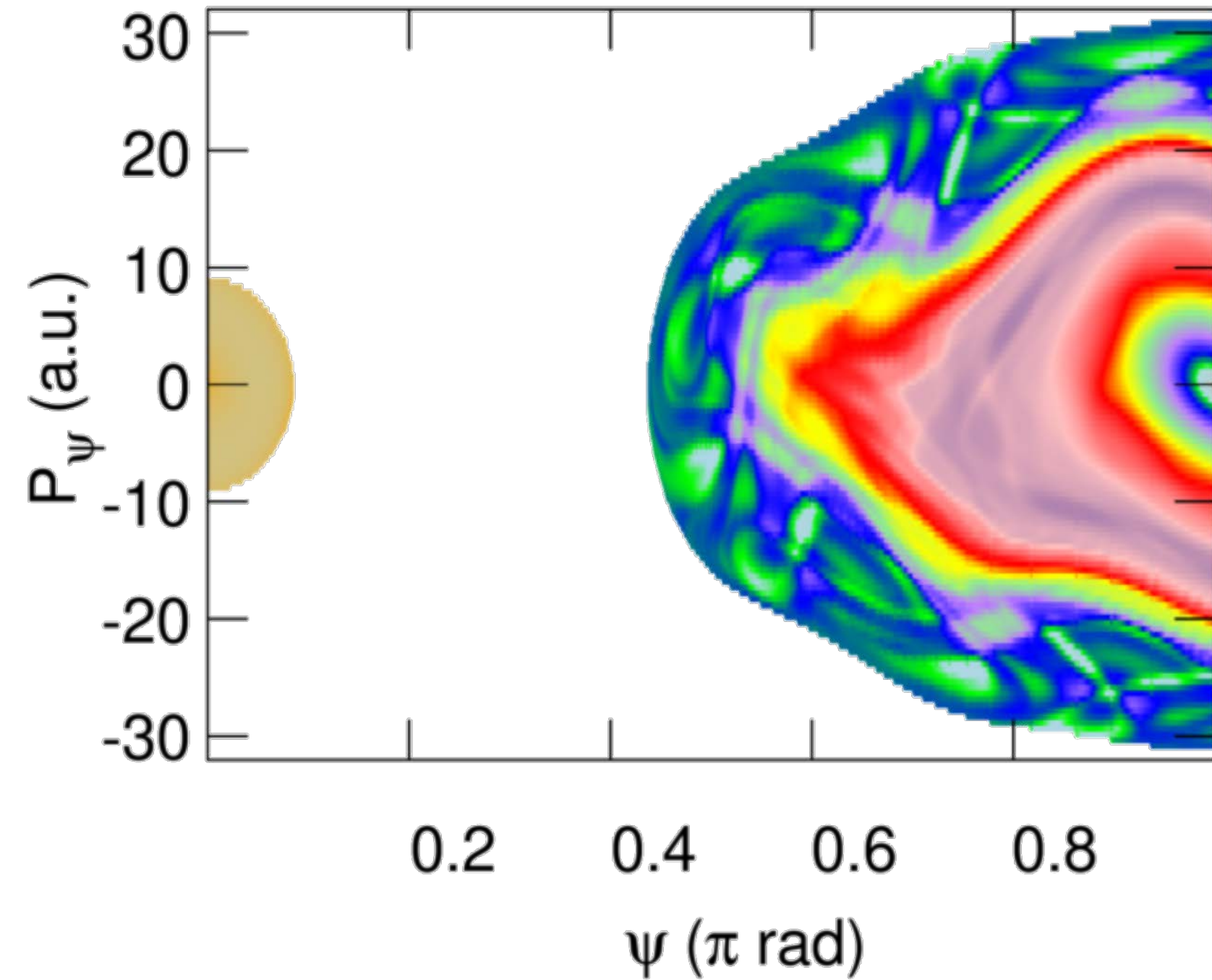




## LAGRANGIAN DESCRIPTORS

$$p = 0.1$$

$$\tau = 2 \cdot 10^4$$

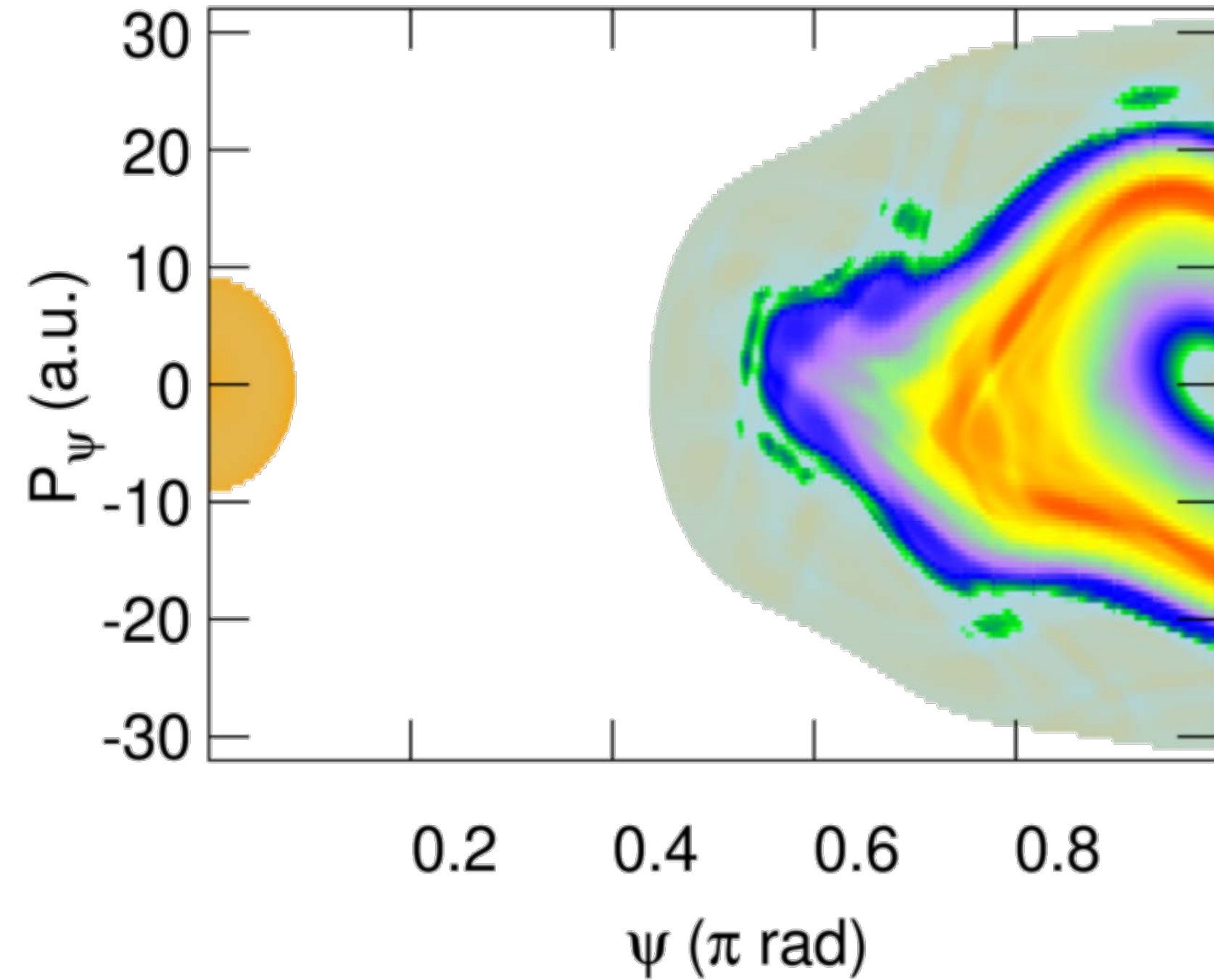


## LAGRANGIAN DESCRIPTORS

$$p = 0.4$$

$$\tau = 2 \cdot 10^4$$

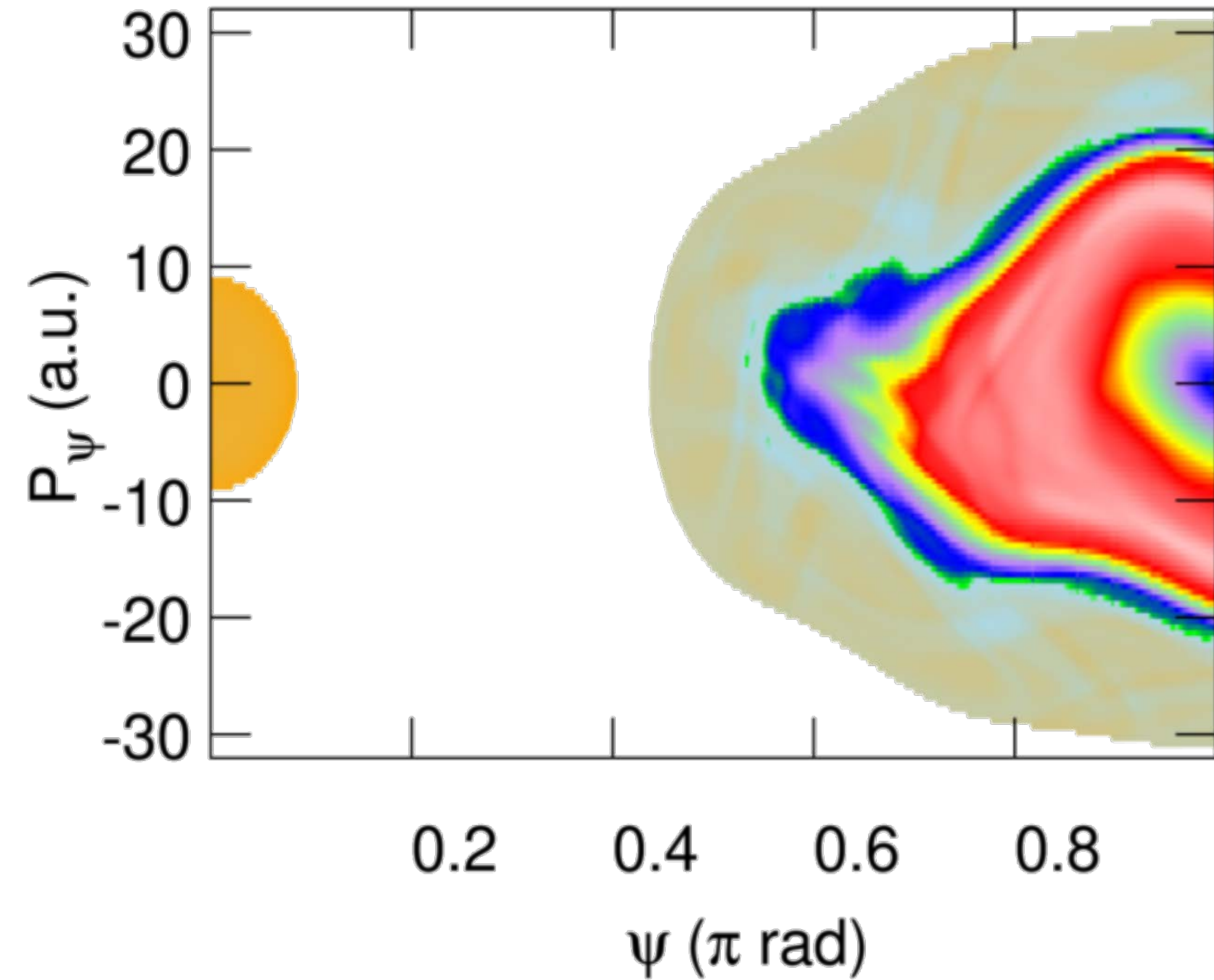




## LAGRANGIAN DESCRIPTORS

$$p = 0.6$$

$$\tau = 2 \cdot 10^4$$

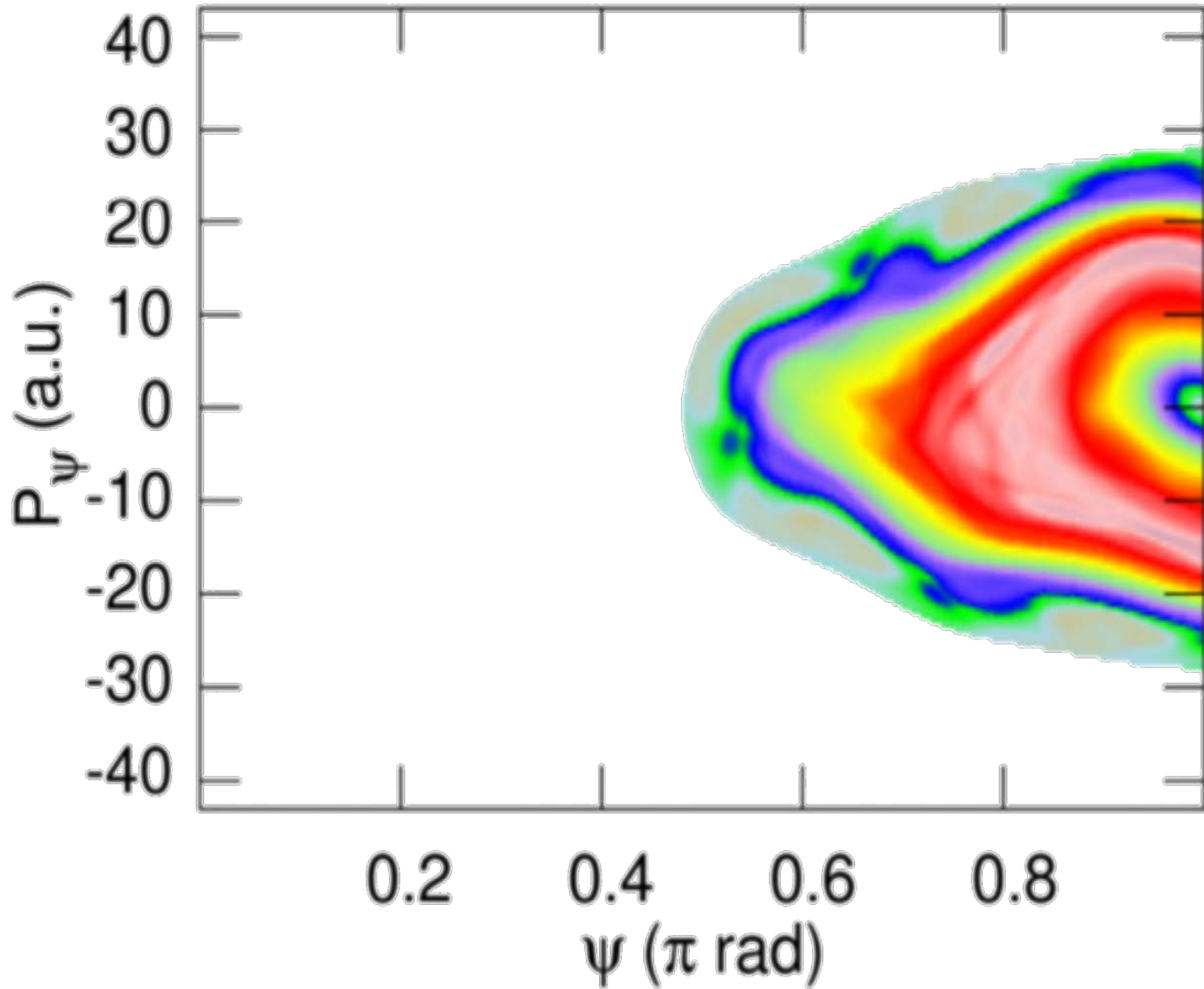


## LAGRANGIAN DESCRIPTORS

$$p = 1$$

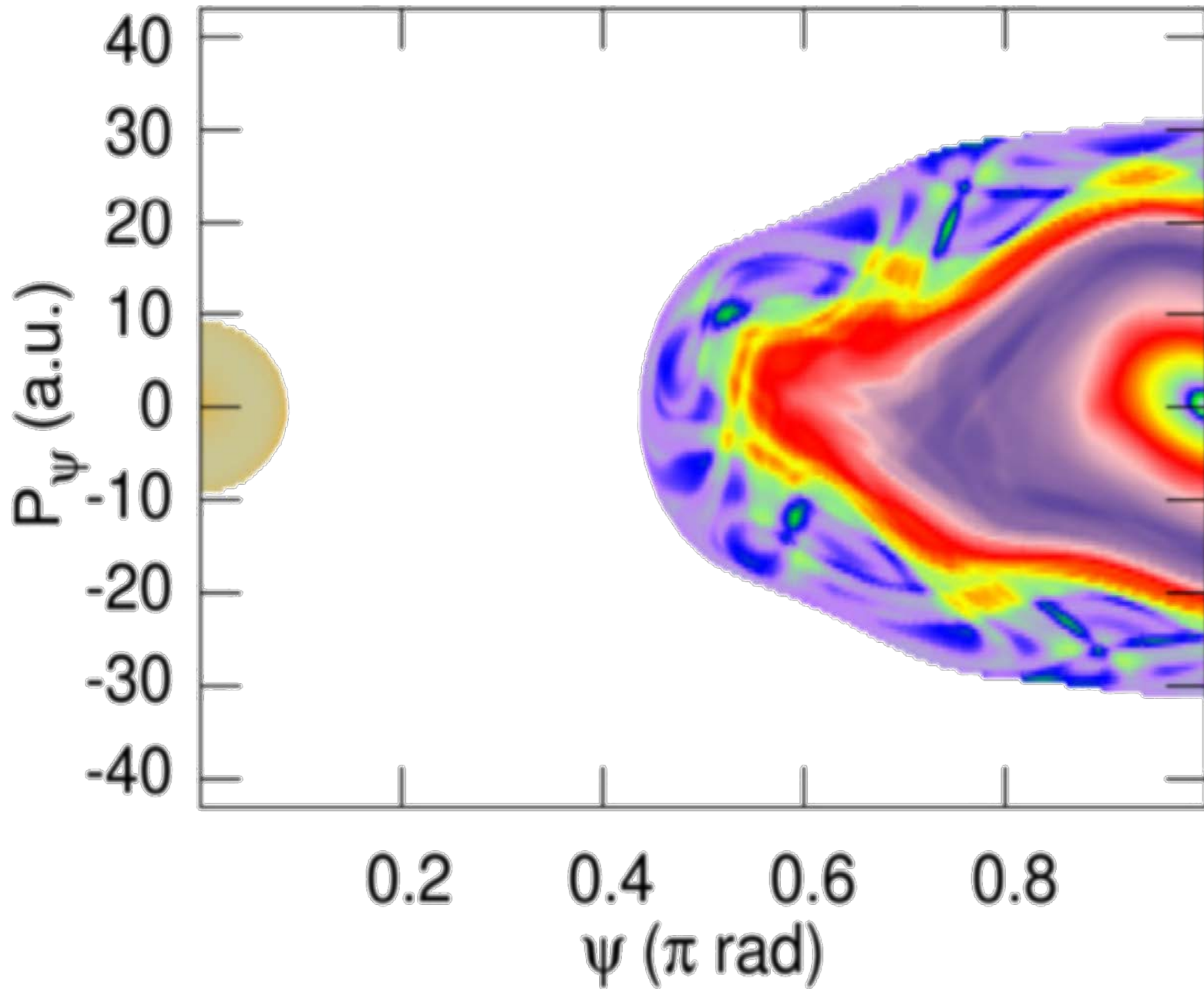
$$\tau = 2 \cdot 10^4$$

**3 DOF**



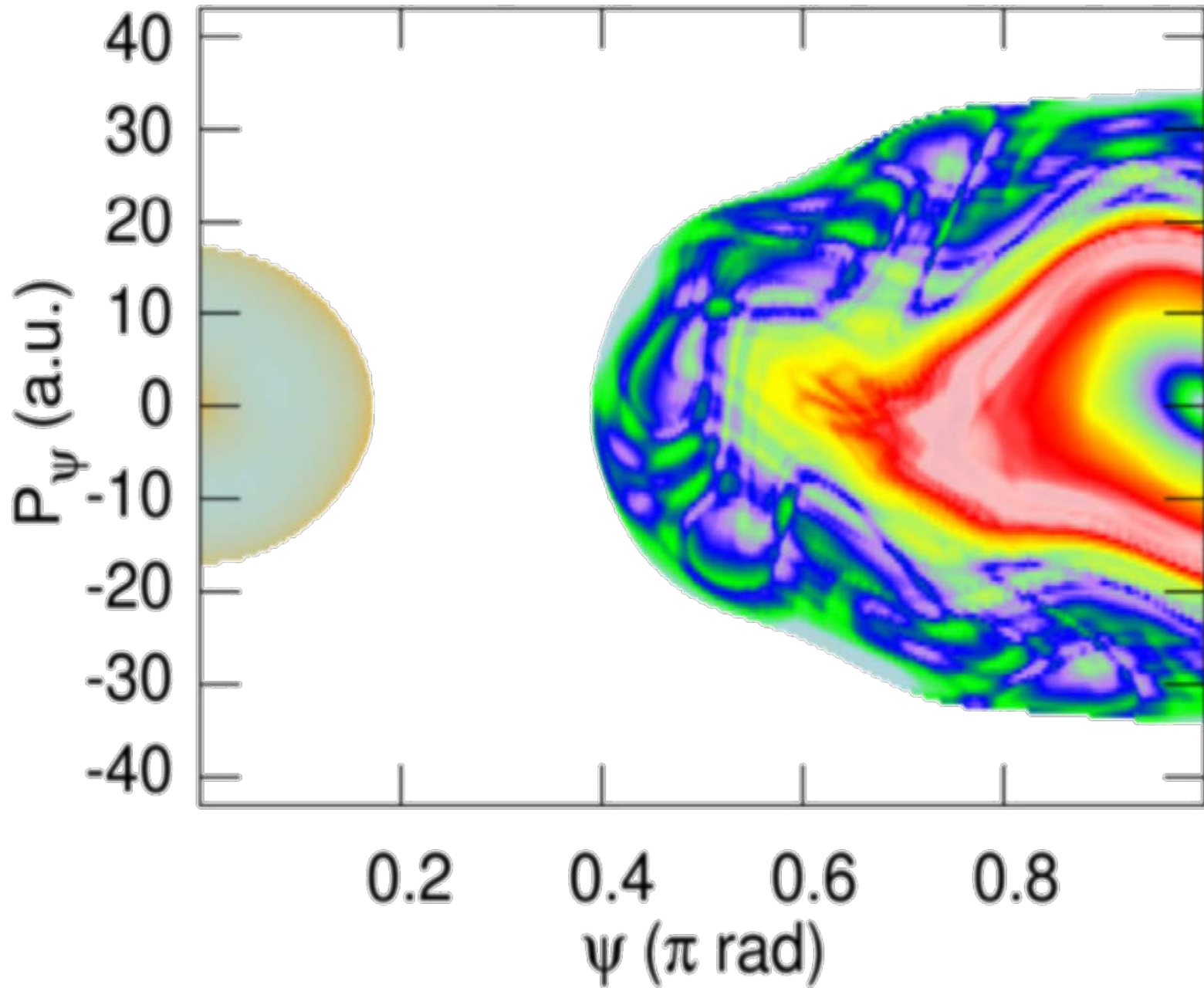
$$E = 3500 \text{ cm}^{-1}$$

$$T_{CN}^{kin} = 1500 \text{ cm}^{-1}$$



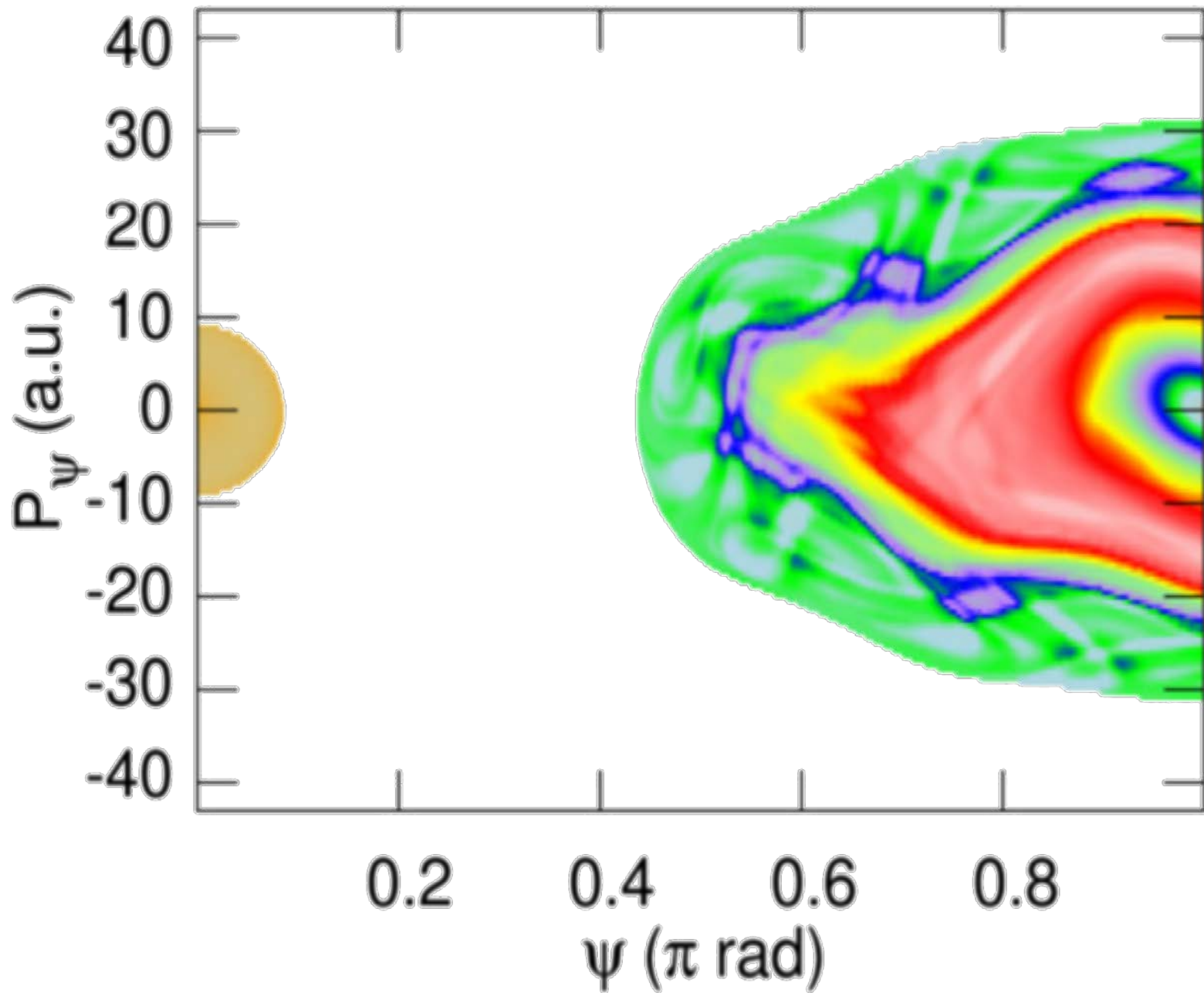
$$E = 4000 \text{ cm}^{-1}$$

$$T_{CN}^{kin} = 1500 \text{ cm}^{-1}$$



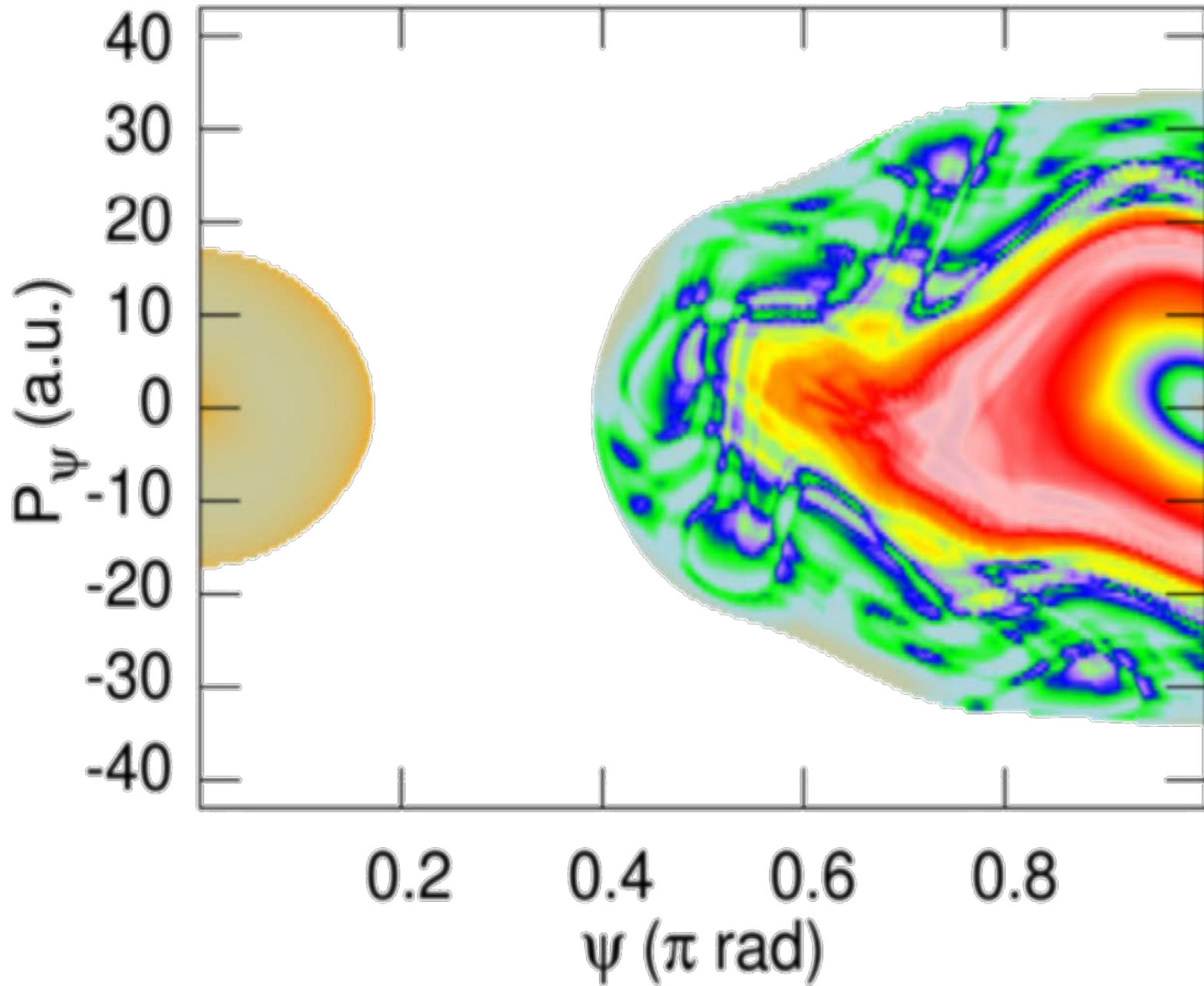
$$E = 4500 \text{ cm}^{-1}$$

$$T_{CN}^{kin} = 1500 \text{ cm}^{-1}$$



$$E = 3500 \text{ cm}^{-1}$$

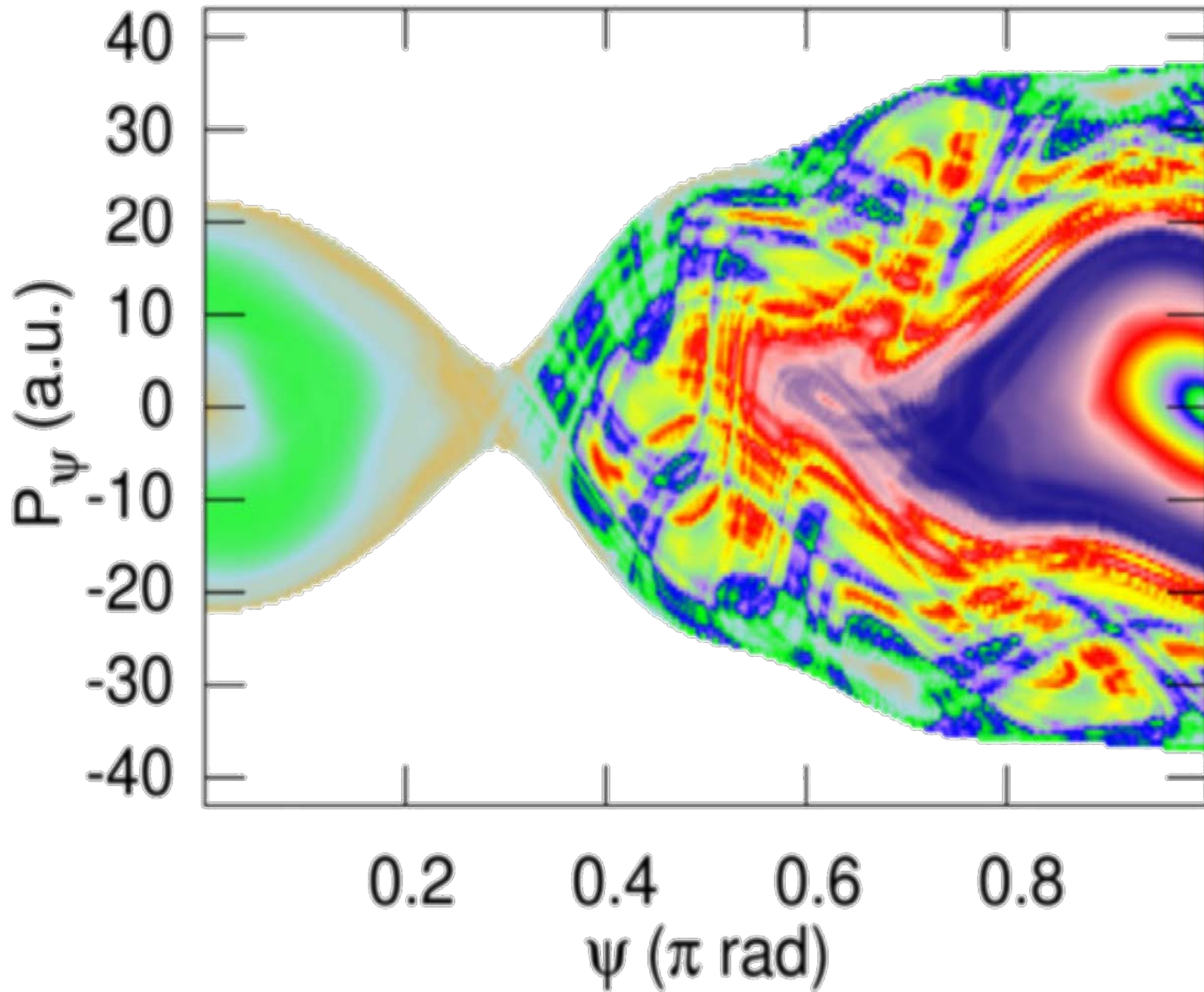
$$T_{CN}^{kin} = 1000 \text{ cm}^{-1}$$



$$E = 4000 \text{ cm}^{-1}$$

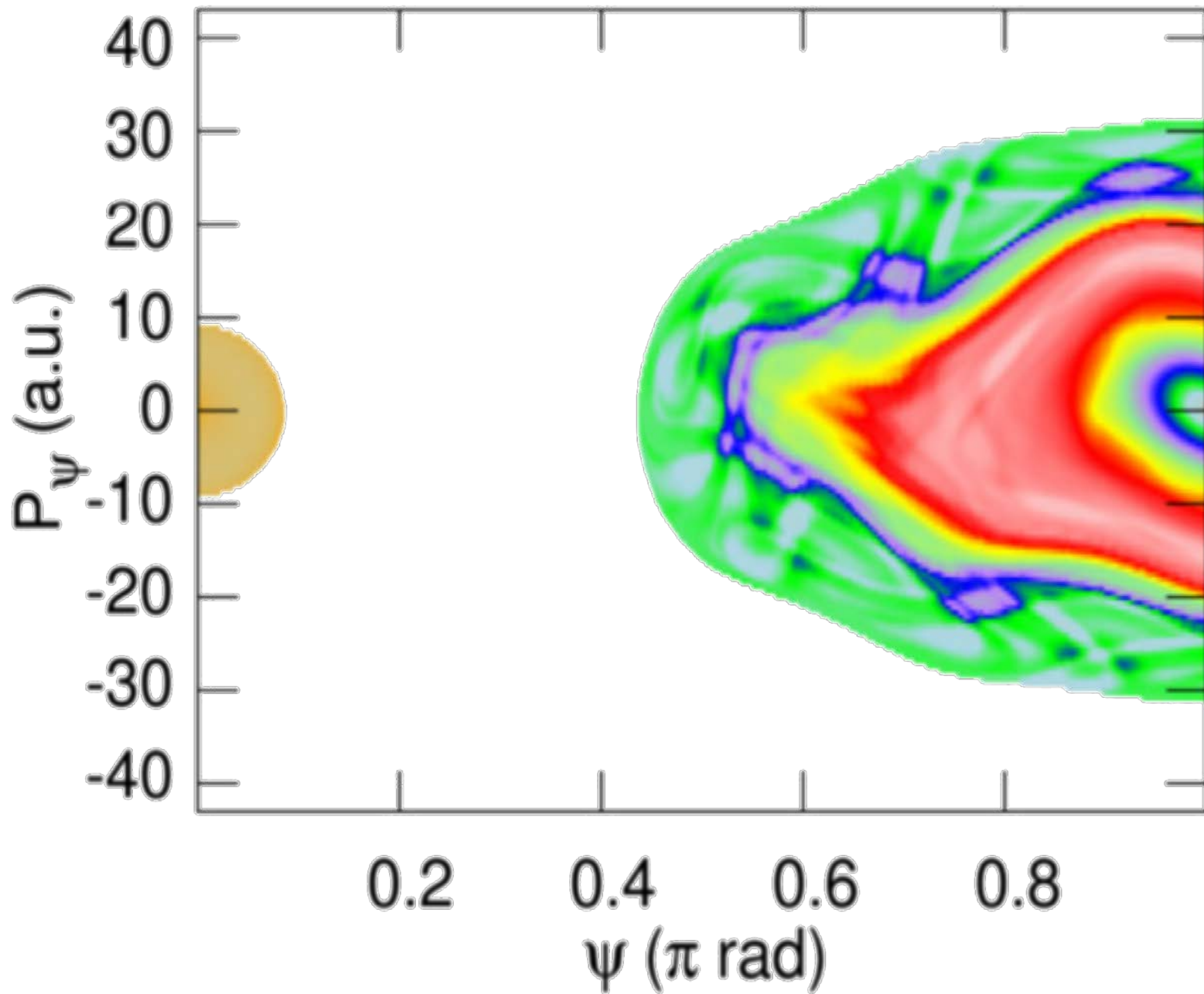
$$T_{CN}^{kin} = 1000 \text{ cm}^{-1}$$



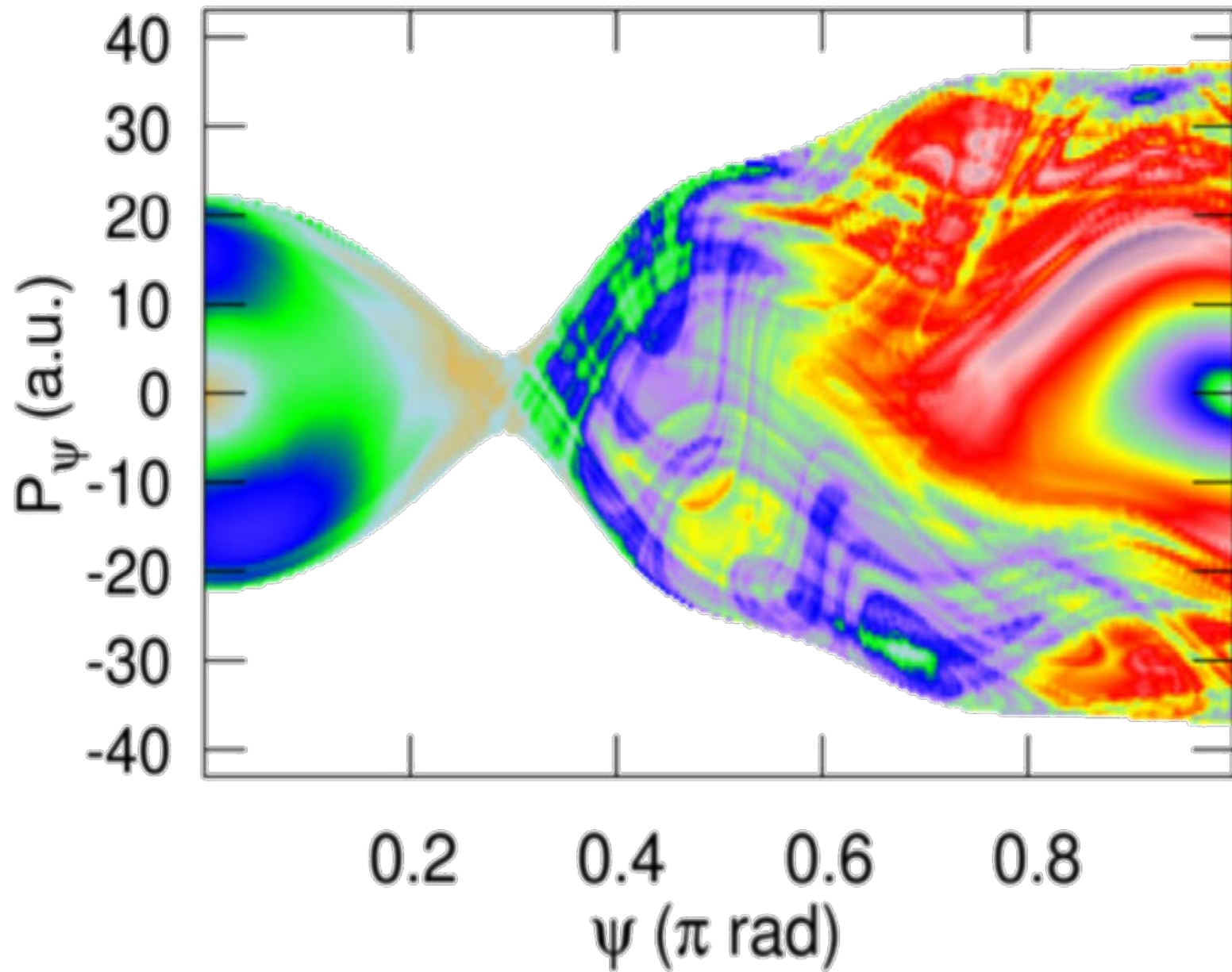


$$E = 4500 \text{ cm}^{-1}$$

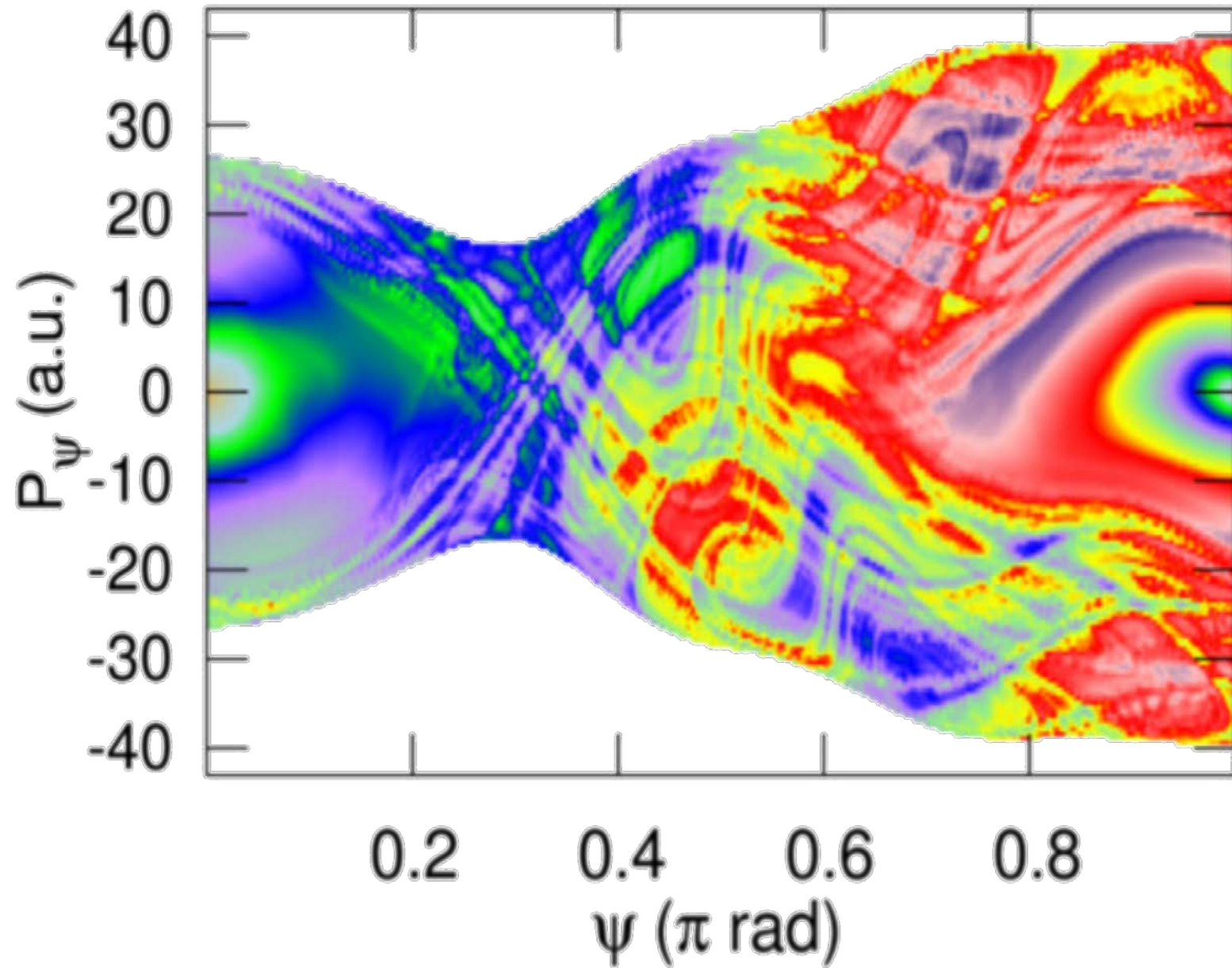
$$T_{CN}^{kin} = 1000 \text{ cm}^{-1}$$



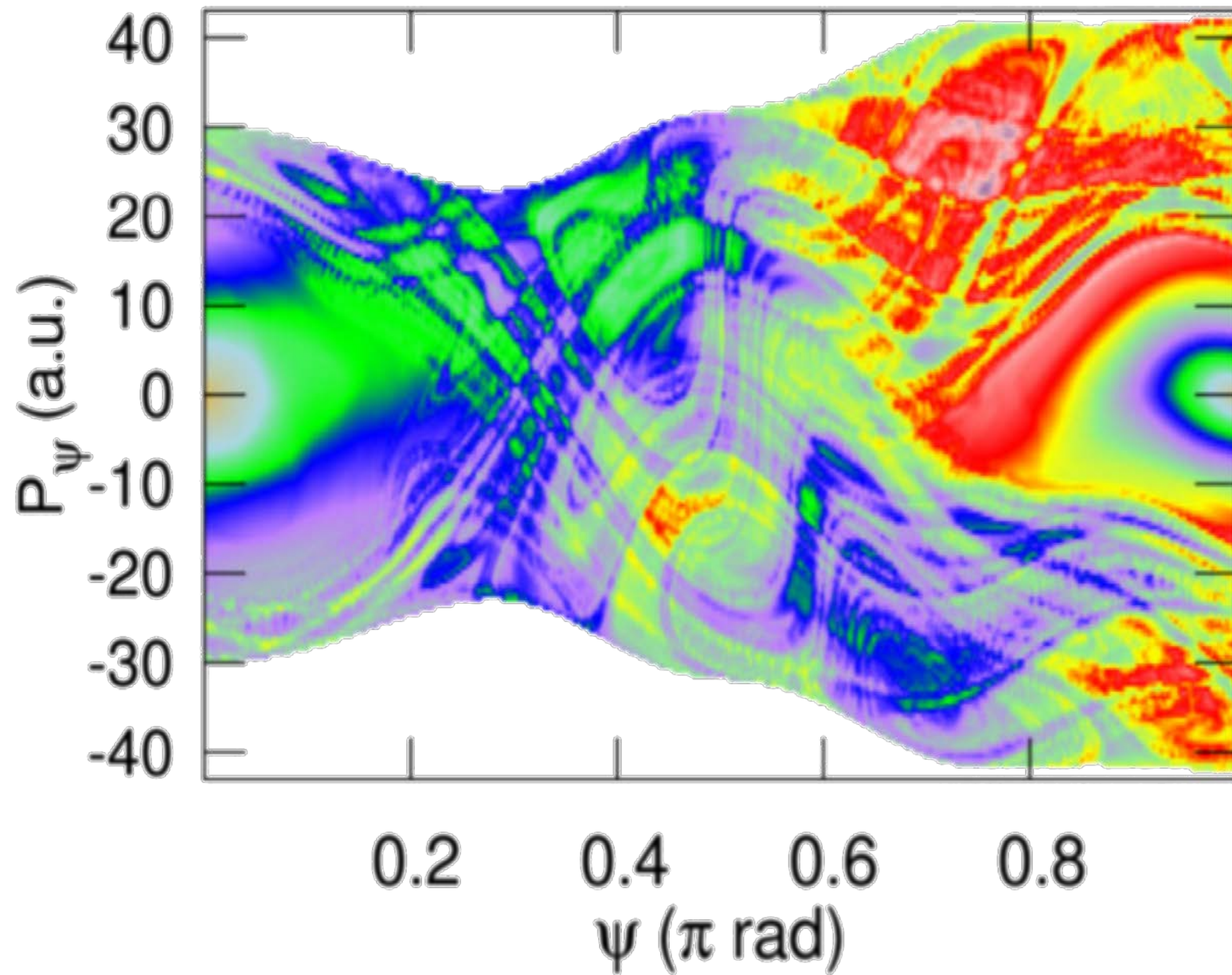
$$E = 3500 \text{ cm}^{-1}$$
$$T_{CN}^{kin} = 0 \text{ cm}^{-1}$$



$$E = 3500 \text{ cm}^{-1}$$
$$T_{CN}^{kin} = 0 \text{ cm}^{-1}$$



$$E = 4000 \text{ cm}^{-1}$$
$$T_{CN}^{kin} = 0 \text{ cm}^{-1}$$



$$E = 4500 \text{ cm}^{-1}$$
$$T_{CN}^{kin} = 0 \text{ cm}^{-1}$$